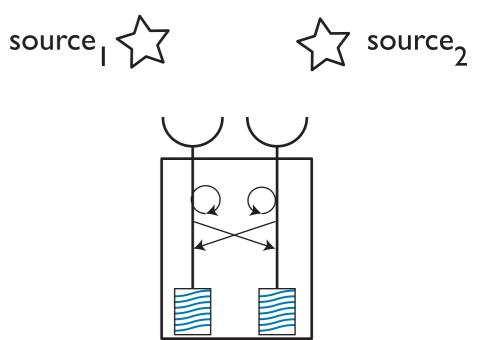
Gregor Schöner gregor.schoener@ini.rub.de

how to represent the inner state of the Central Nervous System?

=> activation concept



#### neural state variables

membrane potential of neurons?

spiking rate?

Impopulation activation...

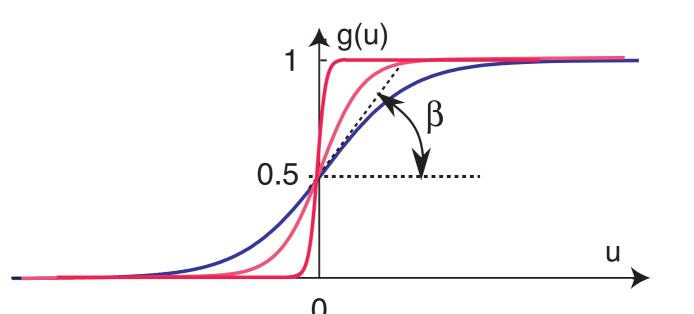
activation as a real number, abstracting from biophysical details

Iow levels of activation: not transmitted to other systems (e.g., to motor systems)

high levels of activation: transmitted to other systems

as described by sigmoidal threshold function

zero activation defined as threshold of that function



#### compare to connectionist notion of activation:

same idea, but tied to individual neurons

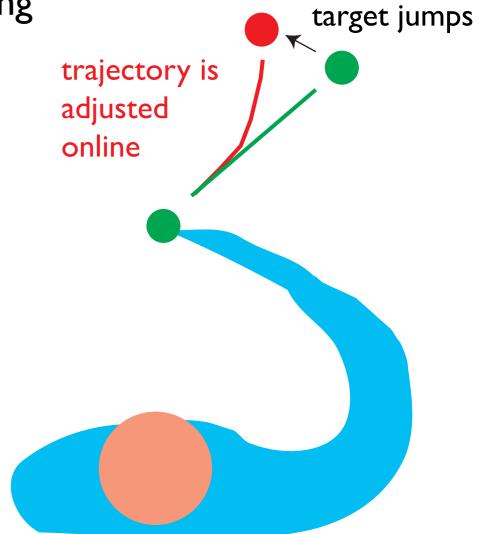
#### compare to abstract activation of production systems (ACT-R, SOAR)

quite different... really a function that measures how far a module is from emitting its output...

#### activation evolves in continuous time

no evidence for a discretization of time, for spike timing to matter for behavior

evidence for continuous online updating



activation evolves continuously in continuous time

no evidence for a discrete events mattering...

evidence for continuity: visual inertia

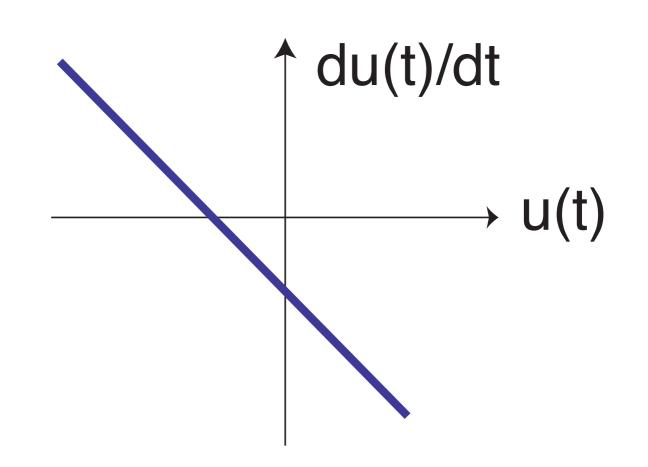


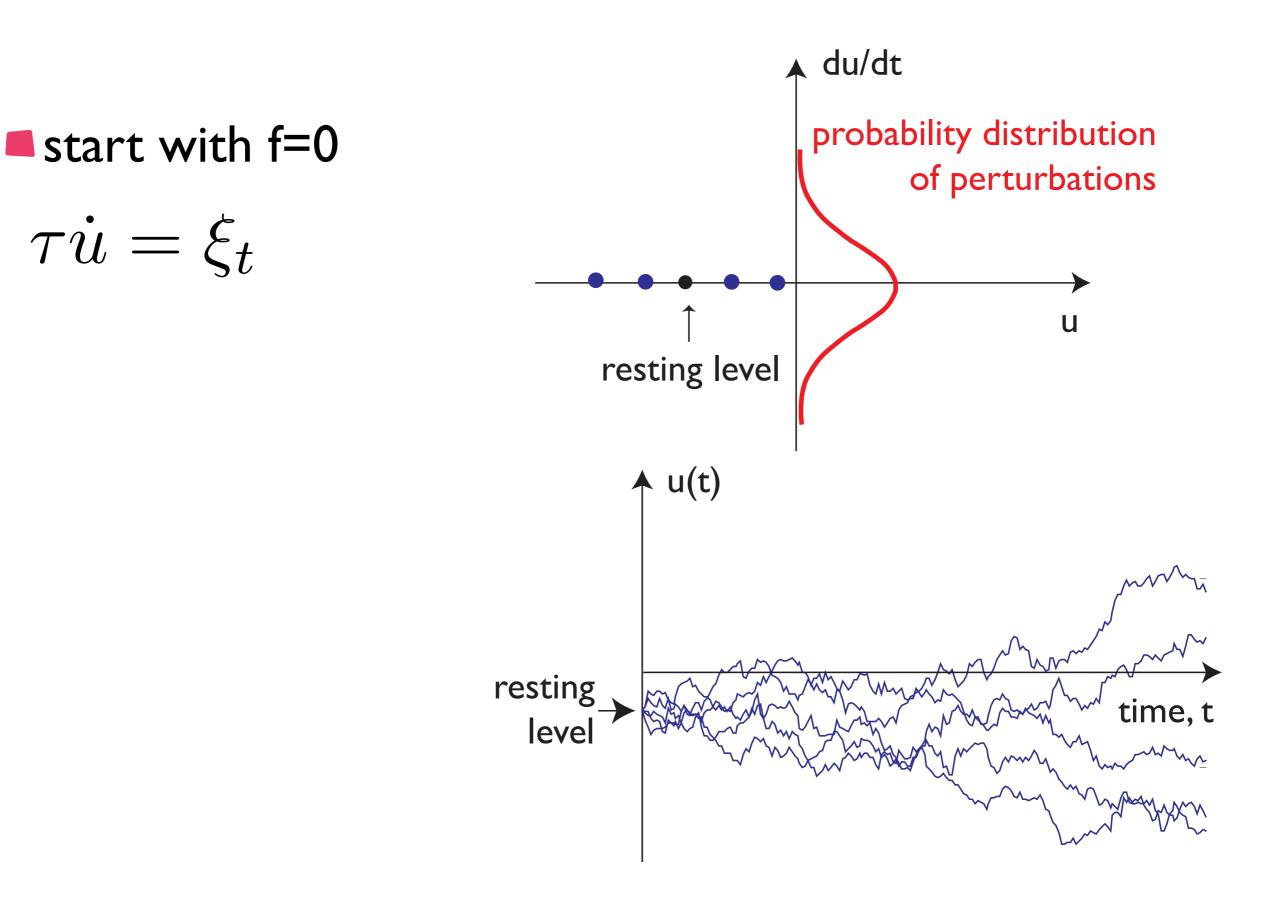
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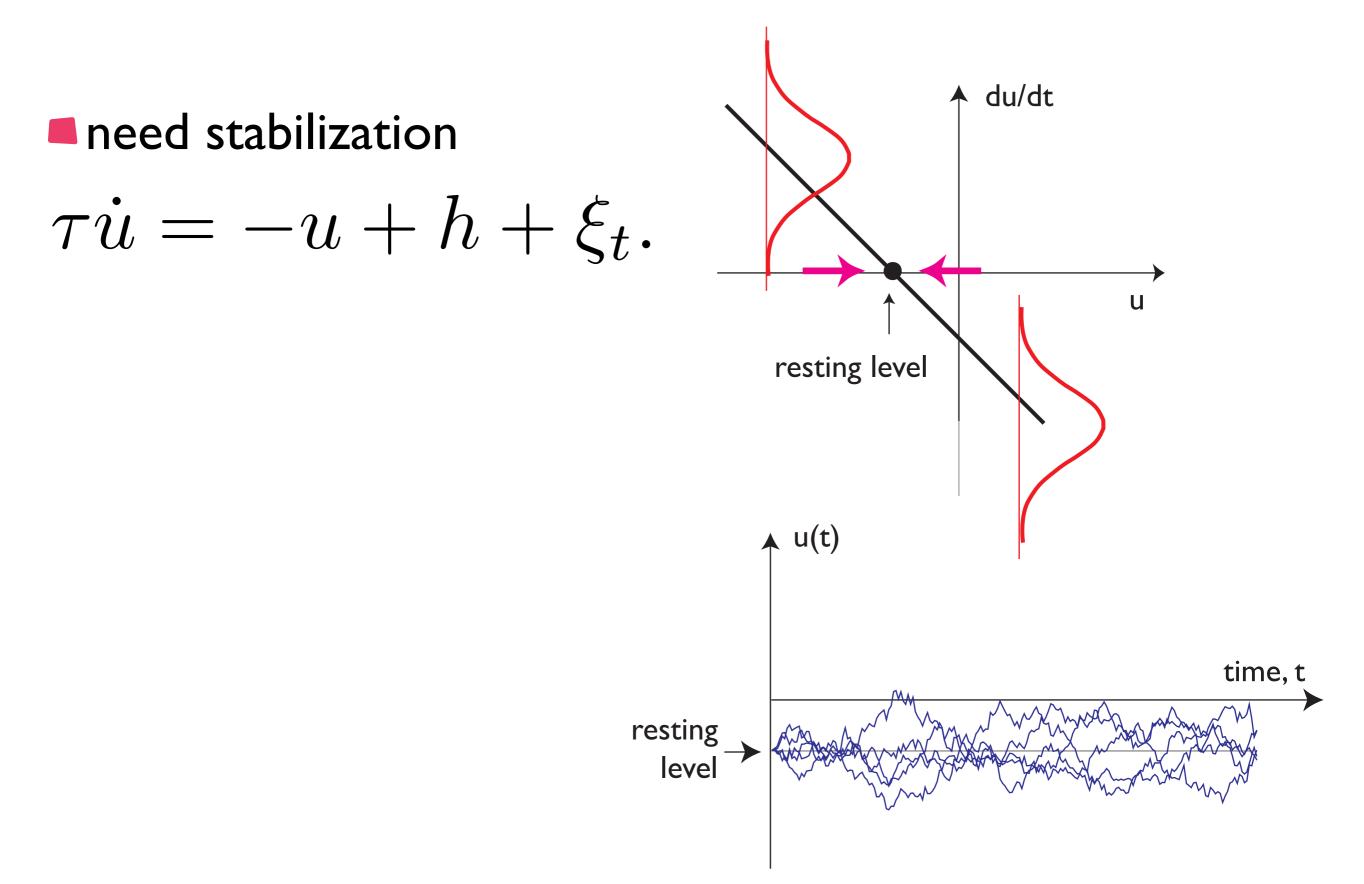
activation variables u(t) as time continuous functions...

