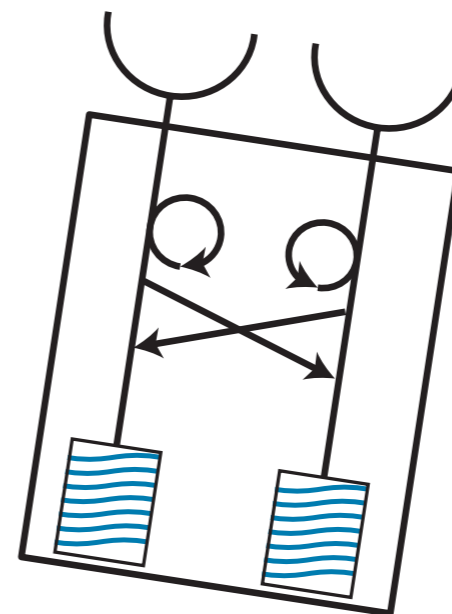
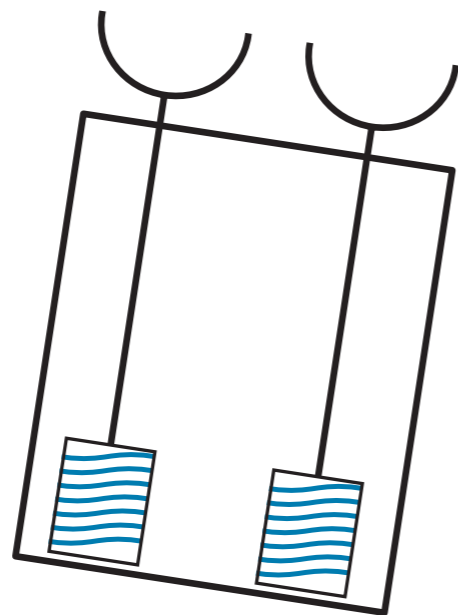
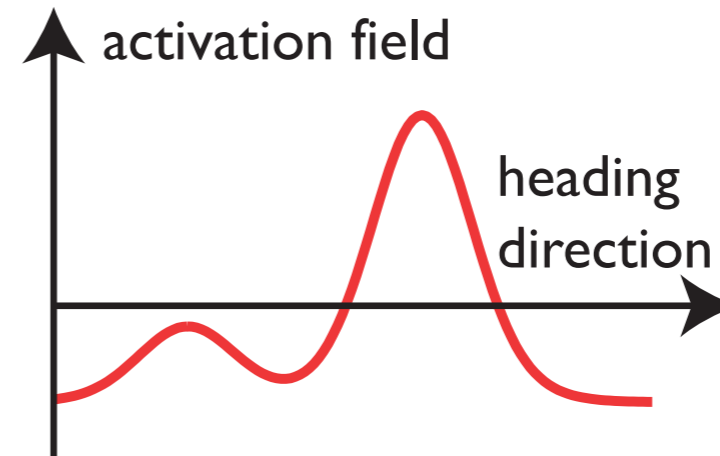
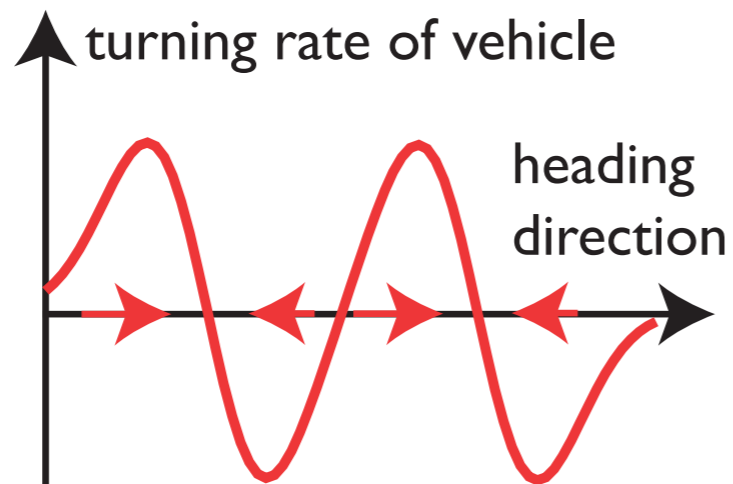


Neural Dynamics

Gregor Schöner

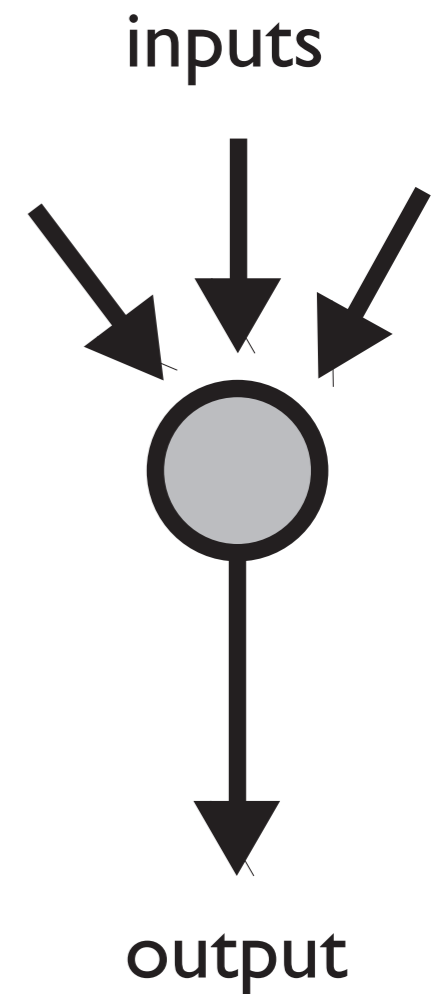
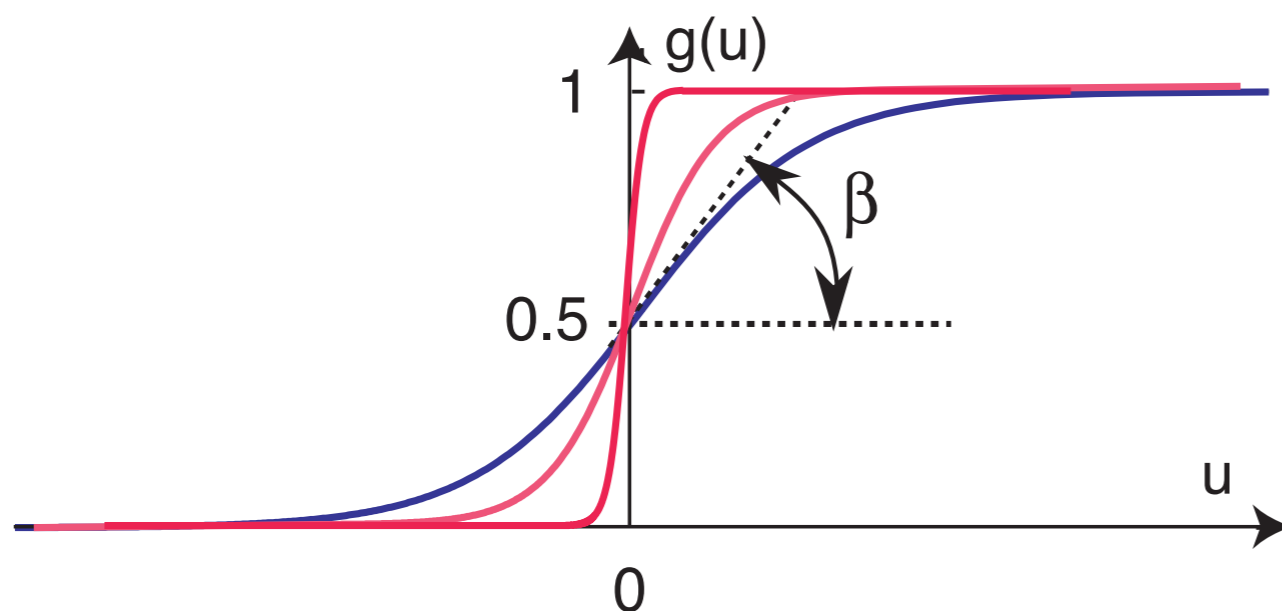
gregor.schoener@ini.rub.de

... from behavioral to neural dynamics



Neurons as input-output threshold elements

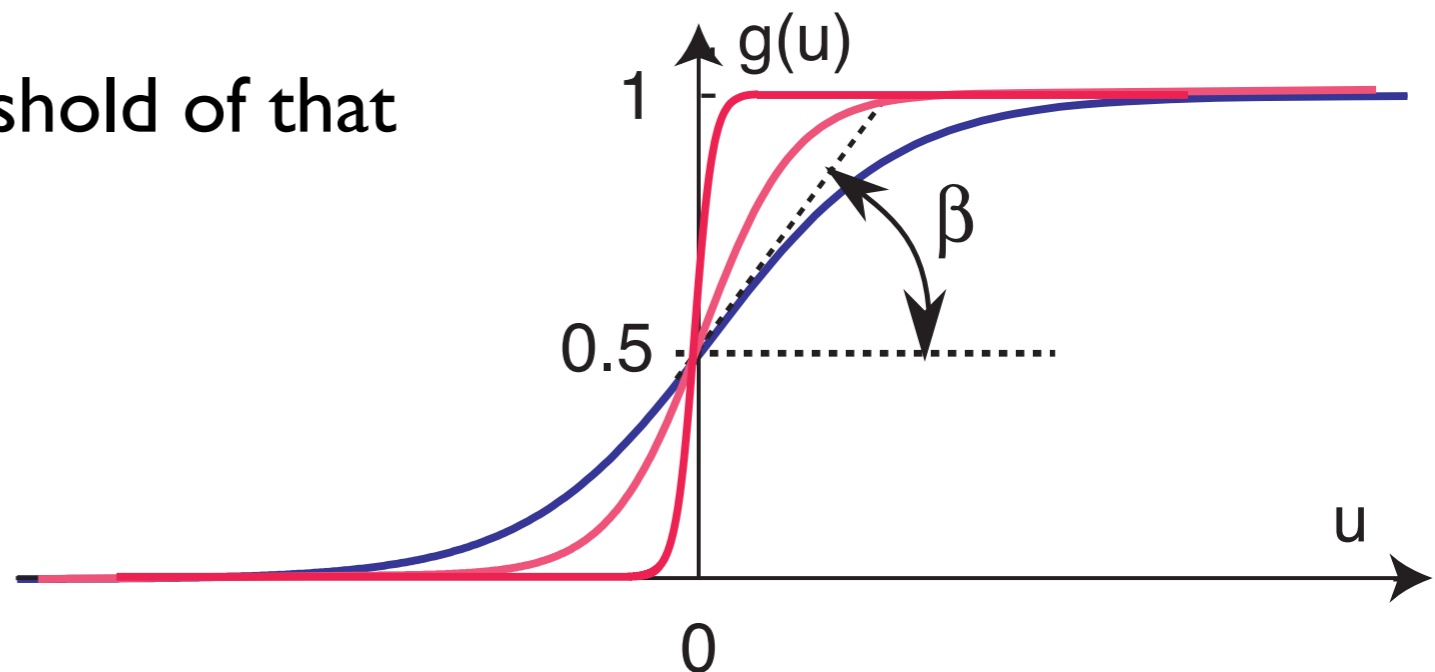
- activation state (membrane potential or spiking rate)
- summing inputs and generating output through a sigmoidal threshold function



$$\text{output} = g \left(\sum (\text{inputs}) \right)$$

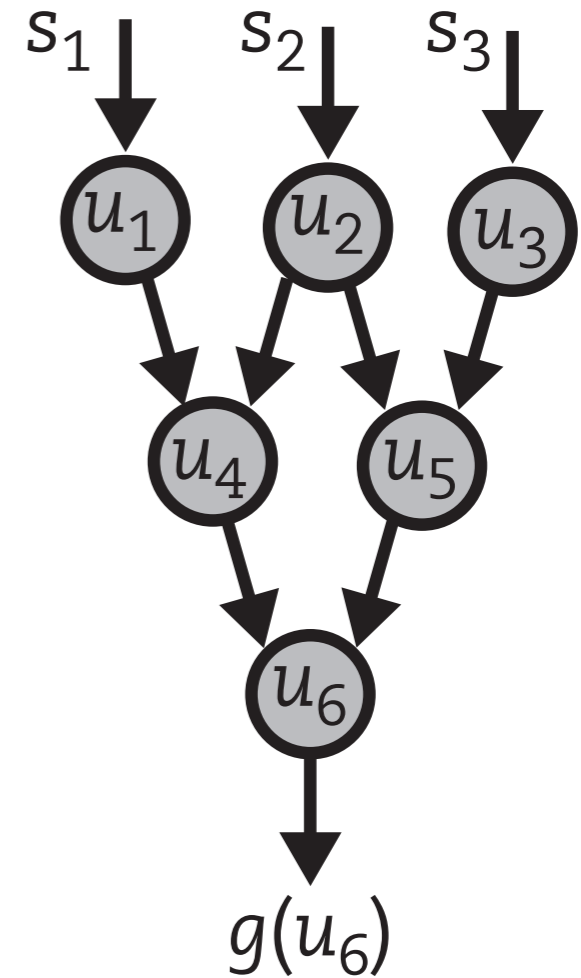
Activation

- activation as a real number, abstracting from biophysical details
- low levels of activation: not transmitted to other systems (e.g., to motor systems)
- high levels of activation: transmitted to other systems
- as described by sigmoidal threshold function
- zero activation defined as threshold of that function



(Forward) neural networks

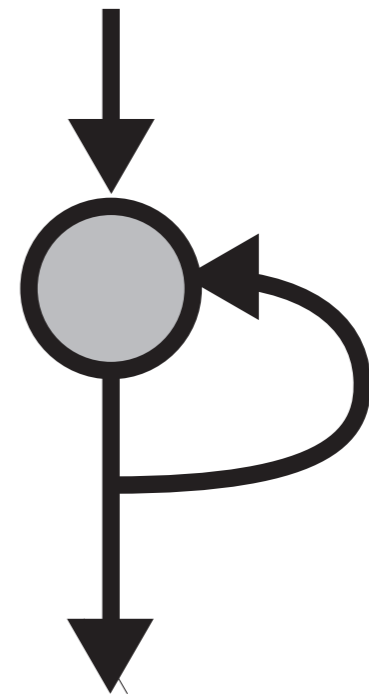
- output from one set of neurons provides input to another set of neuron



Recurrent neural networks

■ neural dynamics...

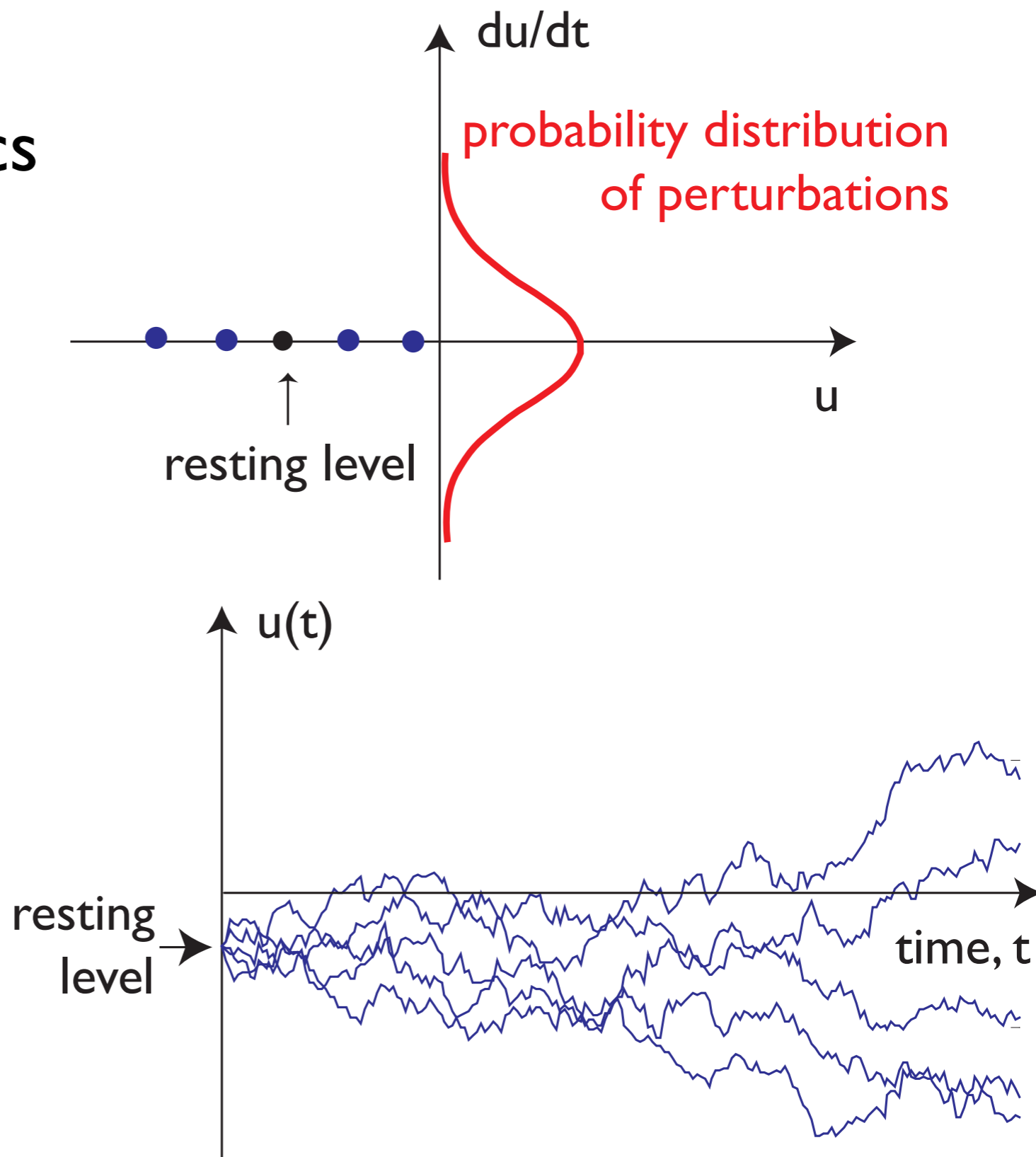
$$\dot{u}(t) = -u(t) + h + \text{input}(t) + g(u(t))$$



Activation dynamics

■ naive neural dynamics

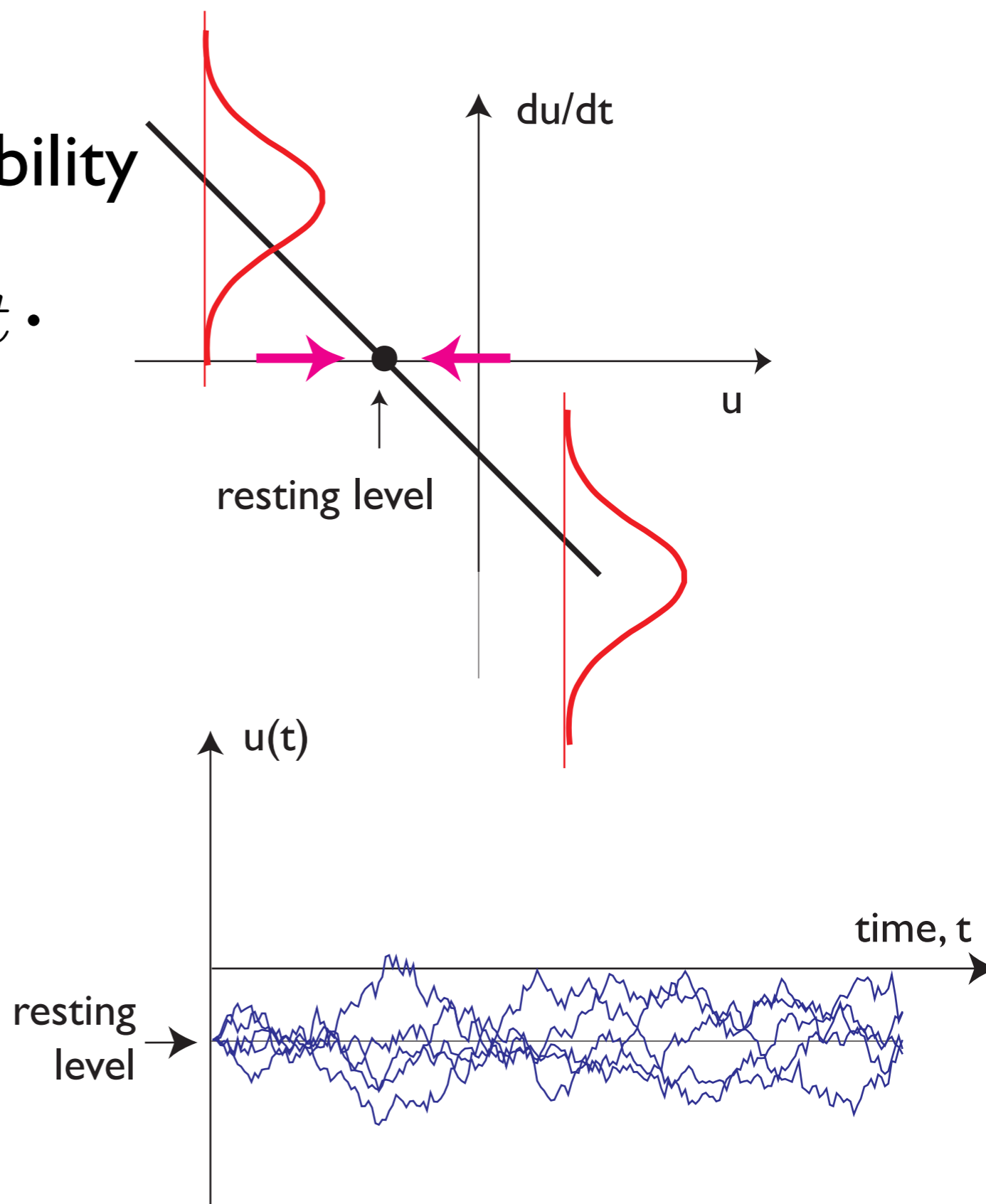
$$\tau \dot{u} = \xi_t$$



Activation dynamics

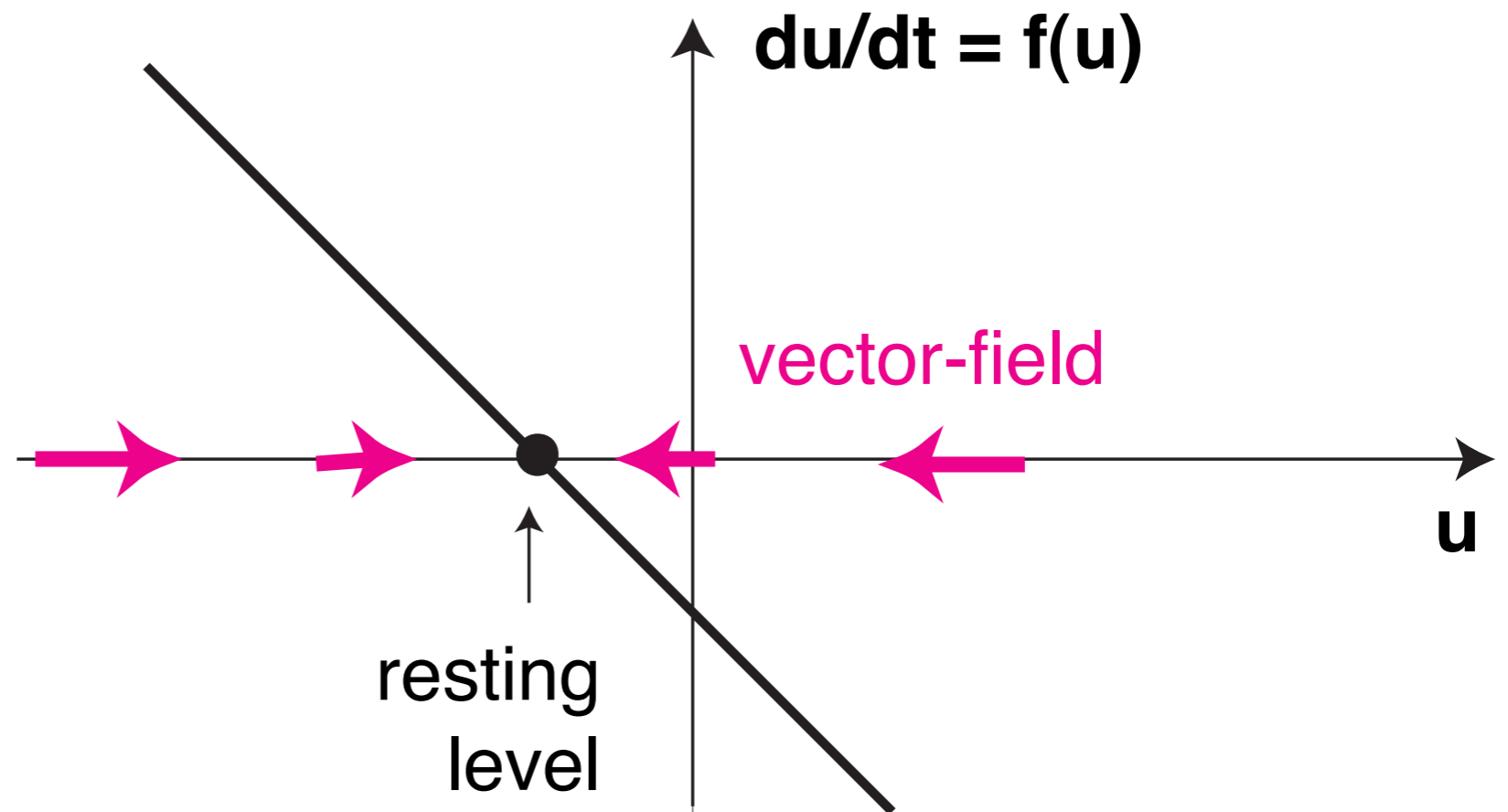
- neural dynamics with stability

$$\tau \dot{u} = -u + h + \xi_t.$$



Neural dynamics

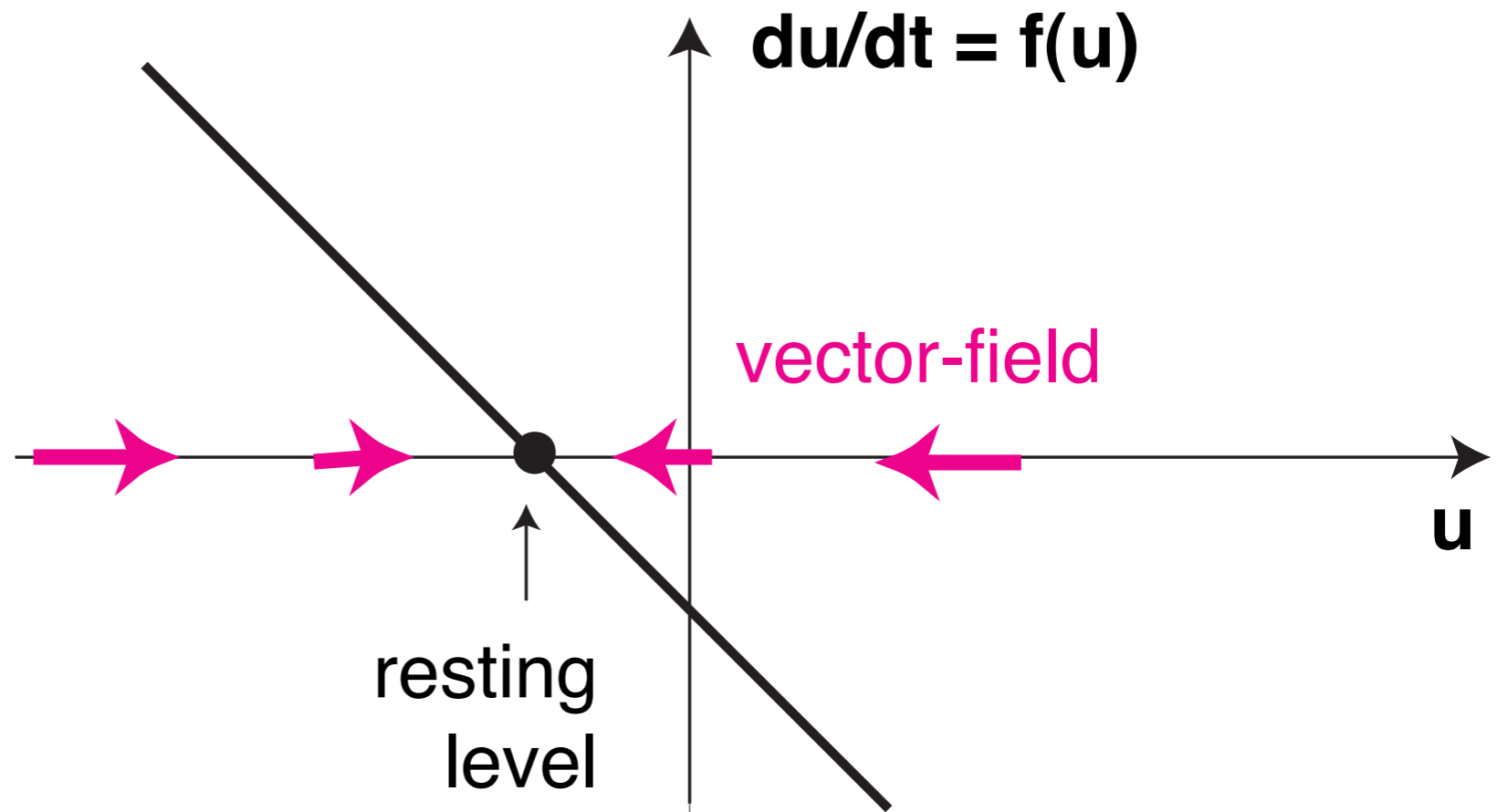
- In a dynamical system, the present predicts the future: given the initial level of activation $u(0)$, the activation at time t : $u(t)$ is uniquely determined



$$\frac{du(t)}{dt} = \dot{u}(t) = -u(t) + h \quad (h < 0)$$

Neural dynamics

- stationary state=**fixed point**= constant solution
- stable fixed point: nearby solutions converge to the fixed point=**attractor**