$$\tau \dot{u}(t) = f(u)$$

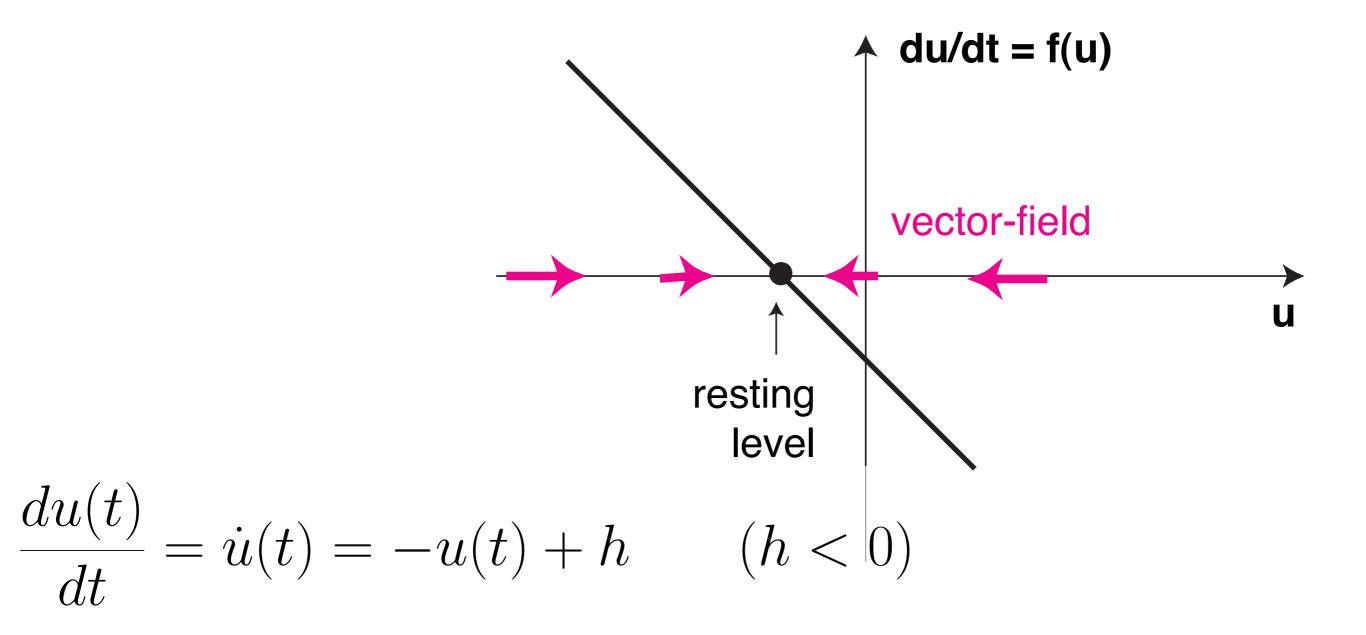
what function f?





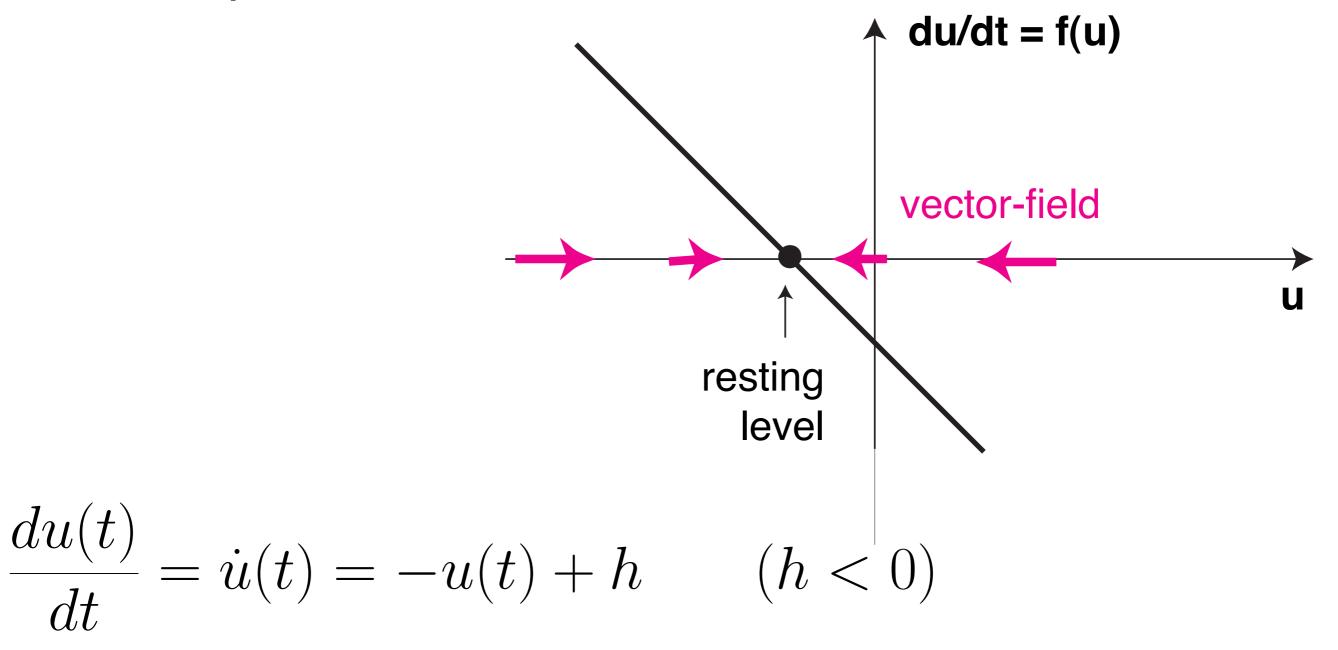


In a dynamical system, the present predicts the future: given the initial level of activation u(0), the activation at time t: u(t) is uniquely determined



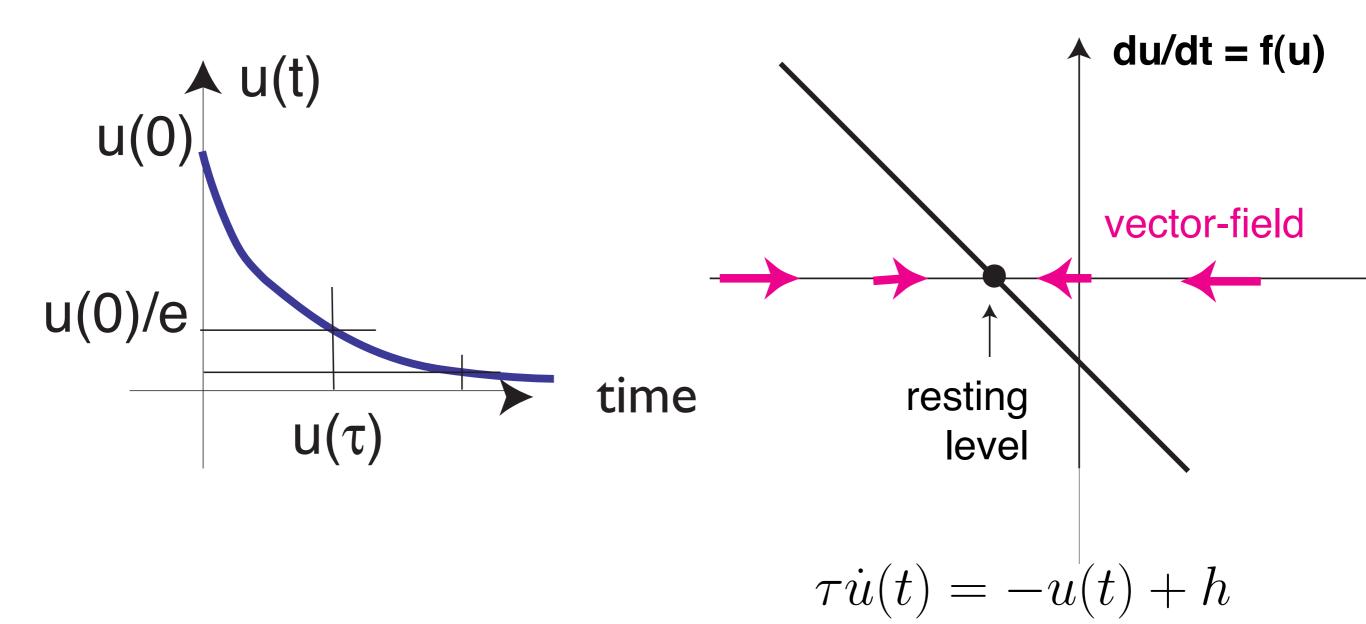
stationary state=fixed point= constant solution

stable fixed point: nearby solutions converge to the fixed point=attractor

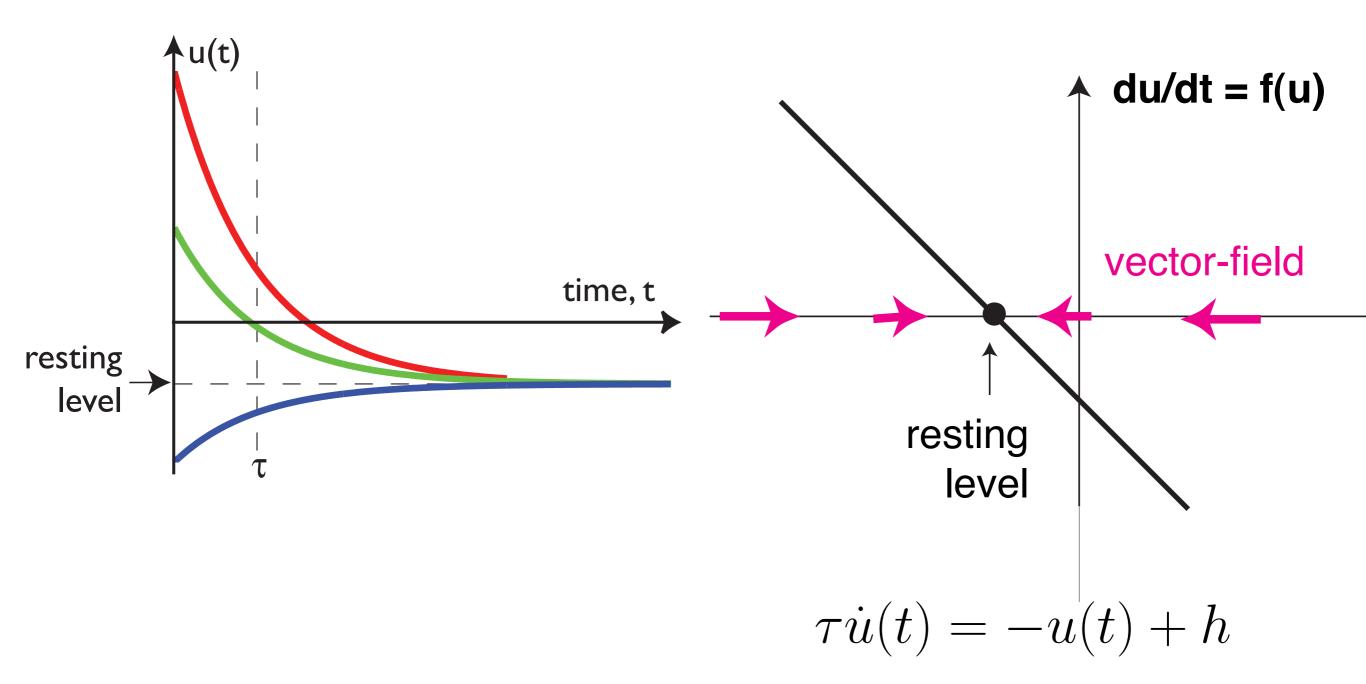


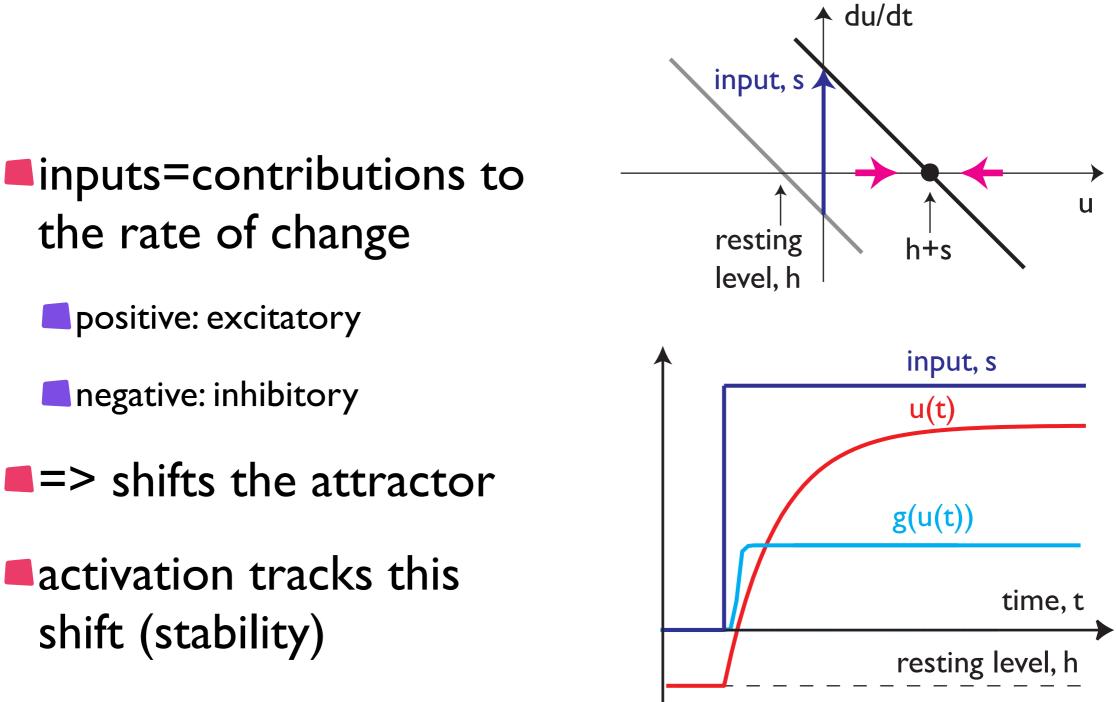
exponential relaxation to fixed-point attractors