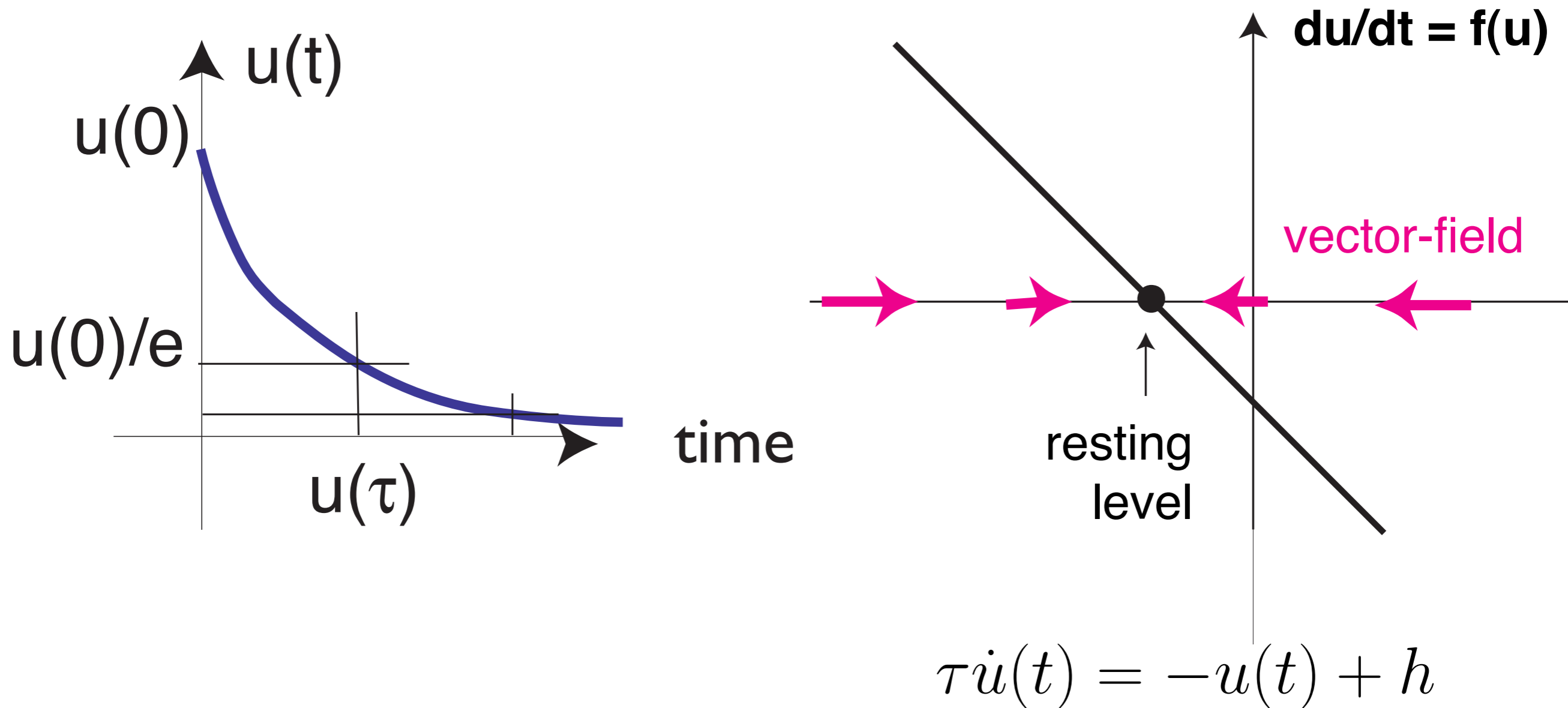


$$\frac{du(t)}{dt} = \dot{u}(t) = -u(t) + h \quad (h < 0)$$

Neural dynamics

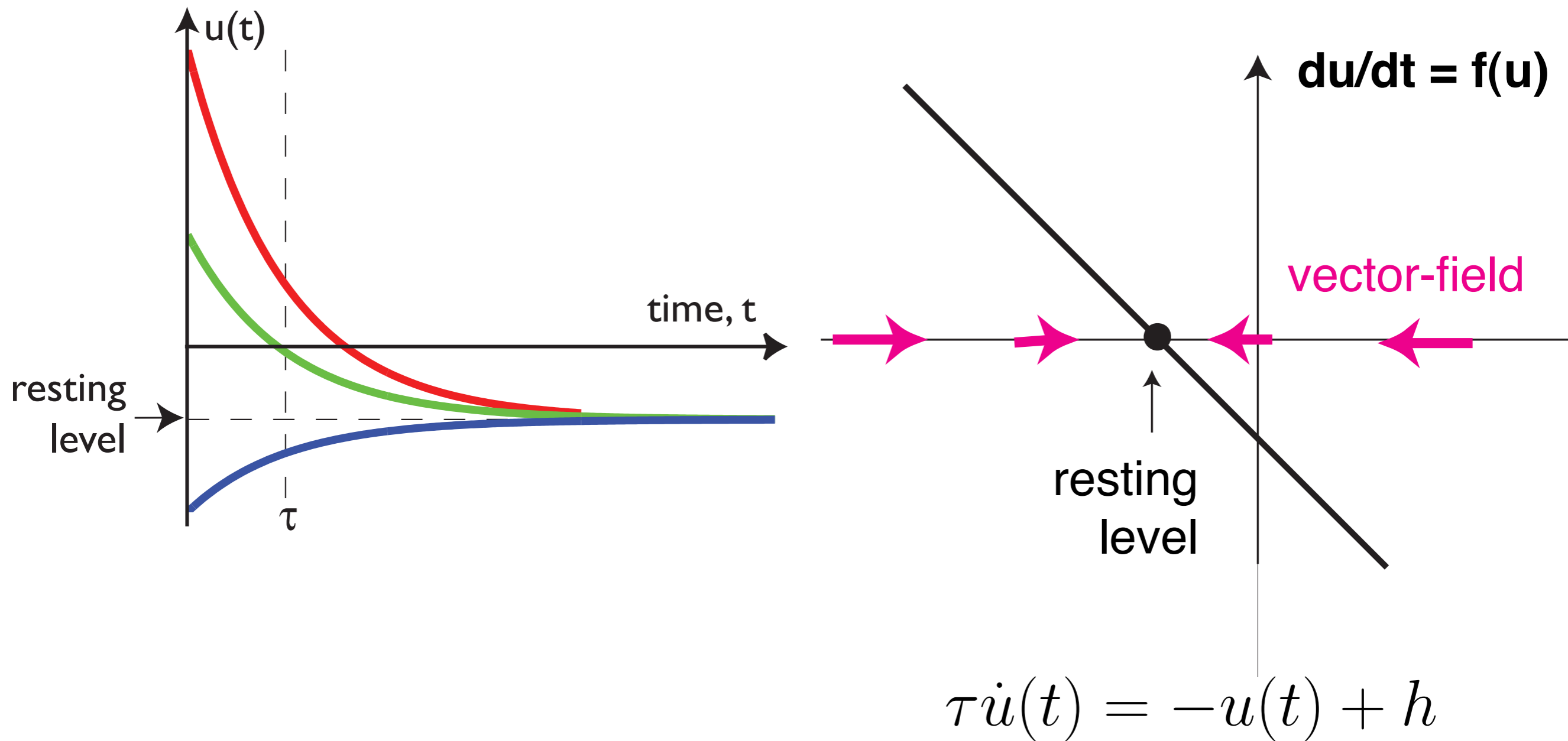
■ exponential relaxation to fixed-point attractors

■ => time scale



Neural dynamics

- attractor structures ensemble of solutions=flow



Neuronal dynamics

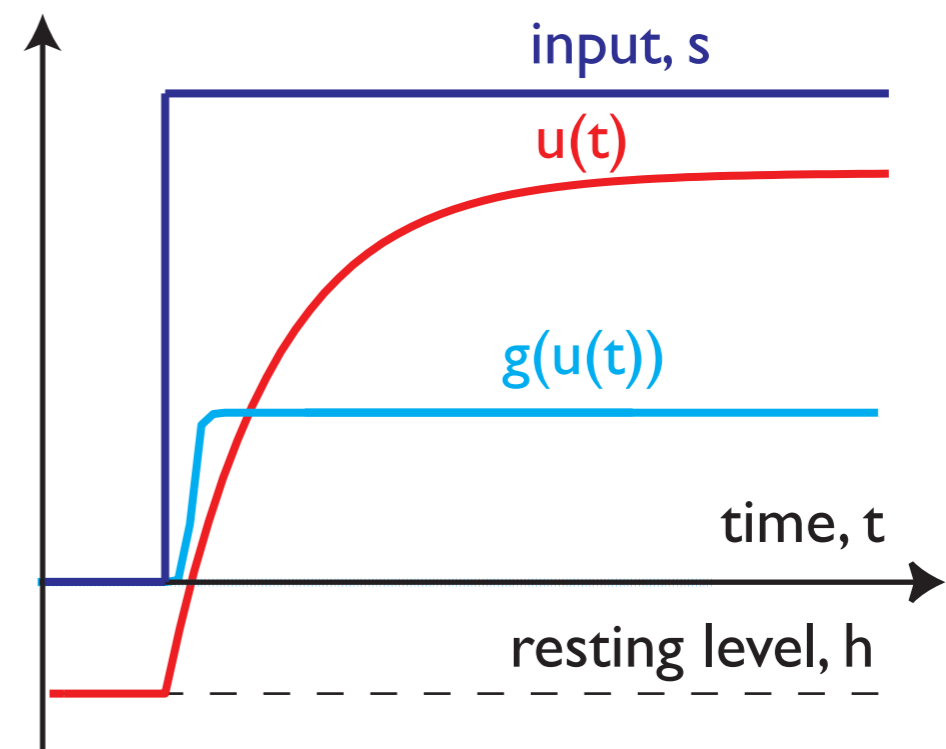
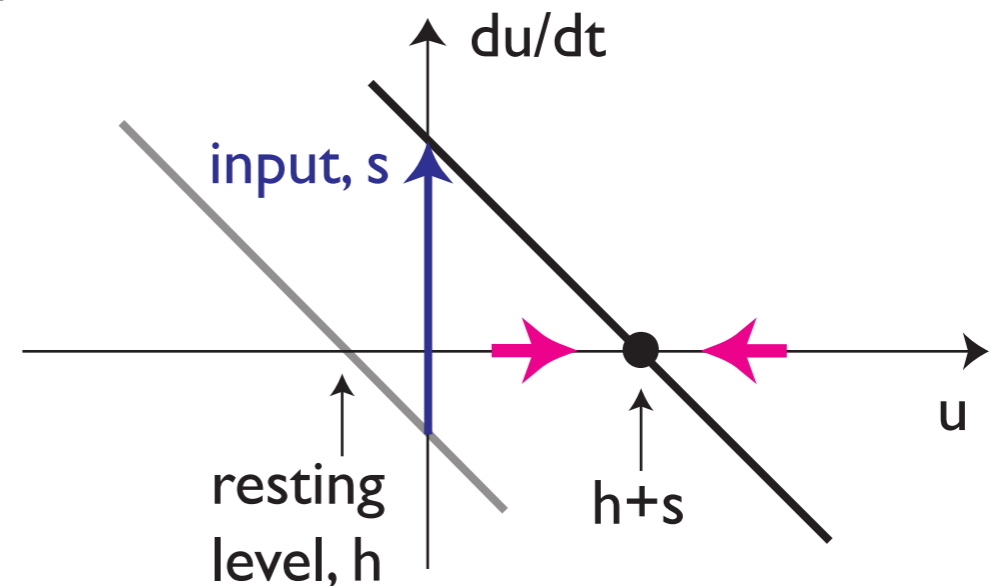
■ inputs=contributions to the rate of change

■ positive: excitatory

■ negative: inhibitory

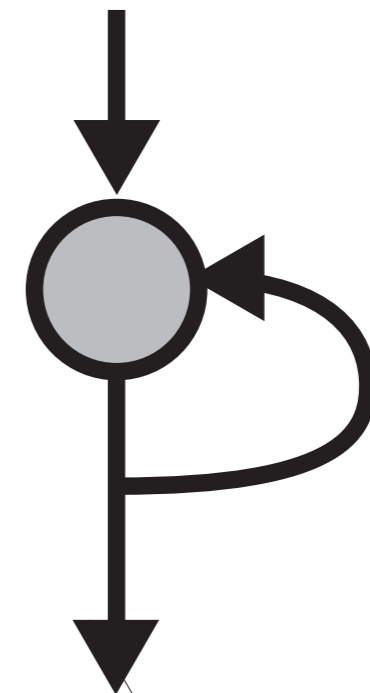
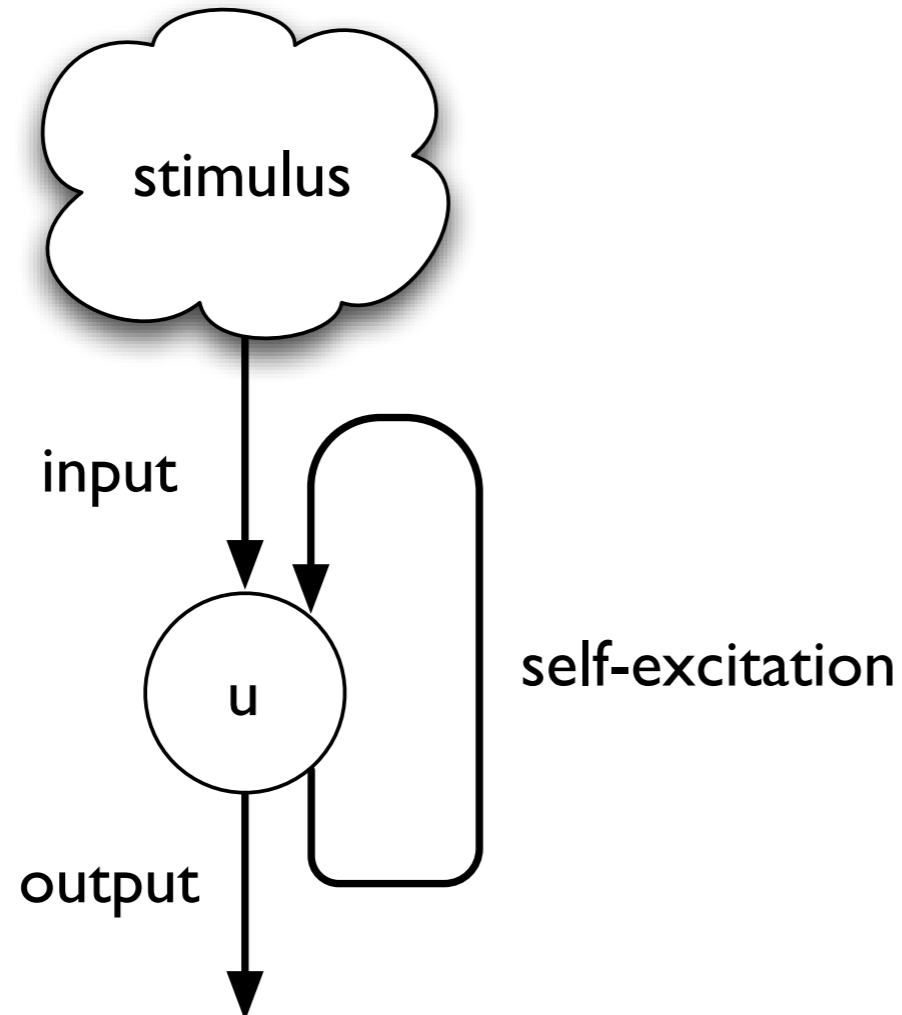
■ => shifts the attractor

■ activation tracks this shift (stability)



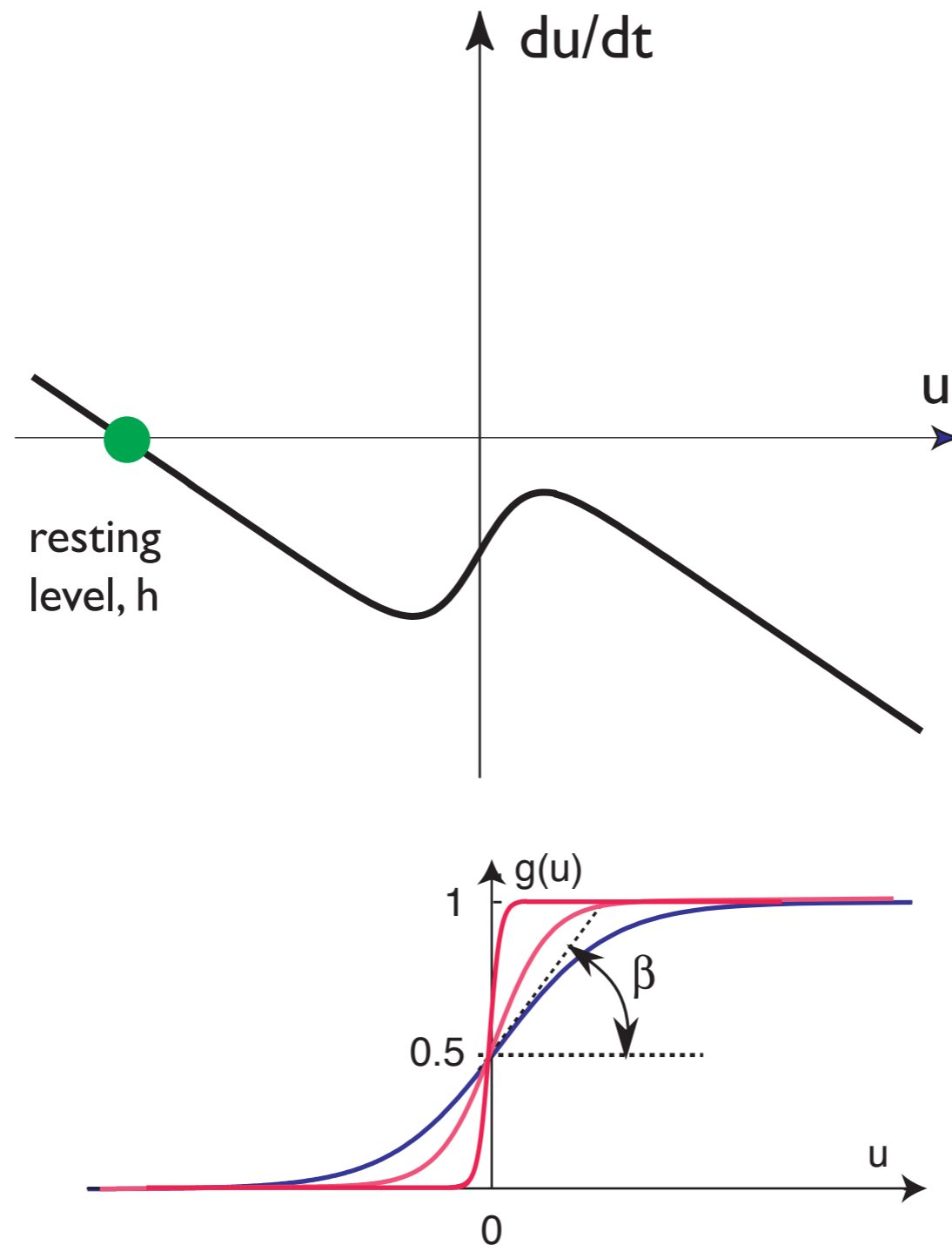
$$\tau \dot{u}(t) = -u(t) + h + \text{inputs}(t)$$