=> time scale



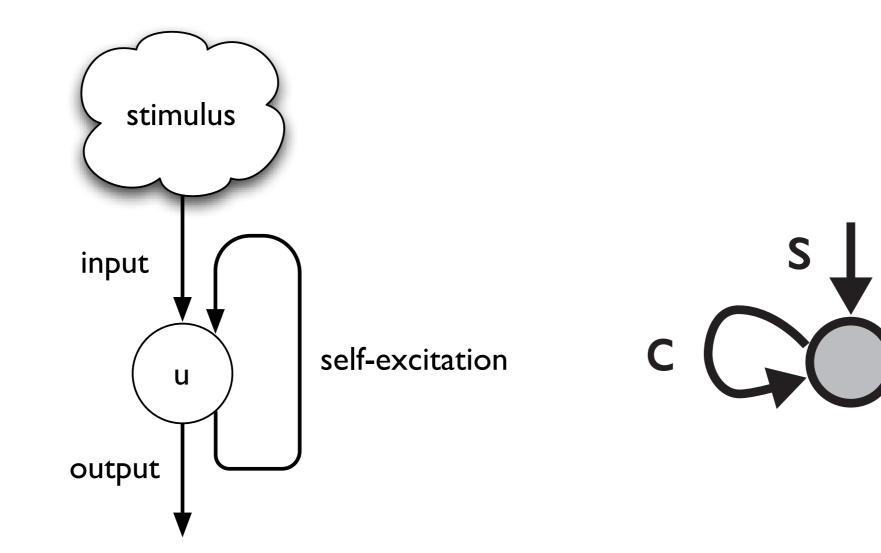
attractor structures ensemble of solutions=flow



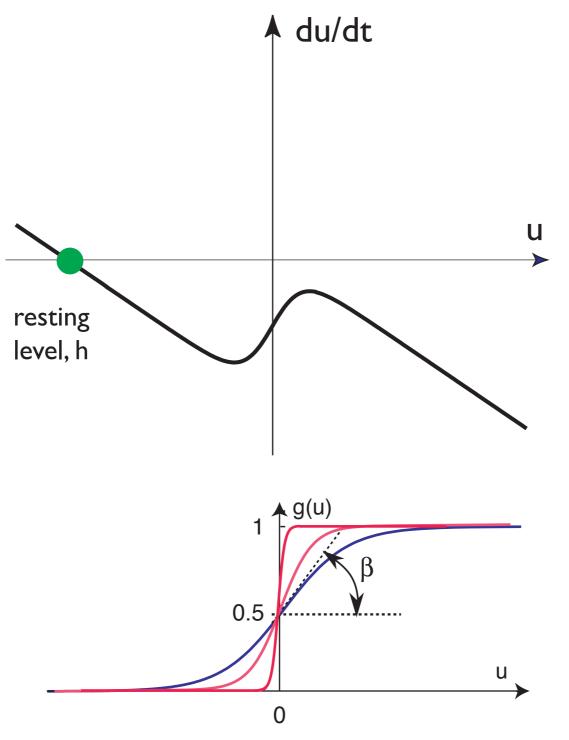


$$\tau \dot{u}(t) = -u(t) + h + \text{ inputs}(t)$$

#### => simulation

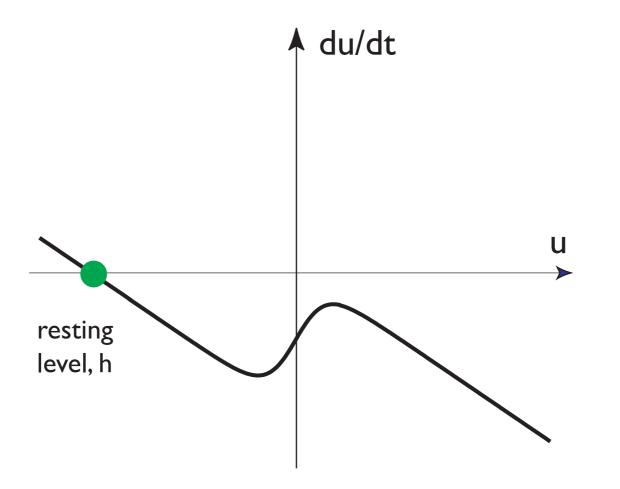


$$\tau \dot{u}(t) = -u(t) + h + S(t) + c\sigma(u(t))$$

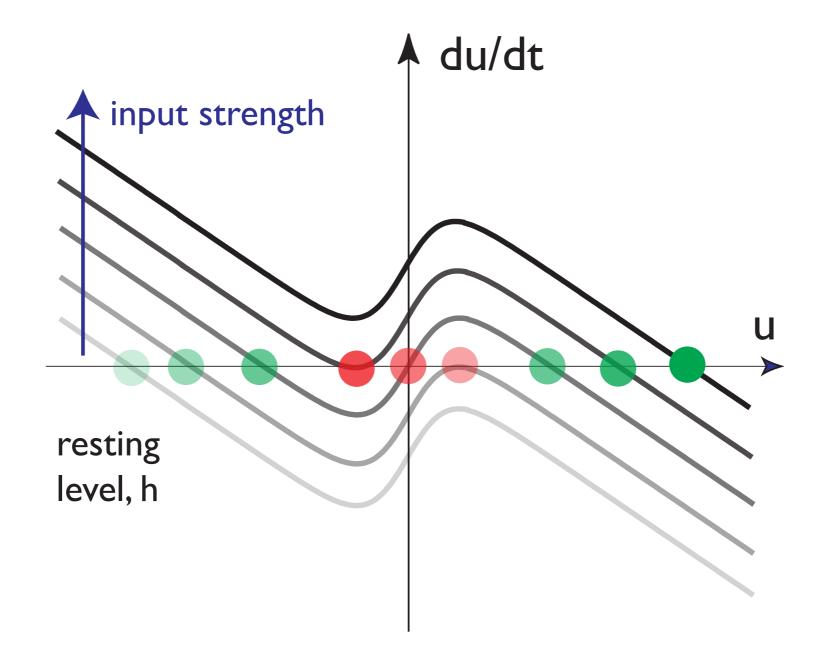


 $\tau \dot{u}(t) = -u(t) + h + S(t) + c\sigma(u(t))$ 

=> this is nonlinear dynamics!

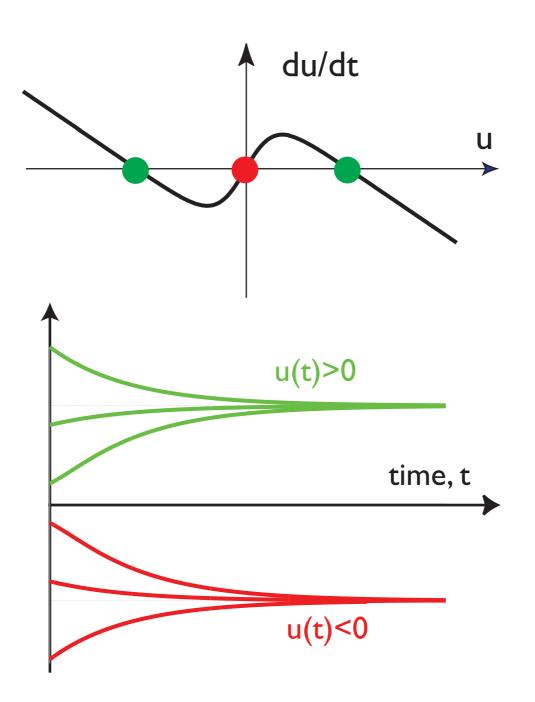


stimulus input

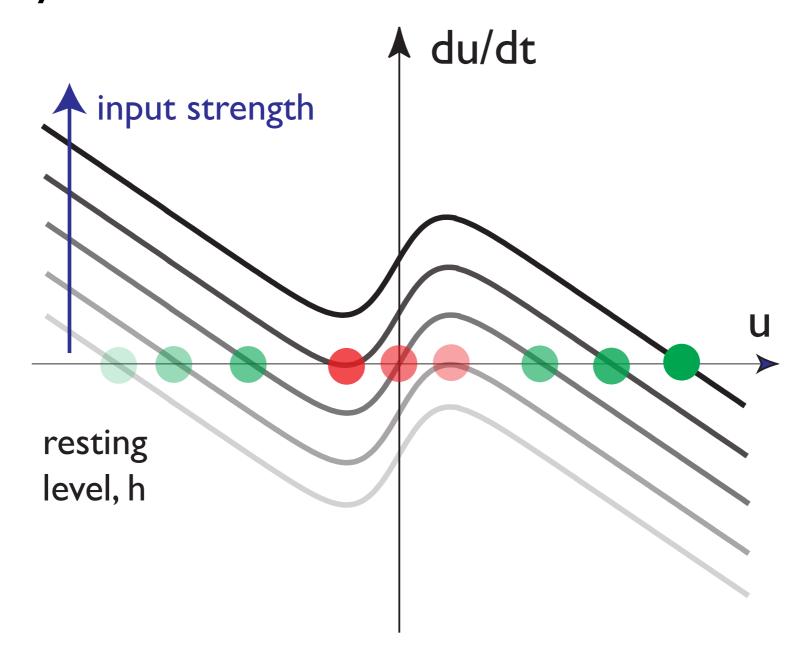


bistable regime at intermediate stimulus strength

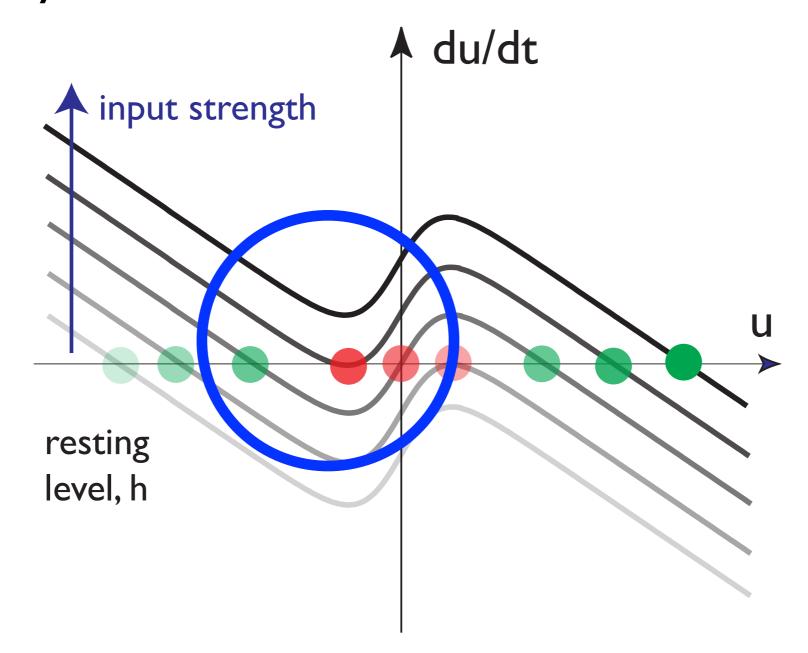
=> essentially nonlinear!



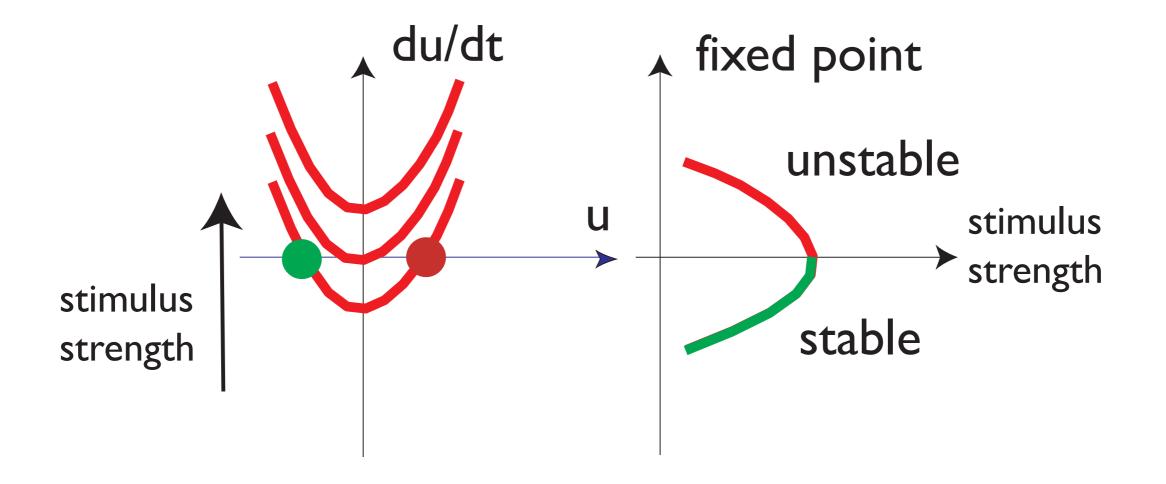
with varying input strength system goes through two instabilities: the detection and the reverse detection instability



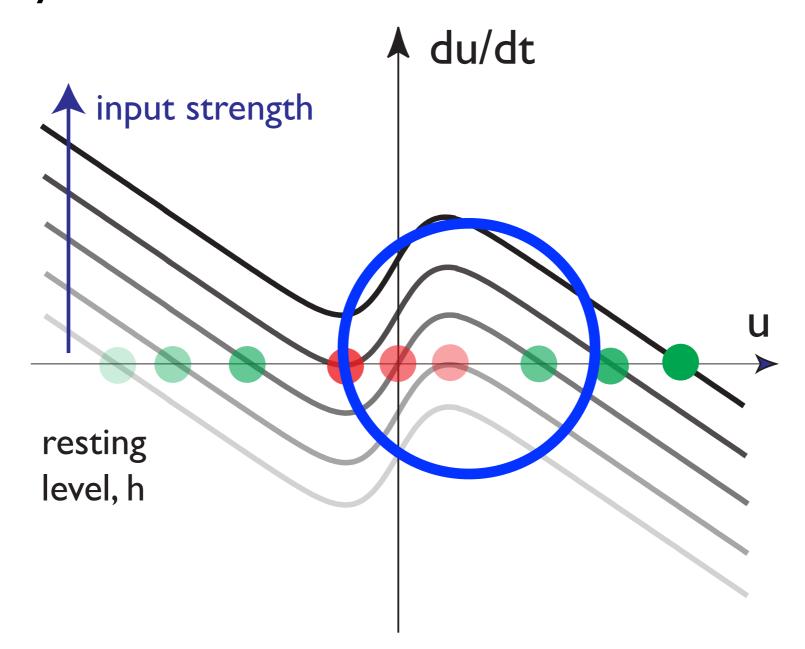
with varying input strength system goes through two instabilities: the detection and the reverse detection instability



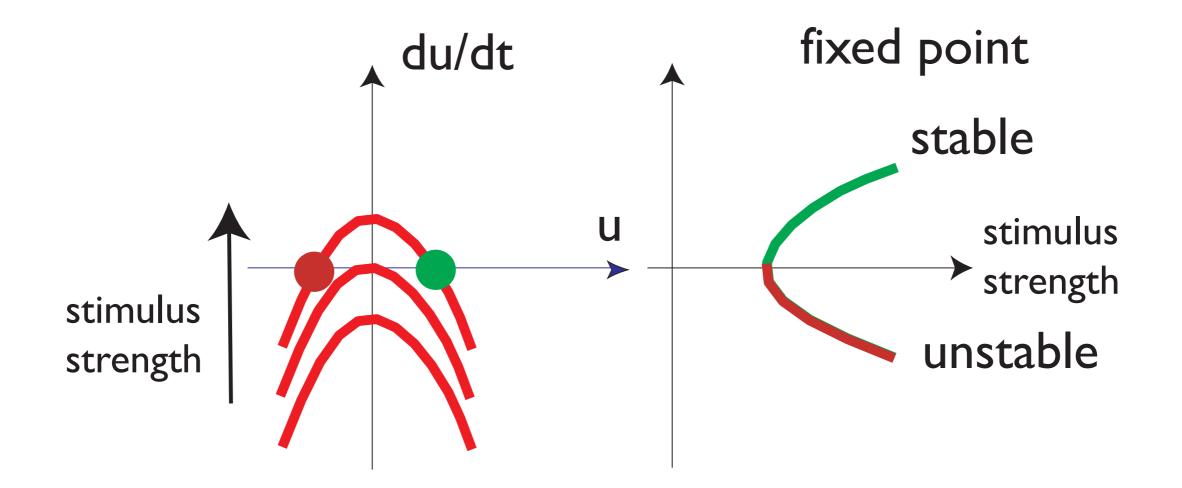
detection instability



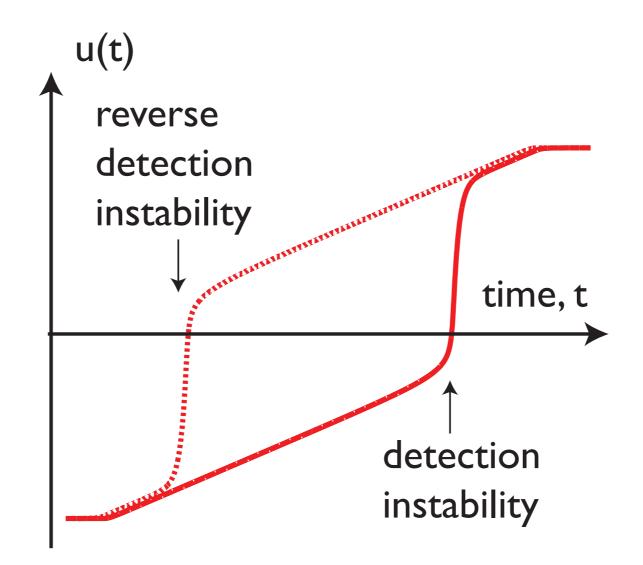
with varying input strength system goes through two instabilities: the detection and the reverse detection instability