Neuronal dynamics with self-excitation



$$\tau \dot{u}(t) = -u(t) + h + S(t) + c\sigma(u(t))$$

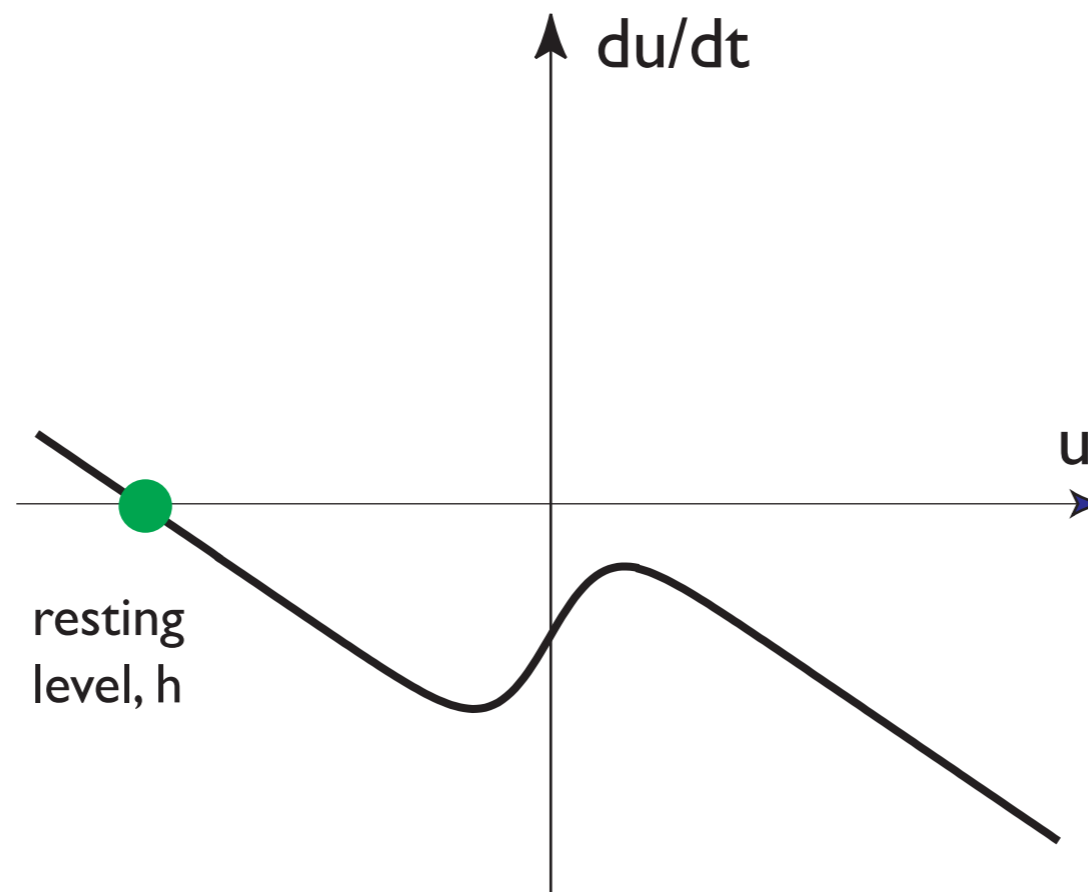
Neuronal dynamics with self-excitation



$$\tau \dot{u}(t) = -u(t) + h + S(t) + c\sigma(u(t))$$

Neuronal dynamics with self-excitation

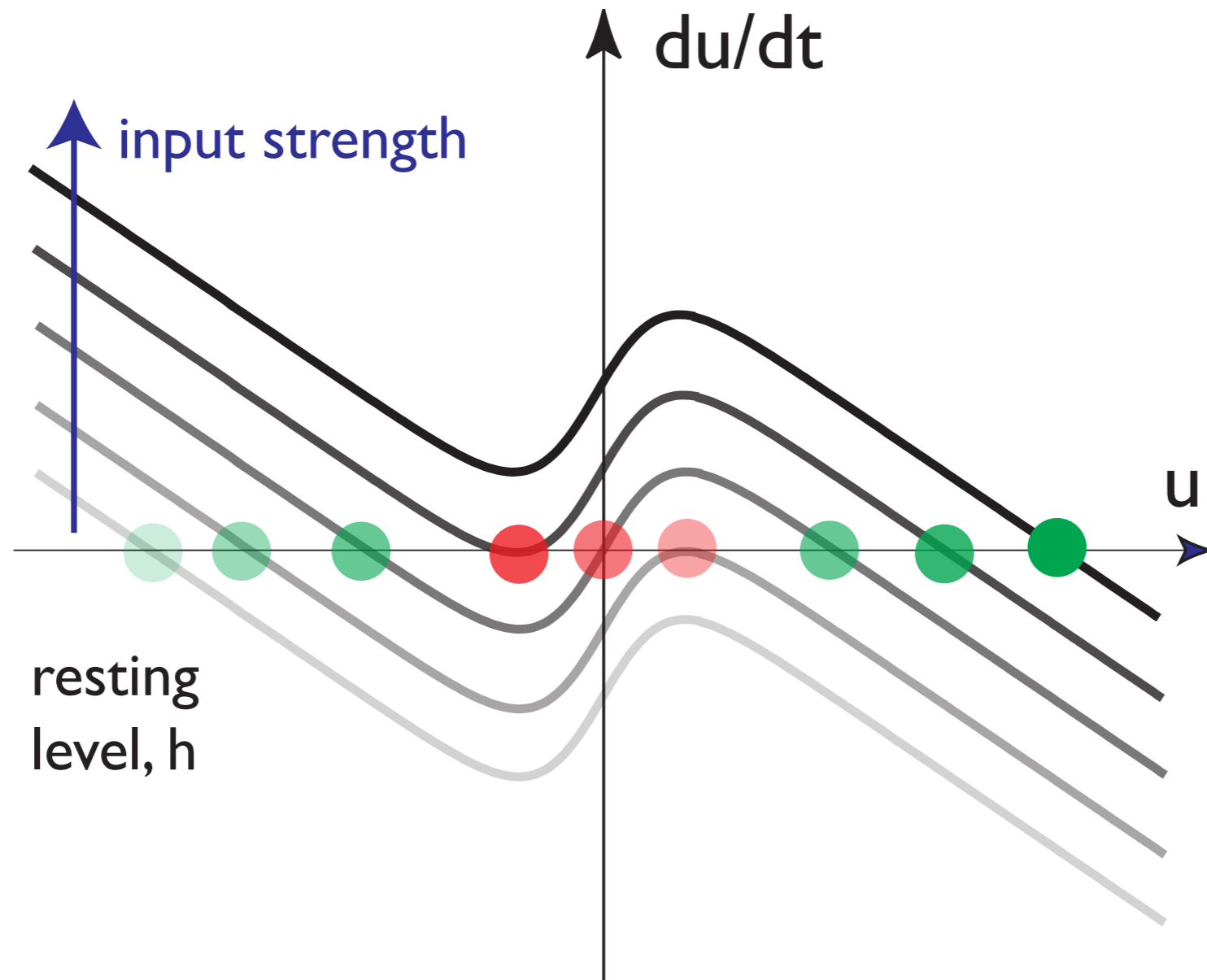
■ => this is nonlinear dynamics!



$$\tau \dot{u}(t) = -u(t) + h + S(t) + c\sigma(u(t))$$

Neuronal dynamics with self-excitation

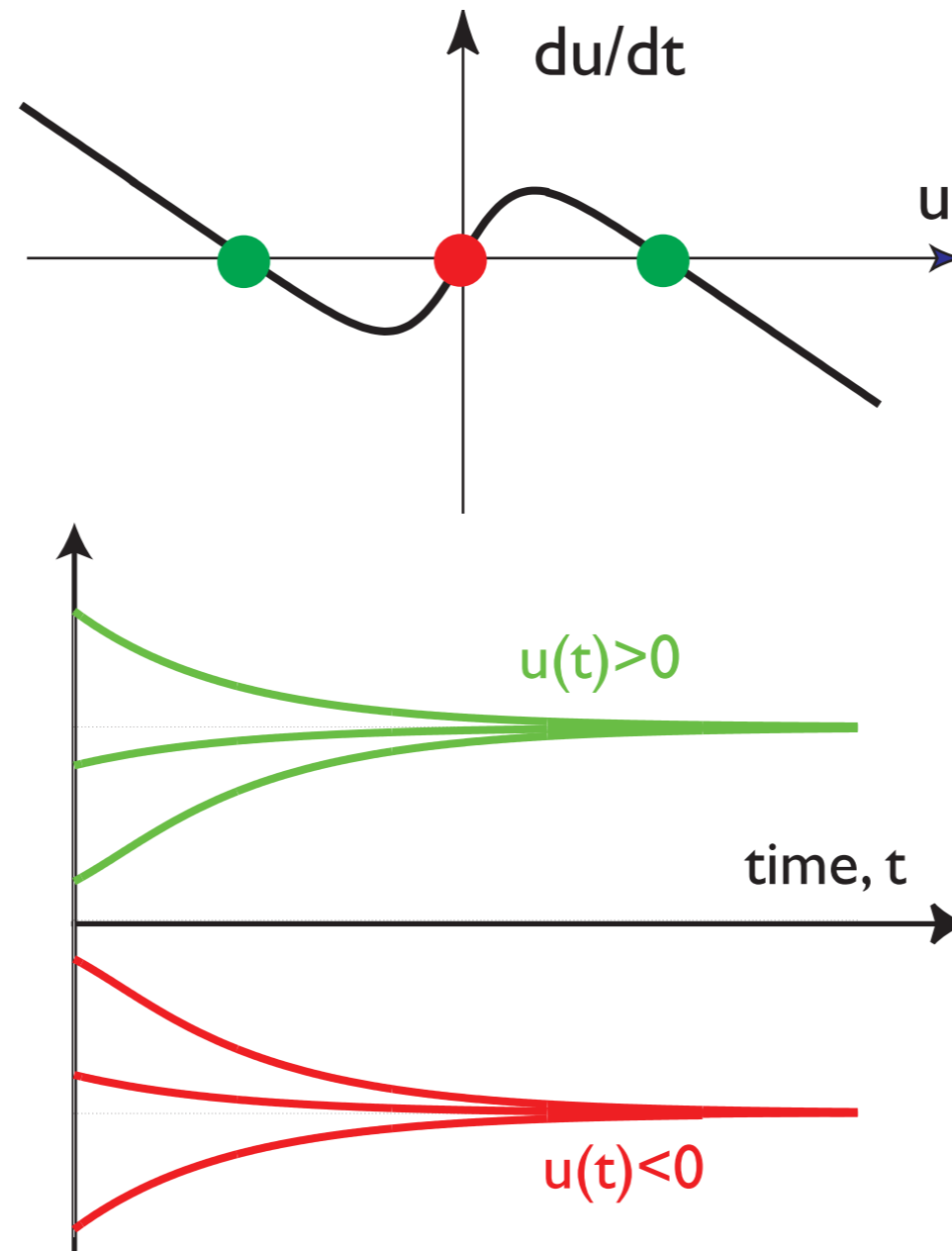
■ stimulus input



$$\tau \dot{u}(t) = -u(t) + h + S(t) + c\sigma(u(t))$$

Neuronal dynamics with self-excitation

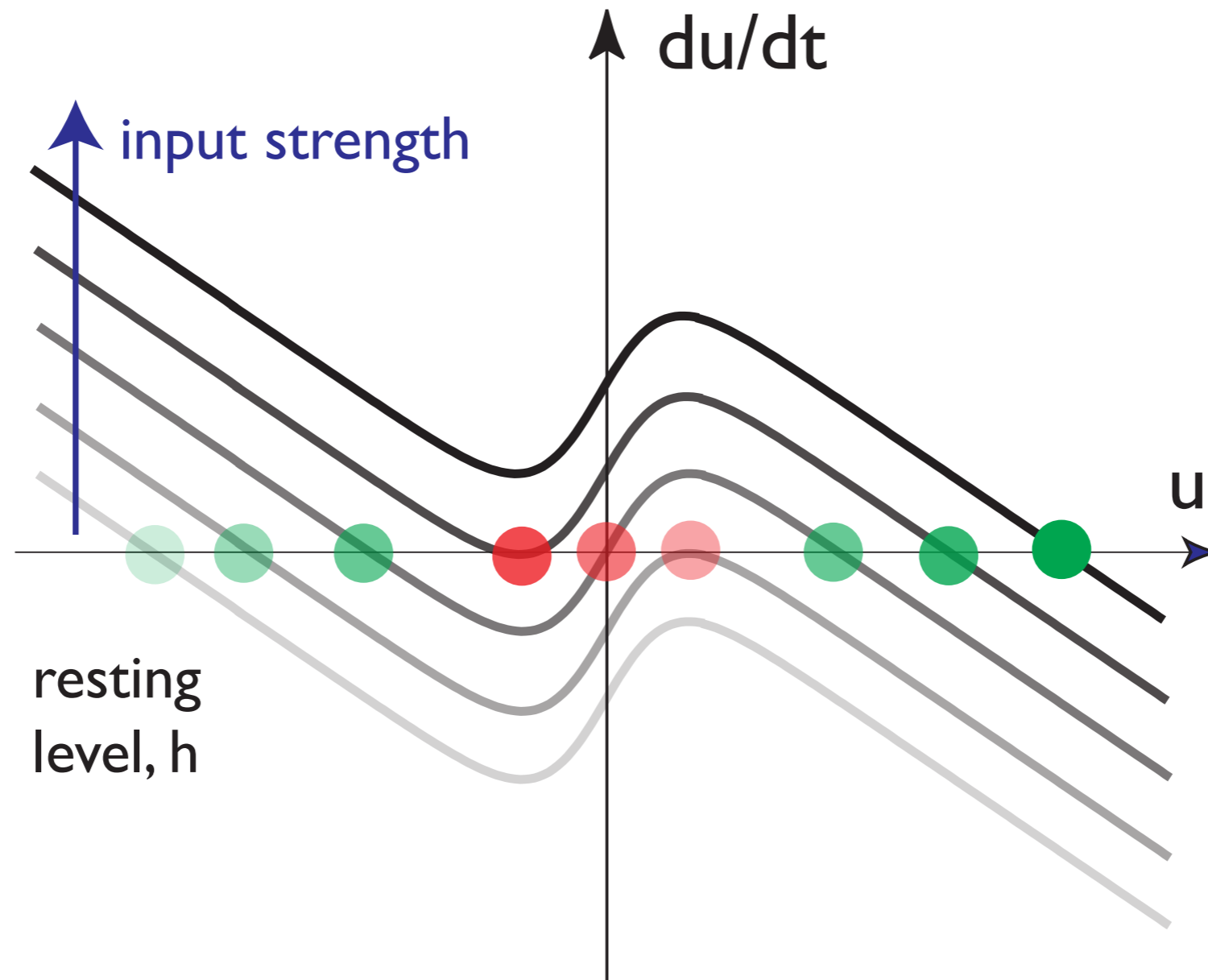
- at intermediate stimulus strength: bistable=> essential nonlinearity