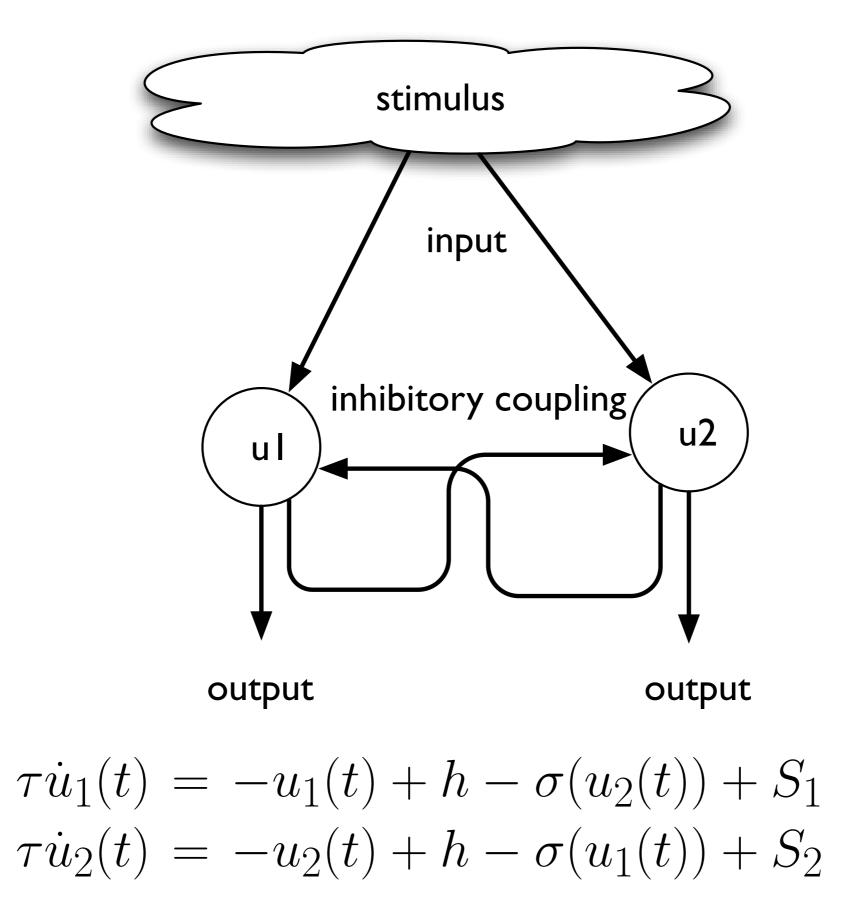
reverse detection instability



signature of instabilities: hysteresis







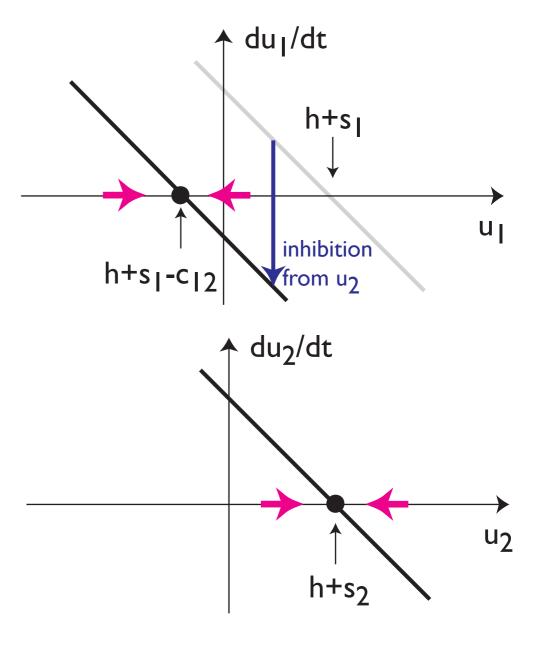
the rate of change of activation at one site depends on the level of activation at the other site

mutual inhibition

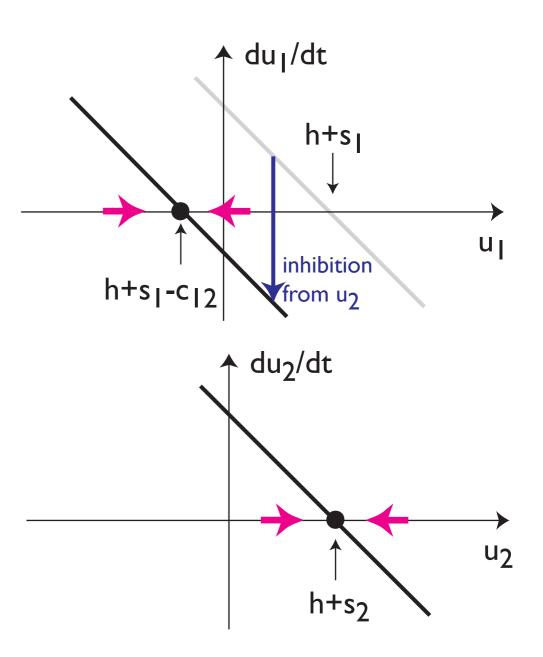
$$\begin{aligned} \tau \dot{u}_1(t) &= -u_1(t) + h - \sigma(u_2(t)) + S_1 \\ \tau \dot{u}_2(t) &= -u_2(t) + h - \sigma(u_1(t)) + S_2 \end{aligned}$$

to visualize, assume that u\_2 has been activated by input to positive level

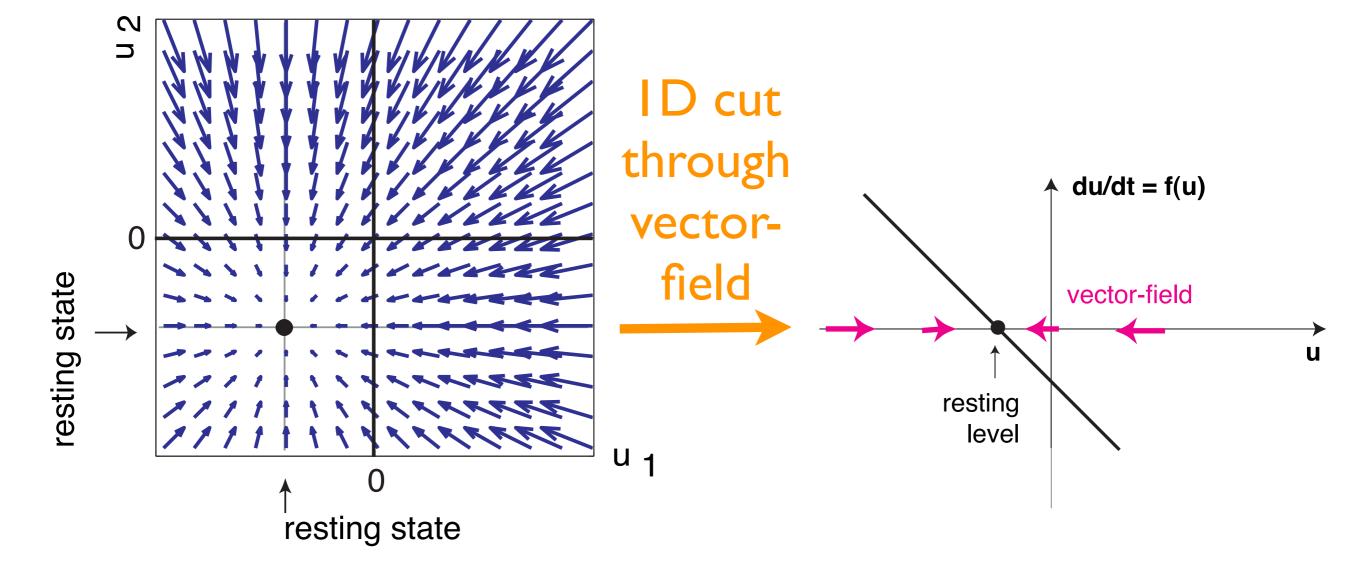
then u\_l is suppressed

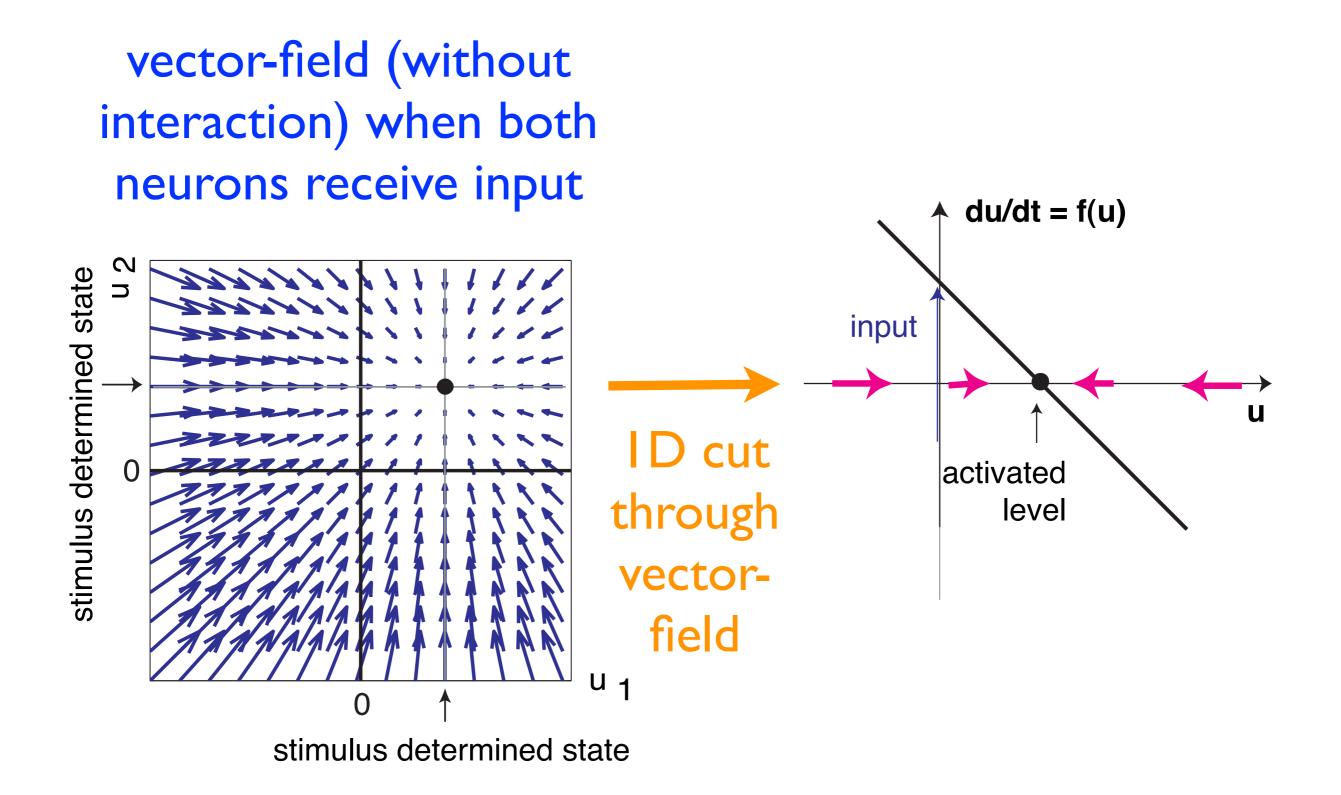


- why would u\_2 be positive before u\_1 is? E.g., it grew faster than u\_1 because its inputs are stronger/inputs match better
- => input advantage translates into time advantage which translates into competitive advantage

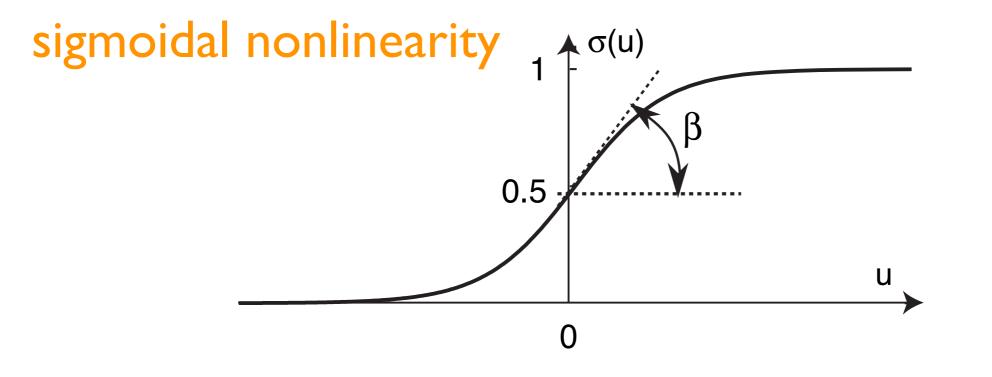




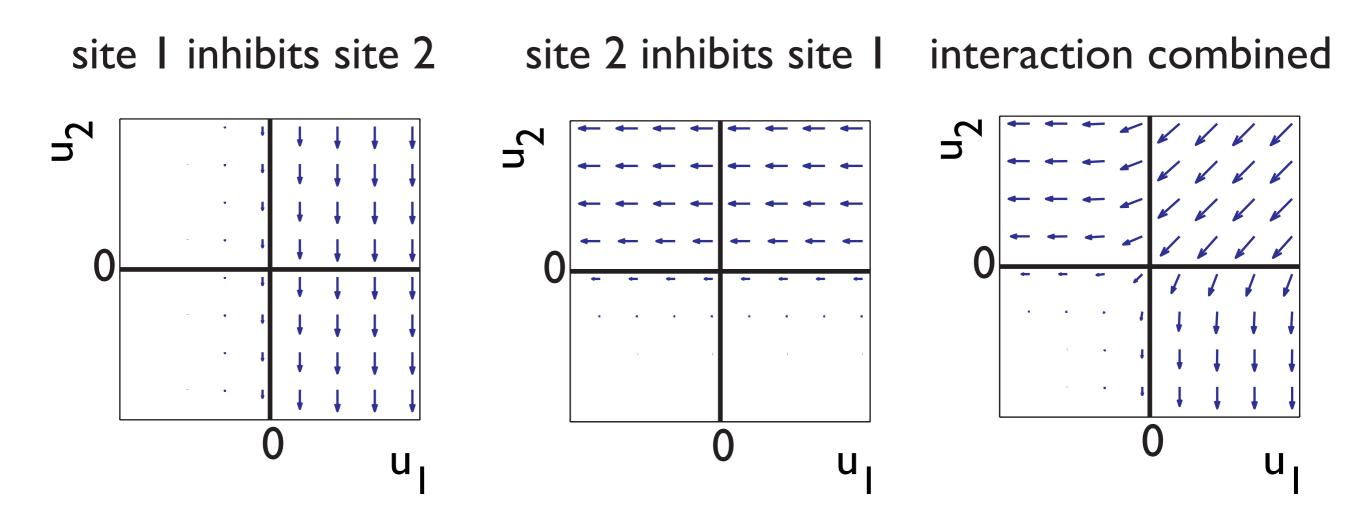




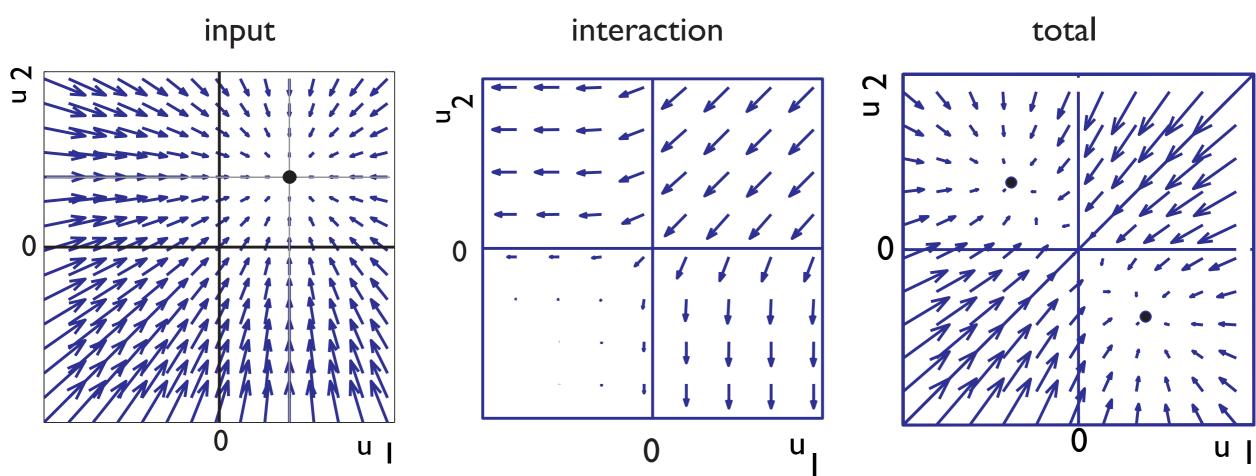
only activated neurons participate in interaction!