$$\tau \dot{u}(t) = -u(t) + h + S(t) + c\sigma(u(t))$$

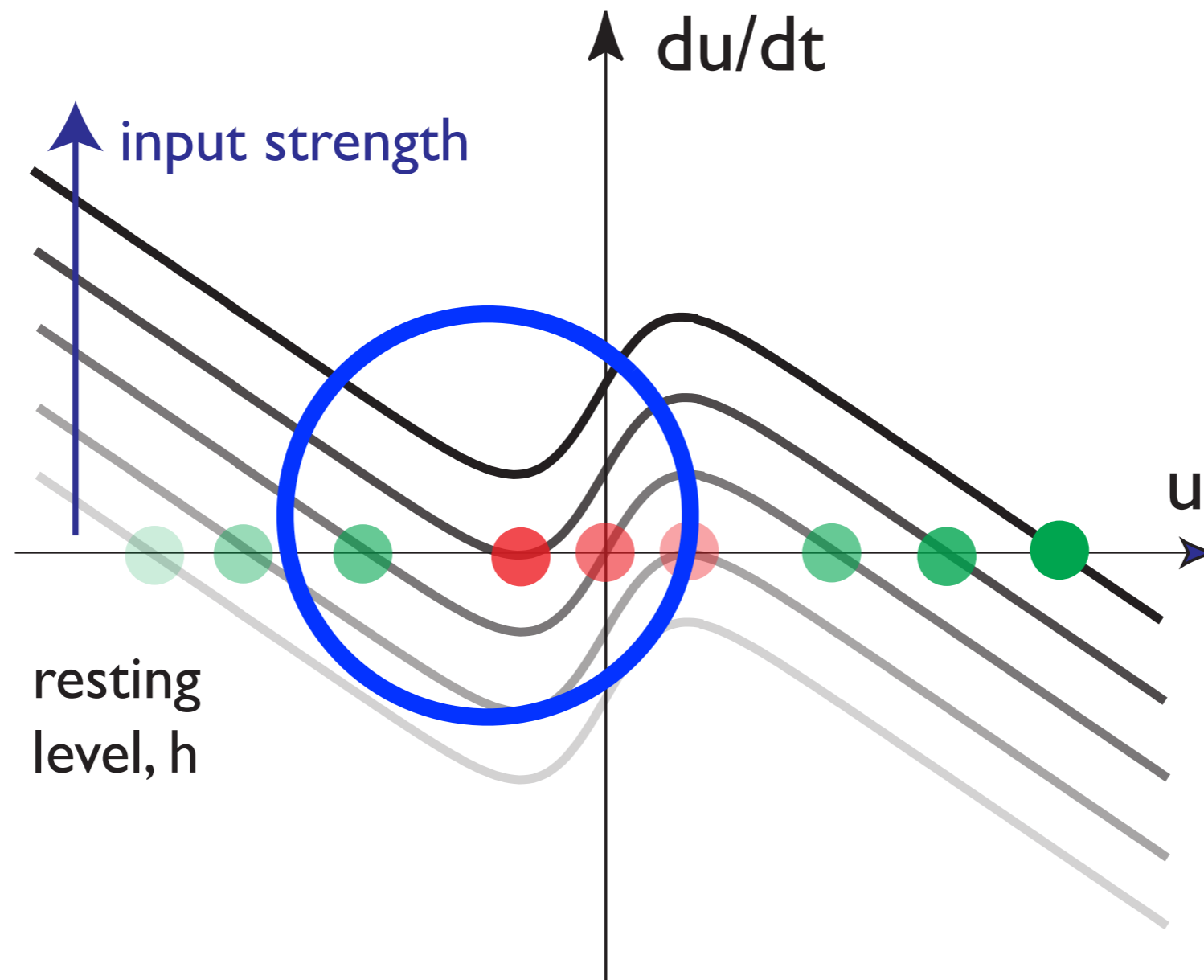
Neuronal dynamics with self-excitation

- with varying input strength system goes through two instabilities: the **detection** and the **reverse detection** instability



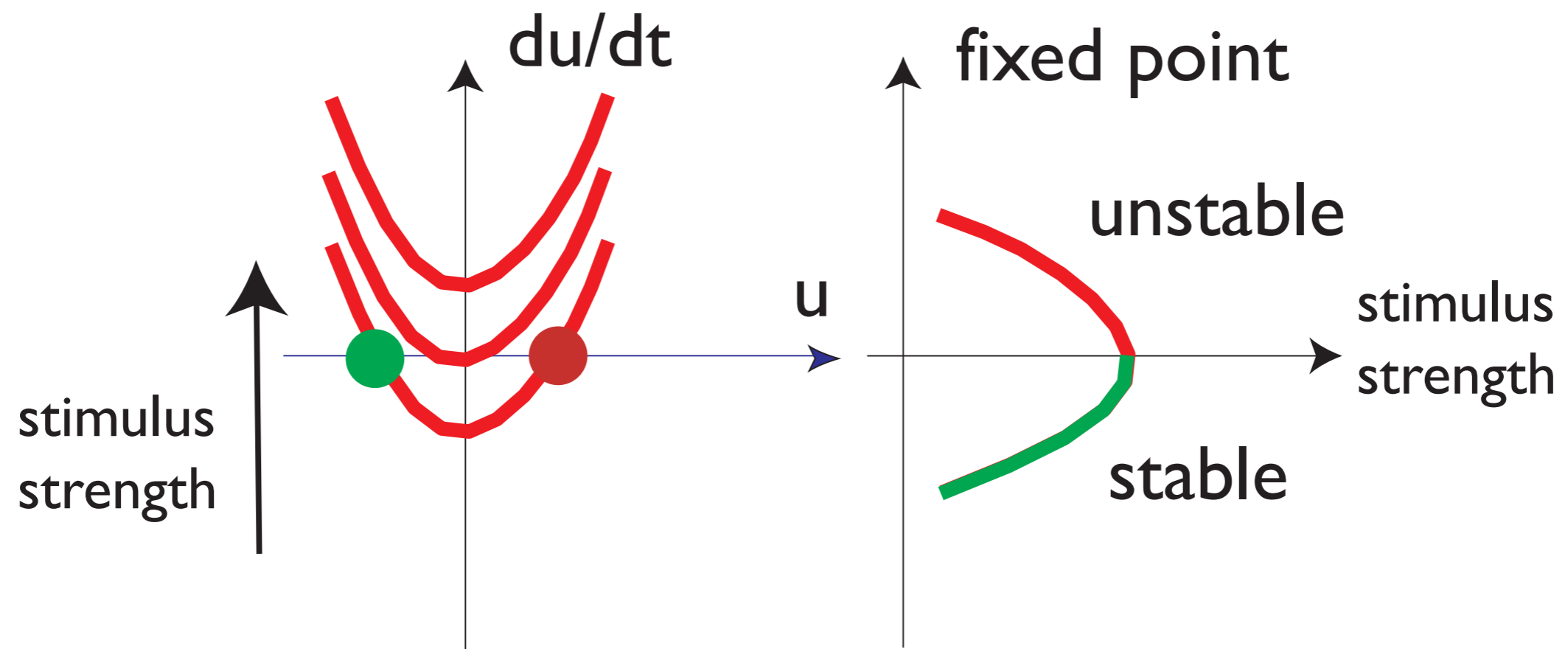
Neuronal dynamics with self-excitation

- with varying input strength system goes through two instabilities: the **detection** and the **reverse detection** instability



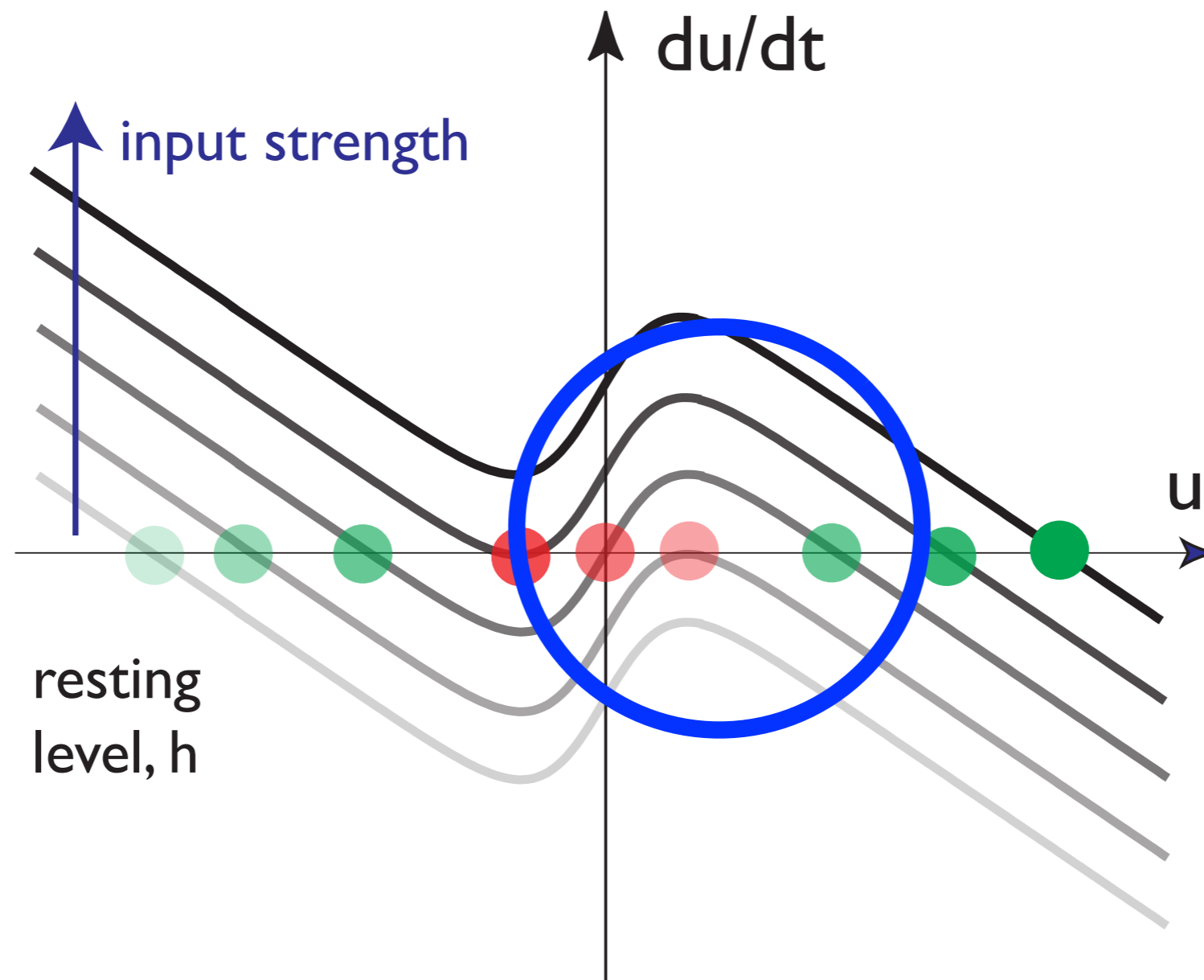
Neuronal dynamics with self-excitation

- detection instability



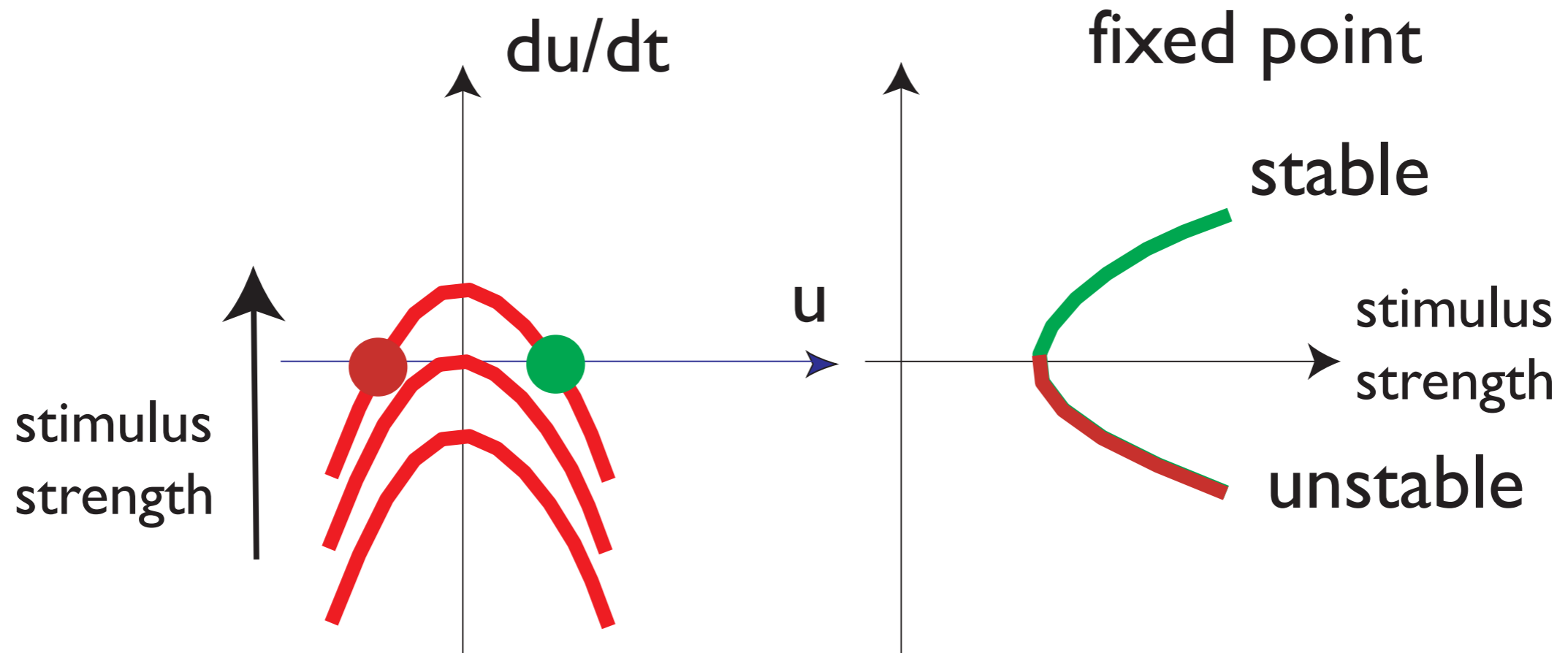
Neuronal dynamics with self-excitation

- with varying input strength system goes through two instabilities: the **detection** and the **reverse detection** instability



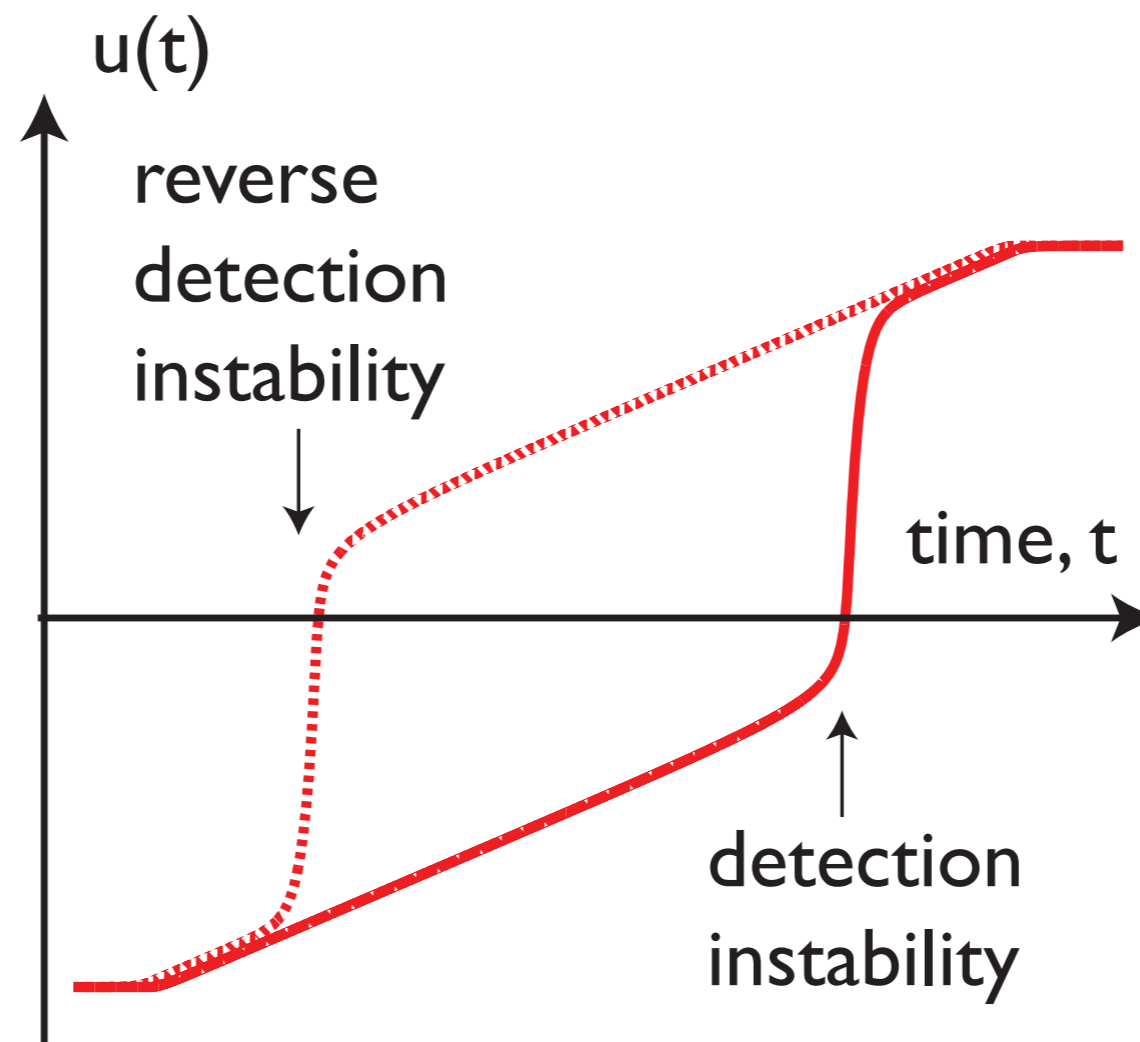
Neuronal dynamics with self-excitation

■ reverse detection instability



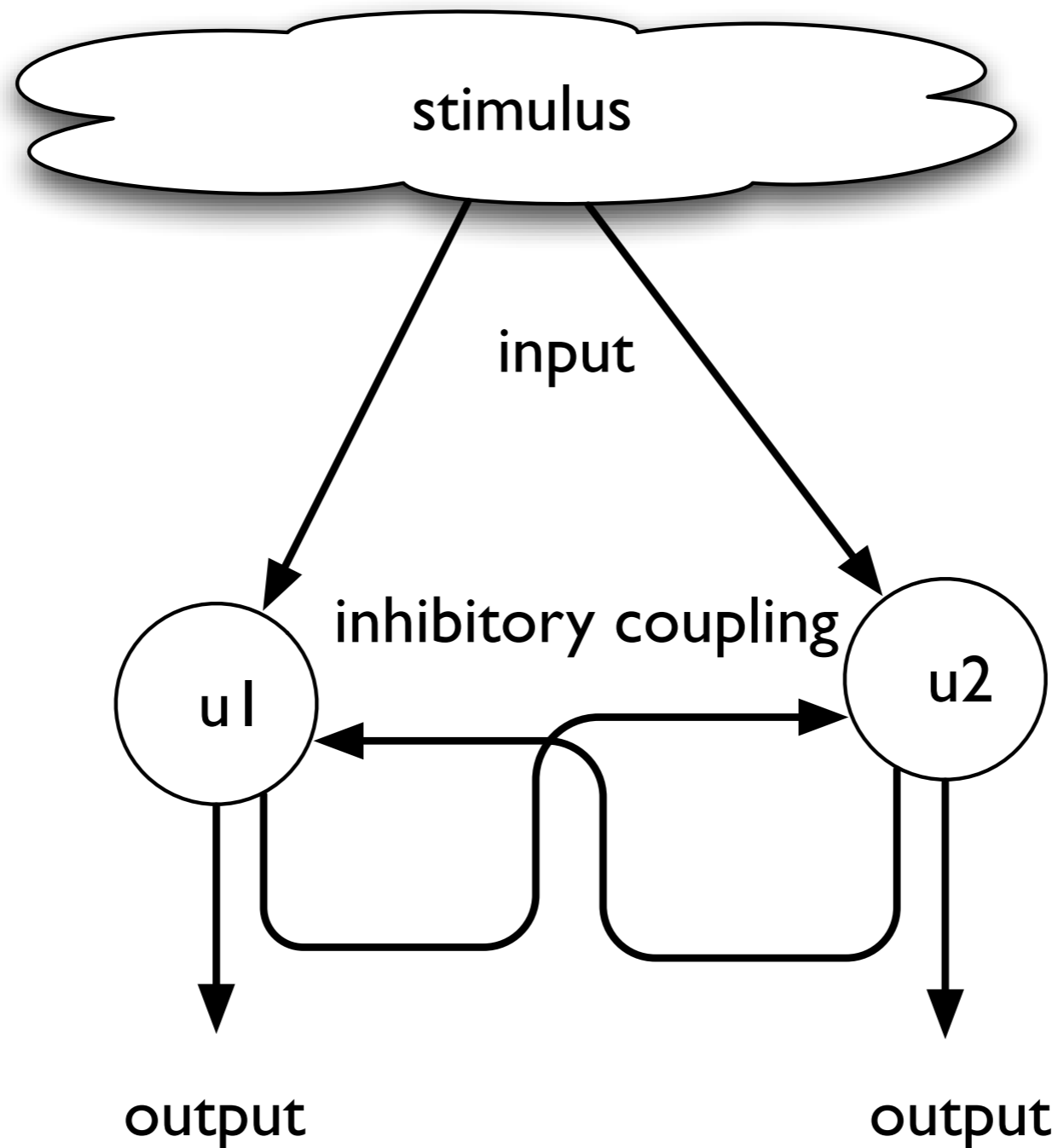
Neuronal dynamics with self-excitation

- signature of instabilities: hysteresis



 => simulation

Neuronal dynamics with competition



$$\tau \dot{u}_1(t) = -u_1(t) + h - \sigma(u_2(t)) + S_1$$

$$\tau \dot{u}_2(t) = -u_2(t) + h - \sigma(u_1(t)) + S_2$$

Neuronal dynamics with competition

■ **interaction**: the rate of change of activation at one site depends on the level of activation at the other site

■ **mutual inhibition**

$$\tau \dot{u}_1(t) = -u_1(t) + h - \sigma(u_2(t)) + S_1$$

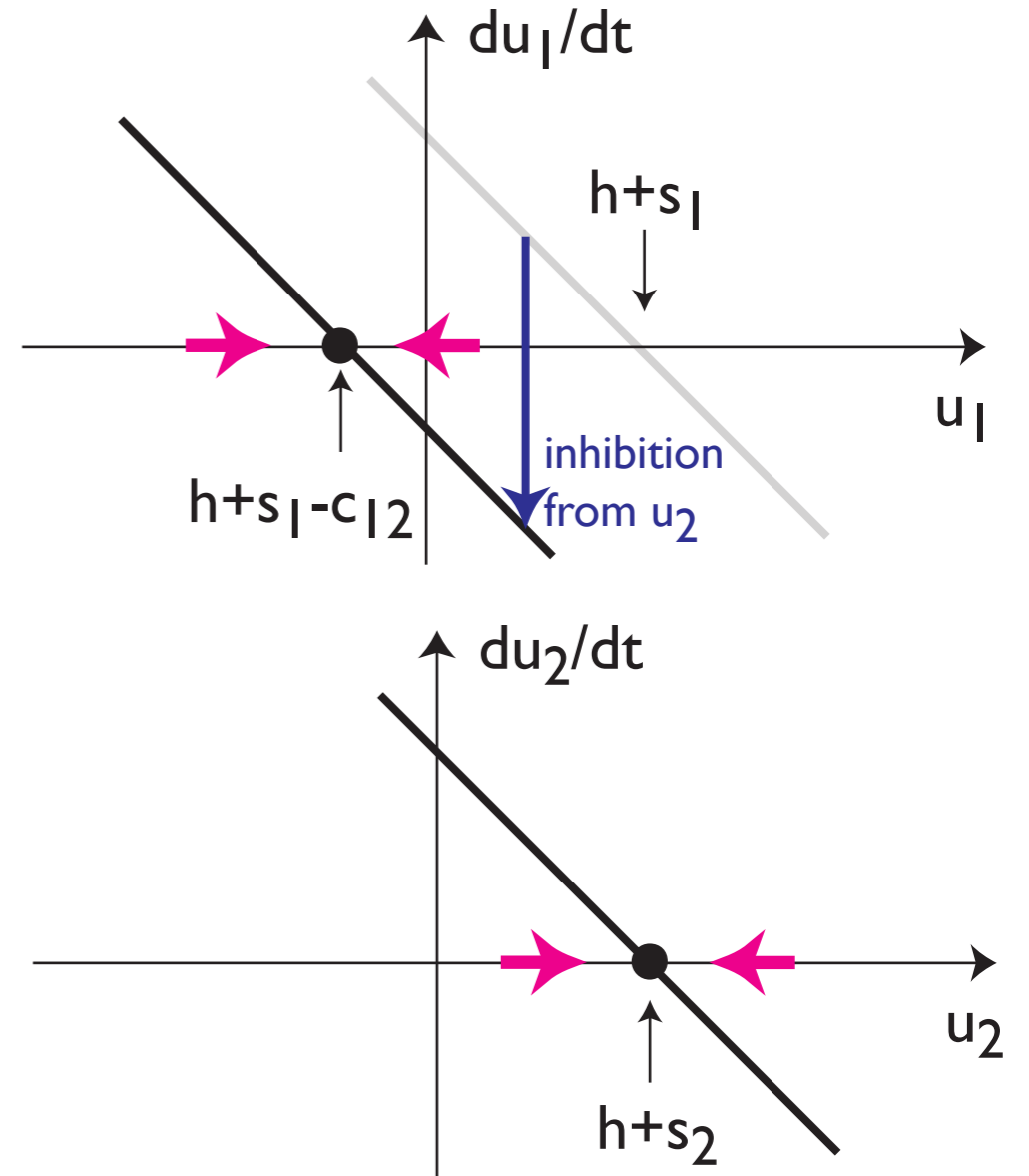
$$\tau \dot{u}_2(t) = -u_2(t) + h - \sigma(u_1(t)) + S_2$$

↑
sigmoidal nonlinearity

Neuronal dynamics with competition

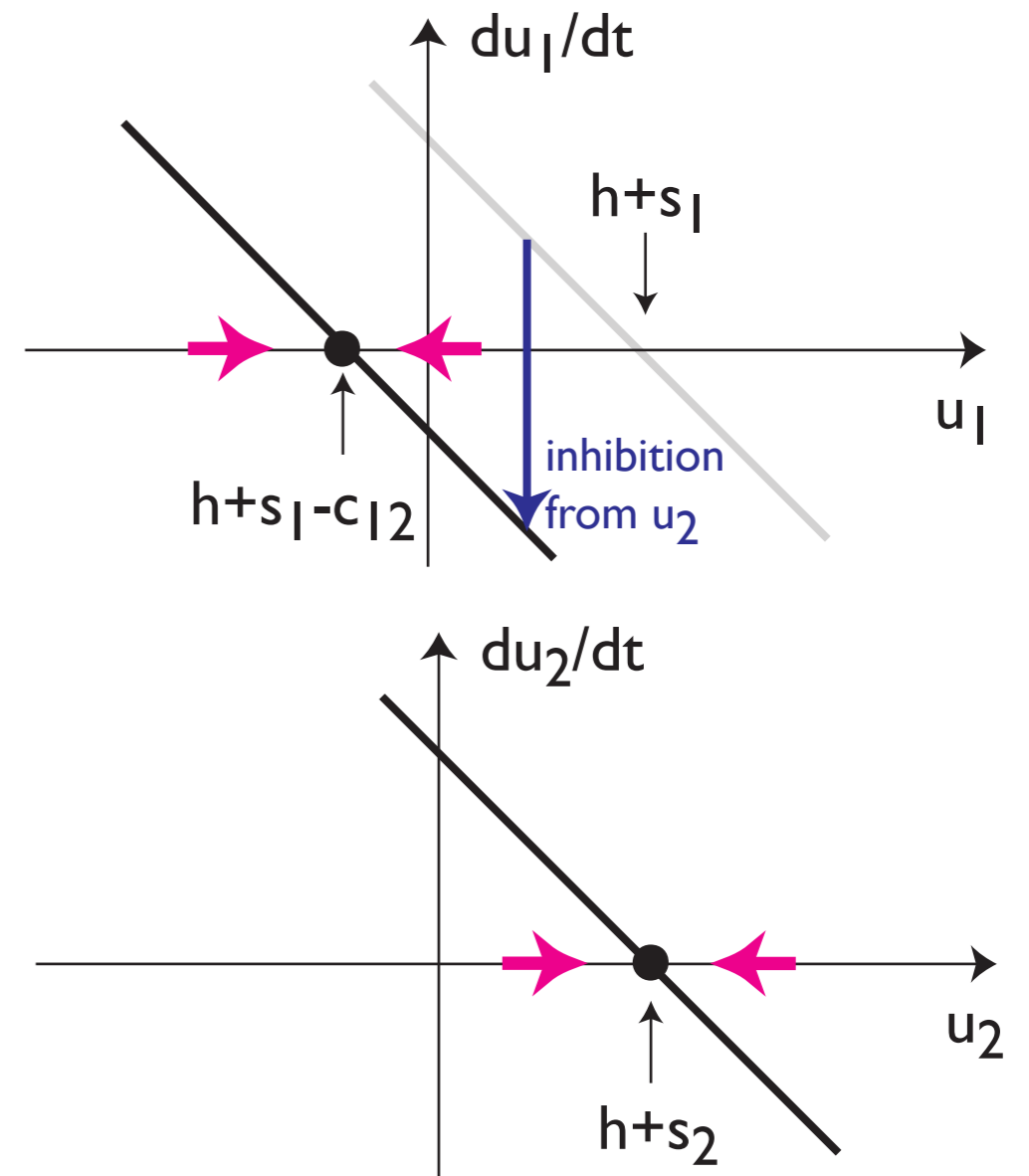
■ to visualize, assume that u_2 has been activated by input to positive level