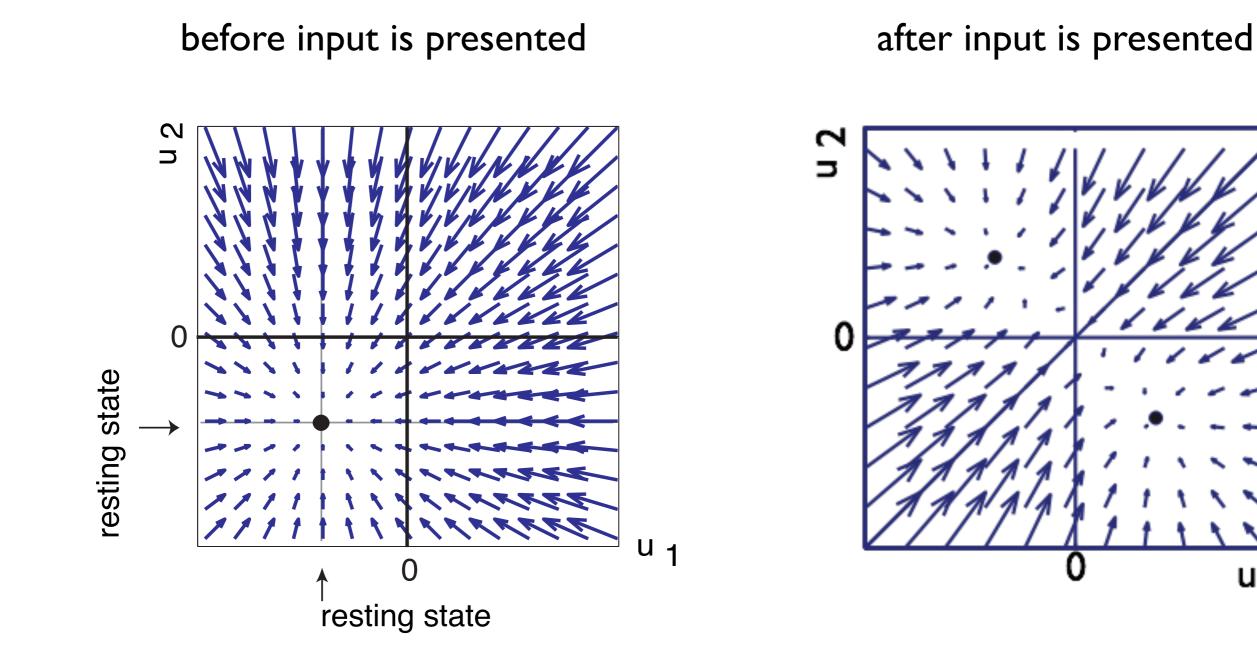


#### vector-field of mutual inhibition



#### vector-field with strong mutual inhibition: bistable



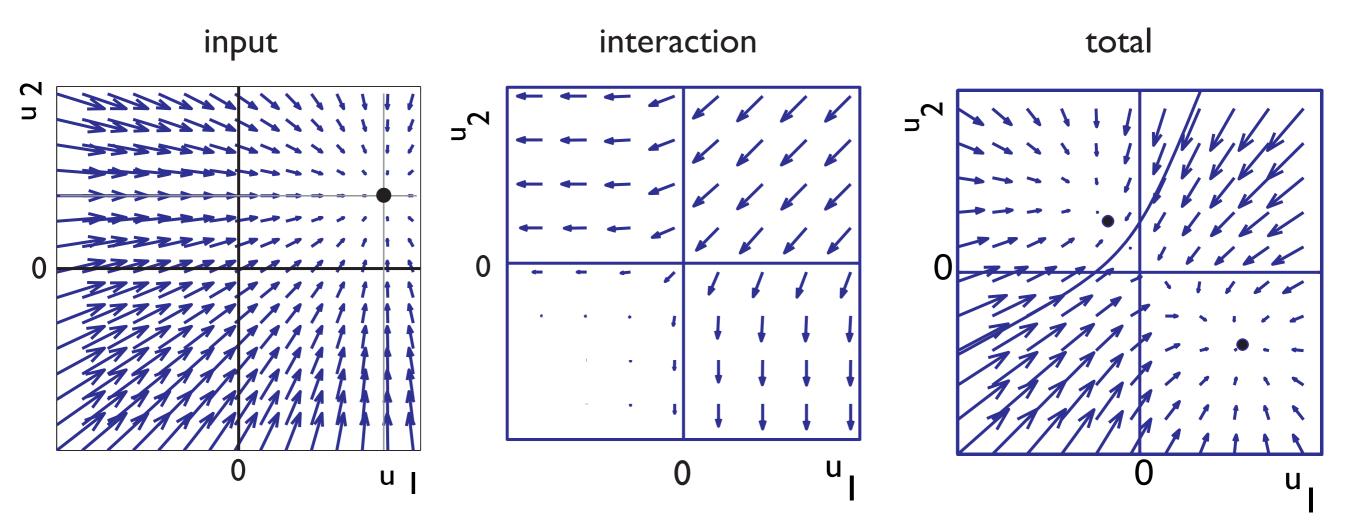


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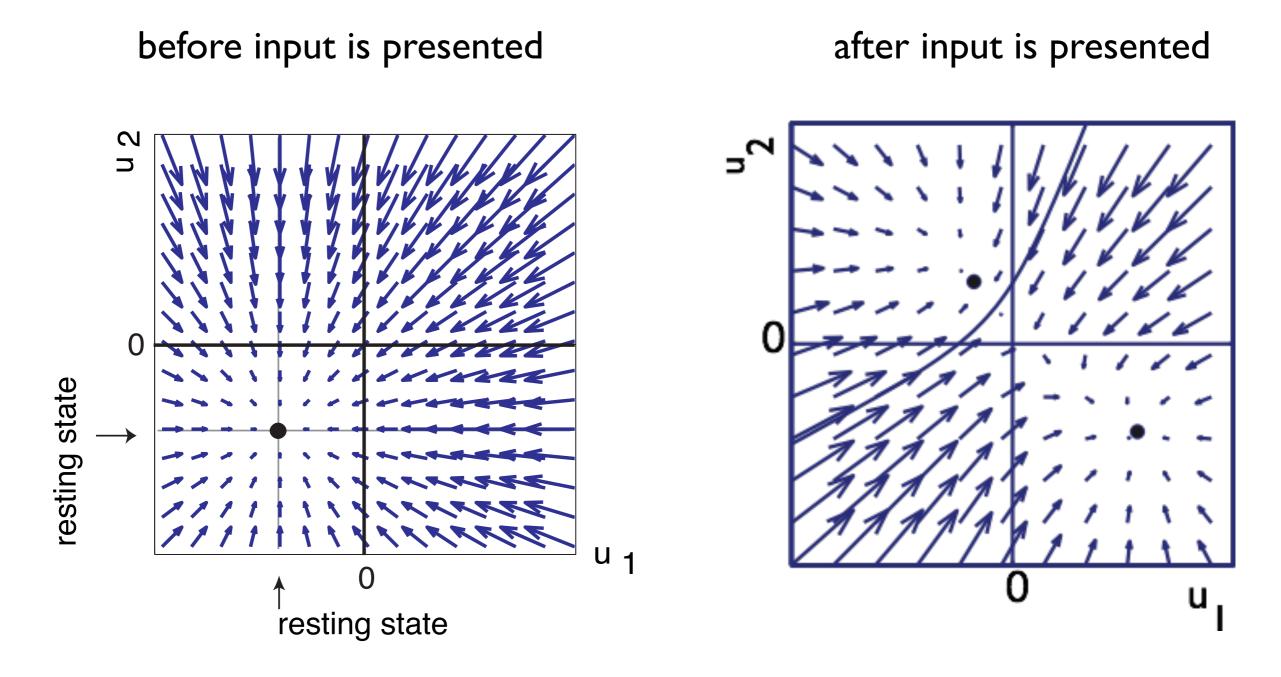
# Neuronal dynamics with competition =>biased competition

stronger input to site 1: attractor with activated u\_1 stronger,

attractor with activated u\_2 weaker, may become unstable



## Neuronal dynamics with competition =>biased competition





where do activation variables come from?

how do discrete activation variables reflect continuous behaviors?

DFT lecture