■ \Rightarrow then u_1 is suppressed



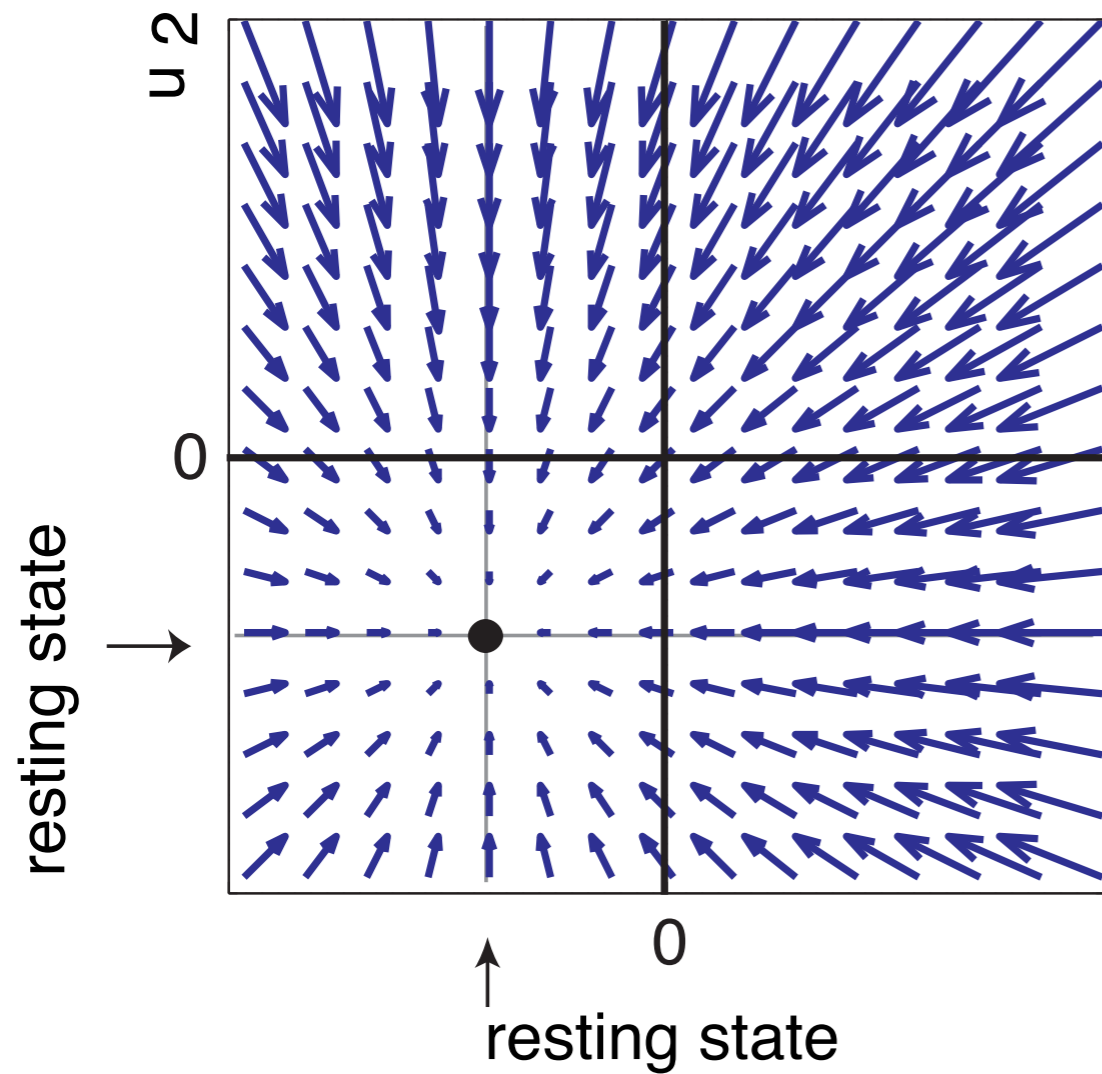
Neuronal dynamics with competition

- why would u_2 be positive before u_1 is? E.g., it grew faster than u_1 because its inputs are stronger/inputs match better
- \Rightarrow input advantage translates into time advantage which translates into competitive advantage

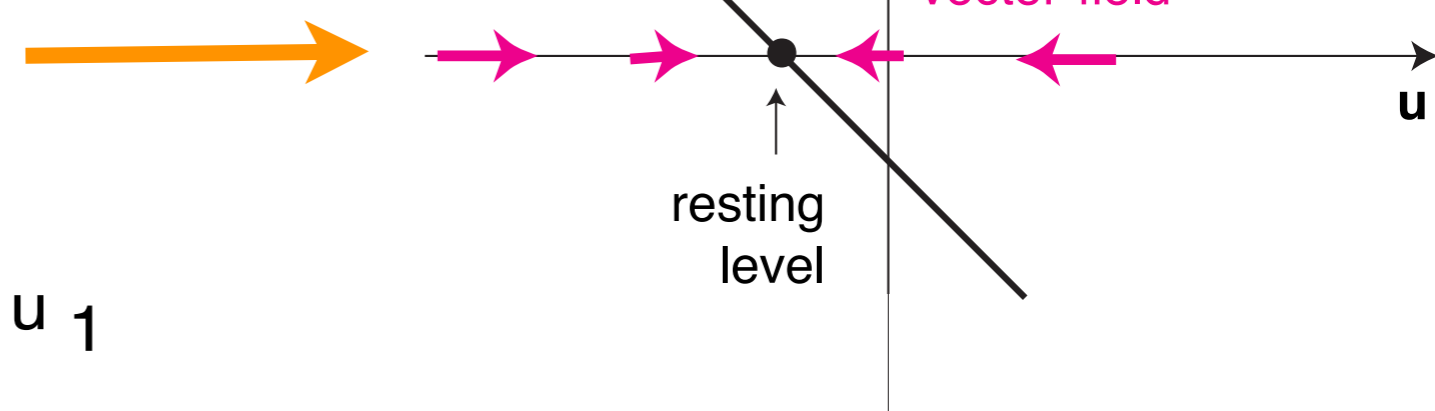


Neuronal dynamics with competition

vector-field in the
absence of input

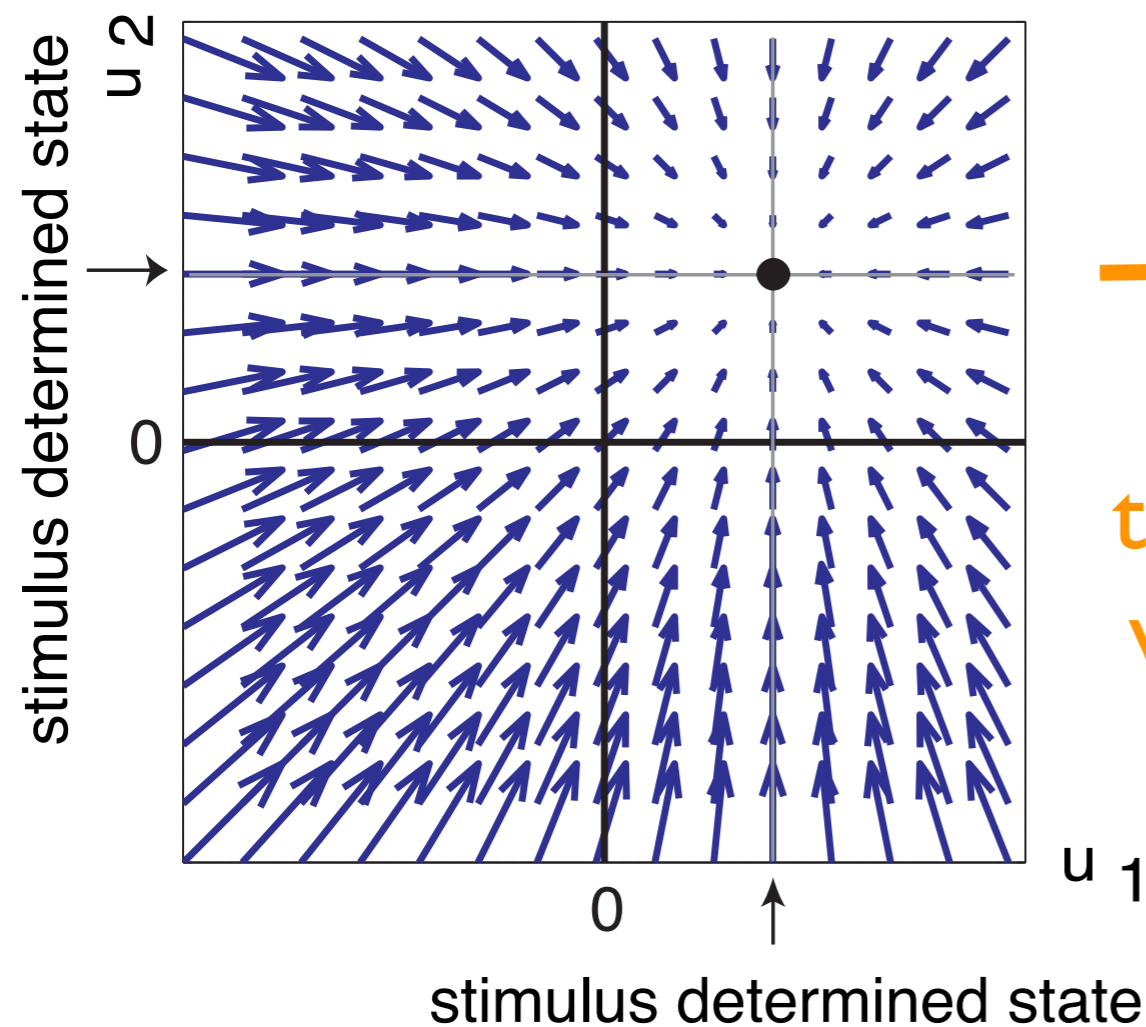


ID cut
through
vector-
field

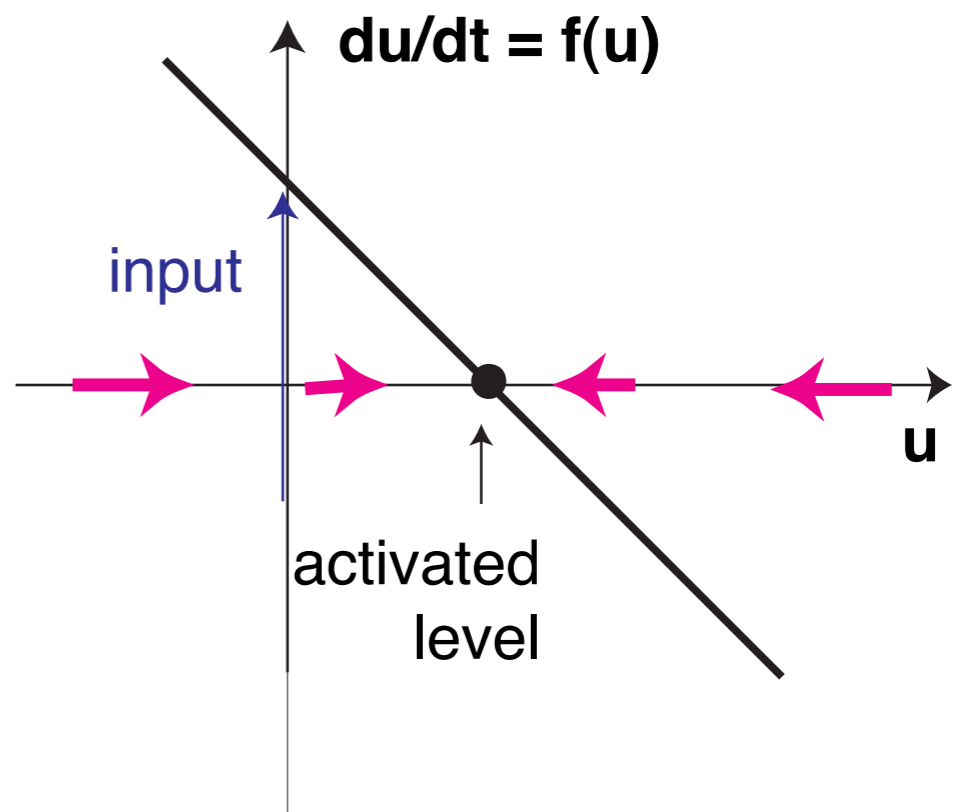


Neuronal dynamics with competition

vector-field (without interaction) when both neurons receive input



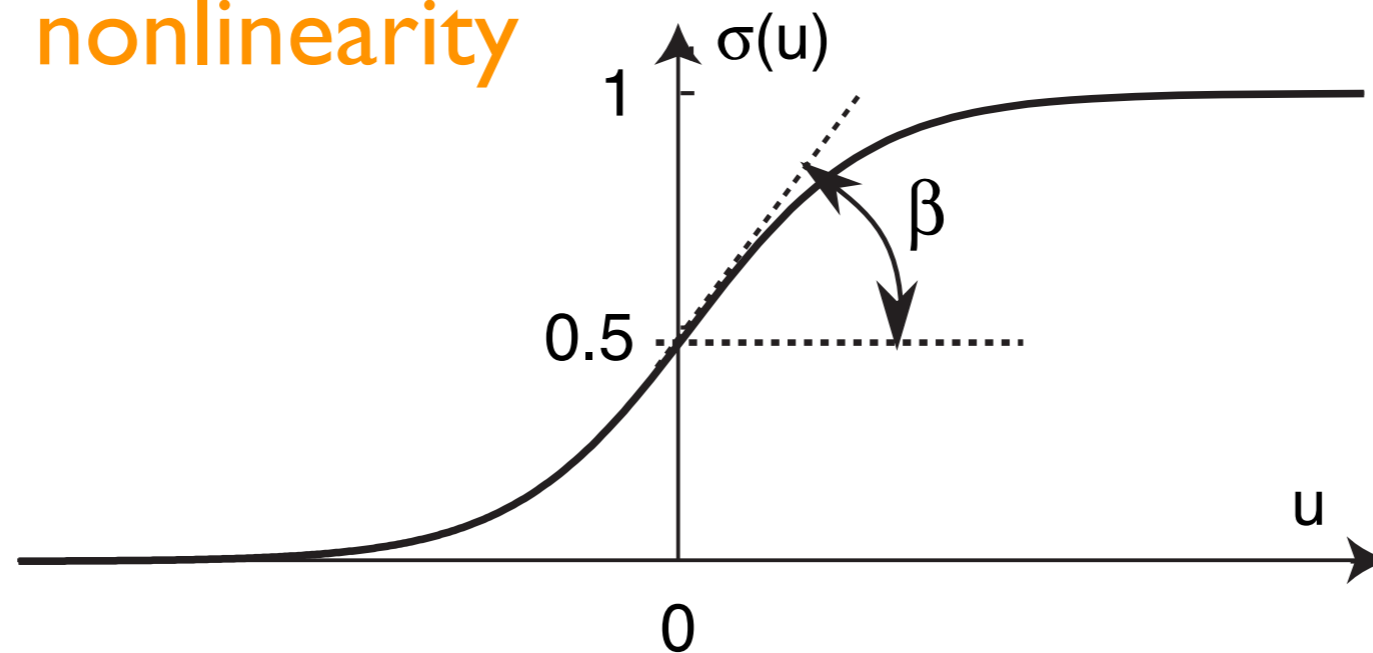
→
ID cut
through
vector-
field



Neuronal dynamics with competition

- only activated neurons participate in interaction!

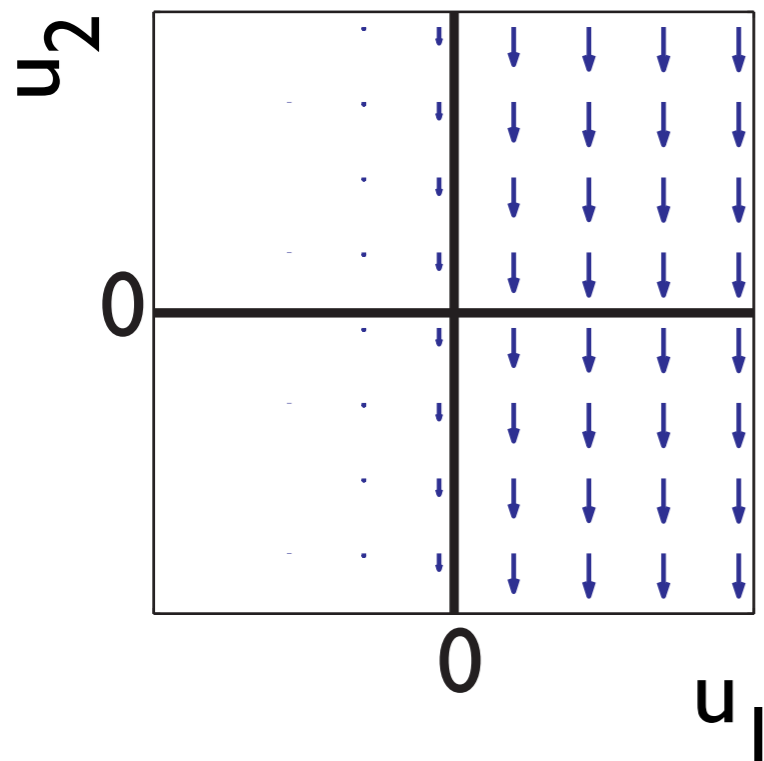
sigmoidal nonlinearity



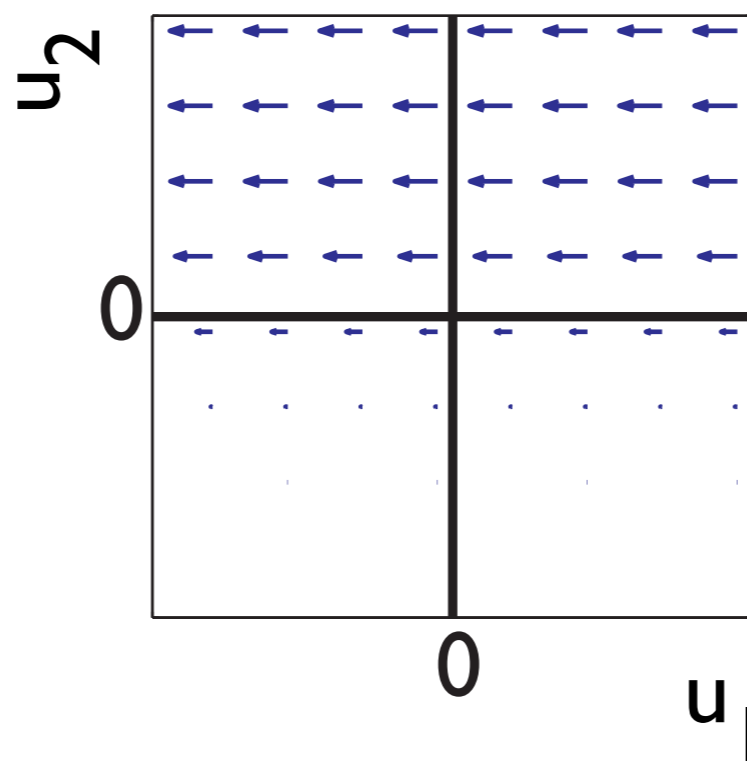
Neuronal dynamics with competition

■ vector-field of mutual inhibition

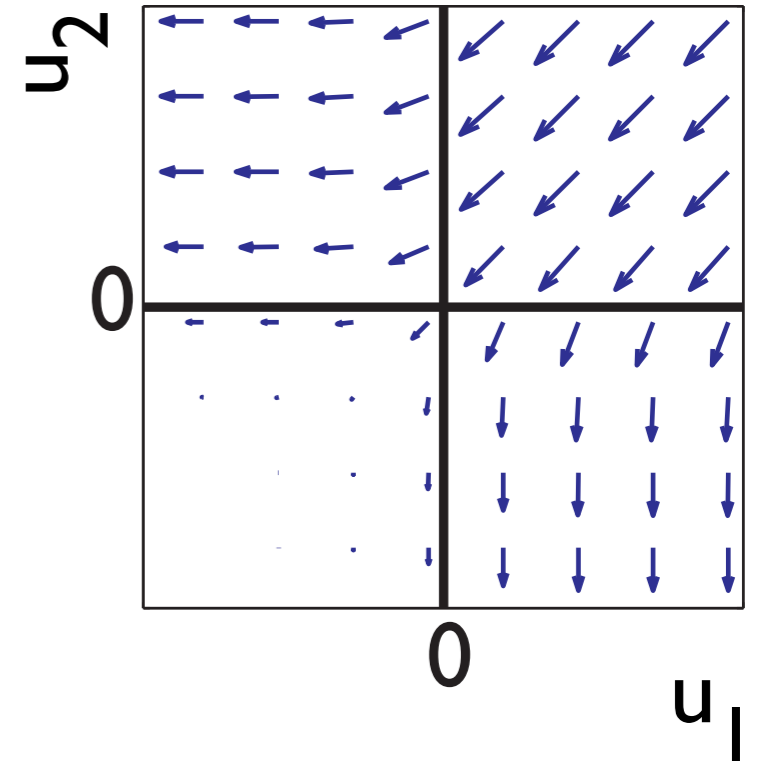
site 1 inhibits site 2



site 2 inhibits site 1



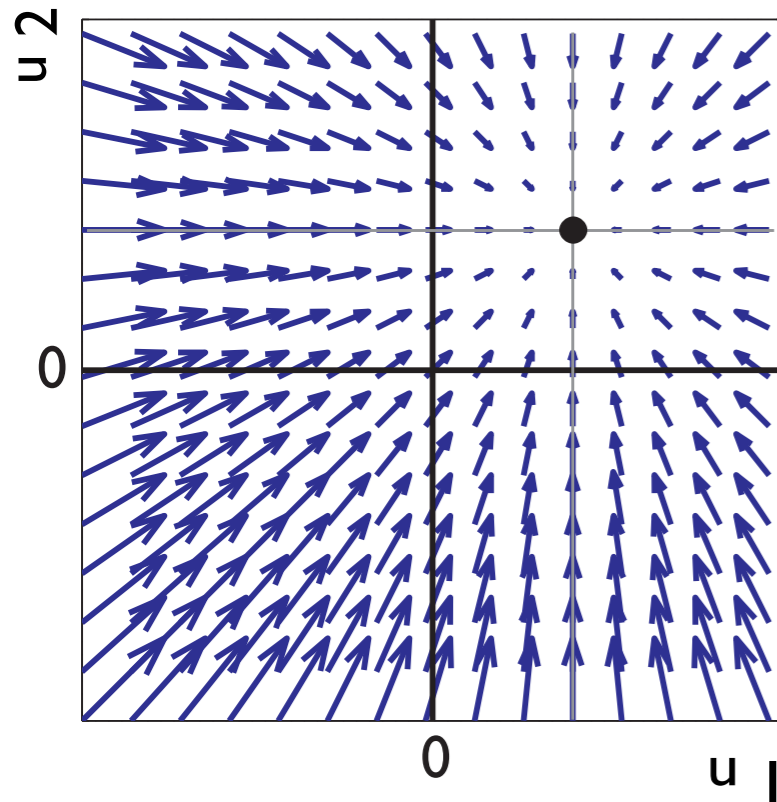
interaction combined



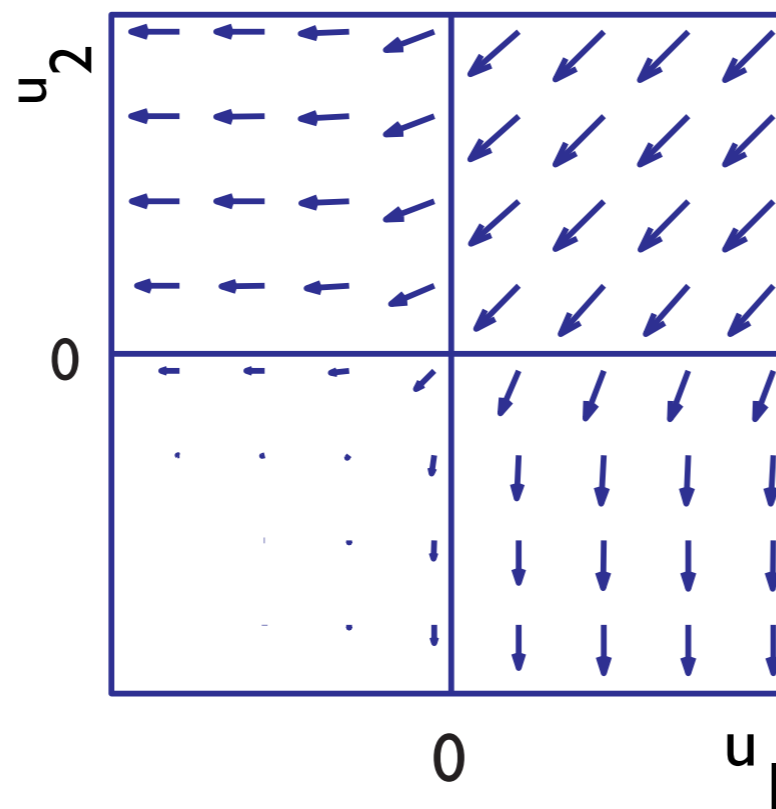
Neuronal dynamics with competition

vector-field with strong
mutual inhibition:
bistable

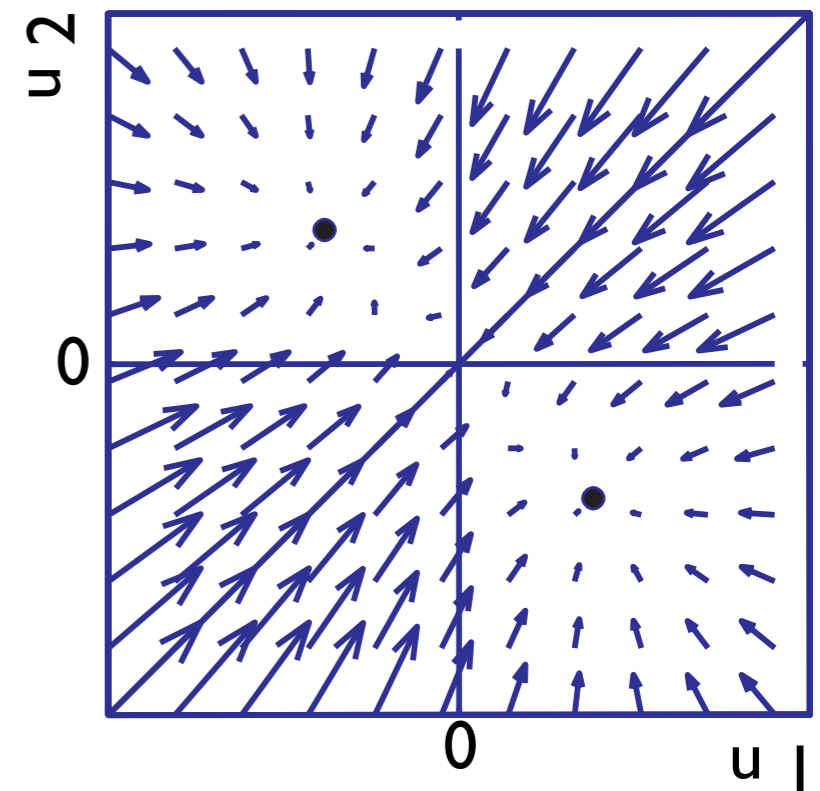
input



interaction

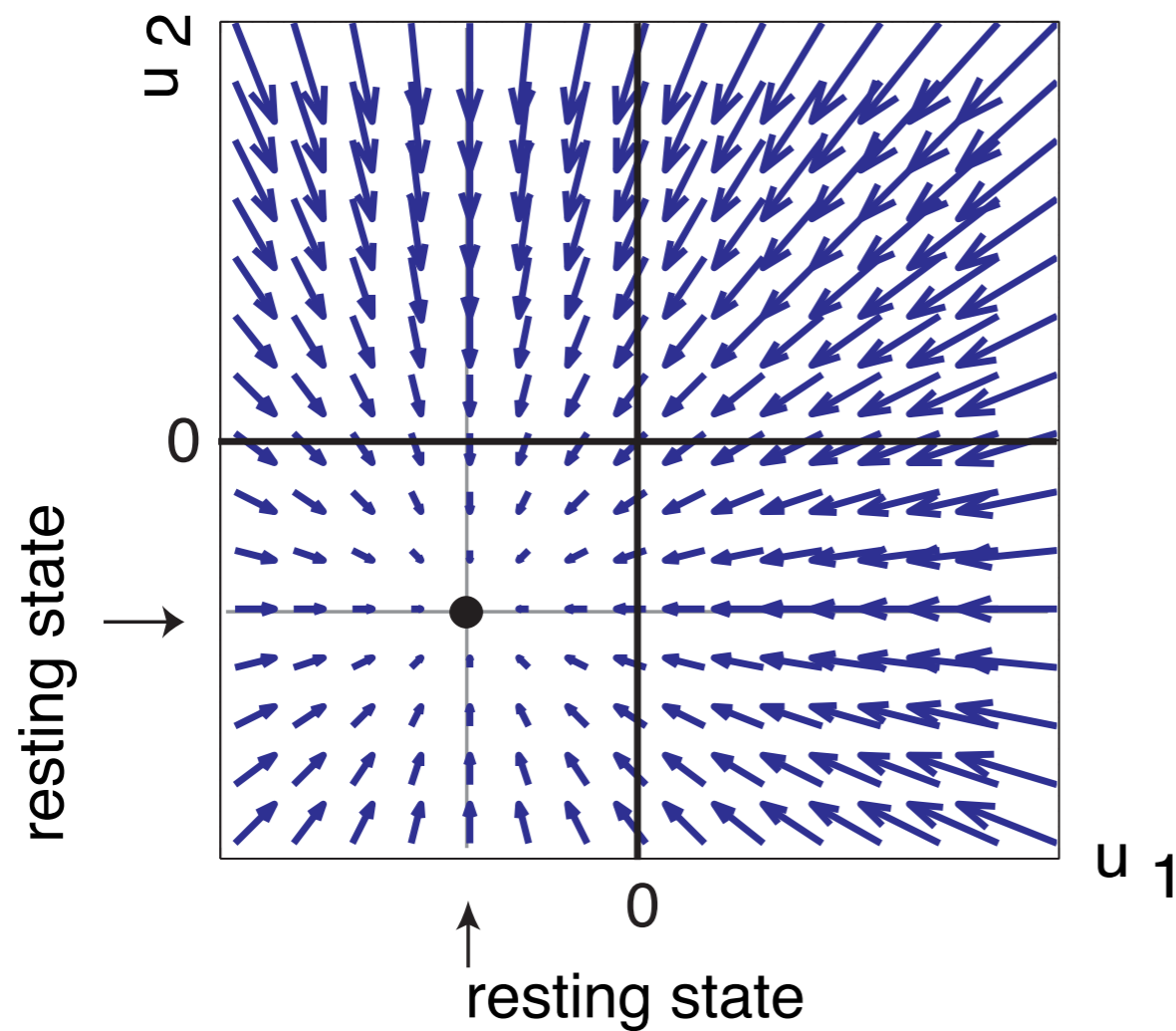


total

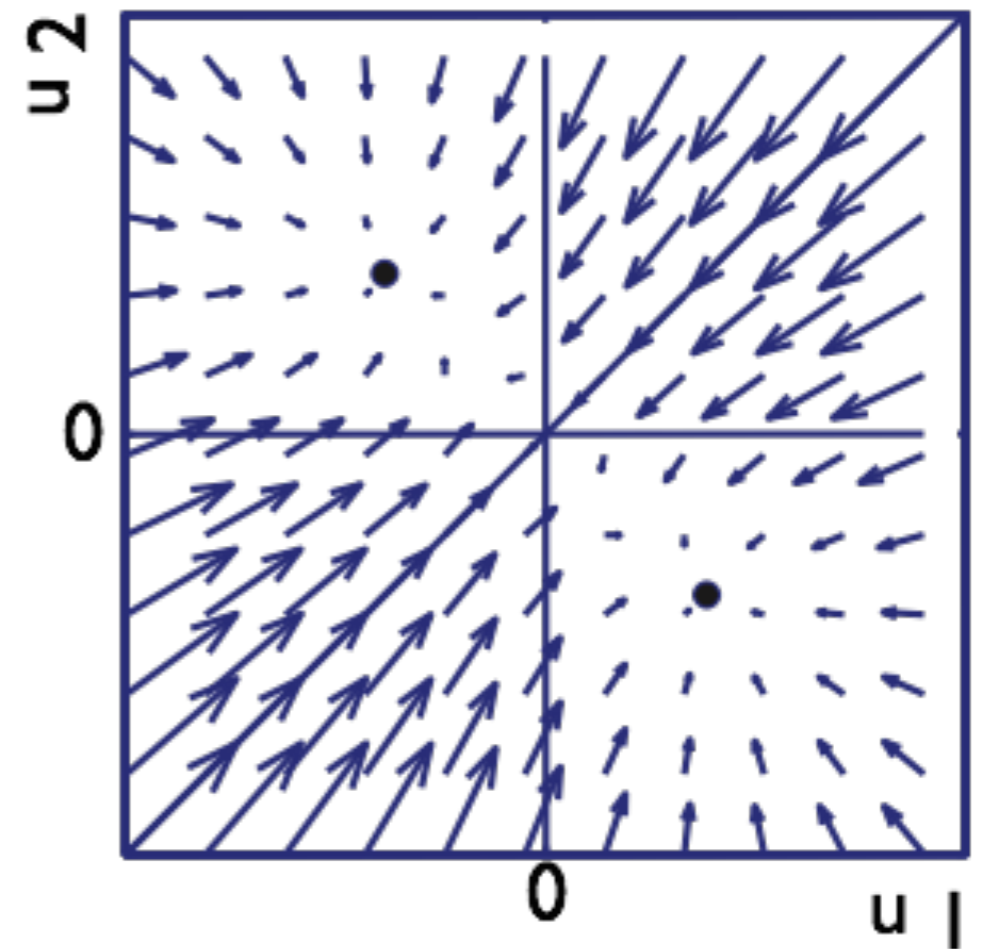


Neuronal dynamics with competition

before input is presented



after input is presented



Neuronal dynamics with competition

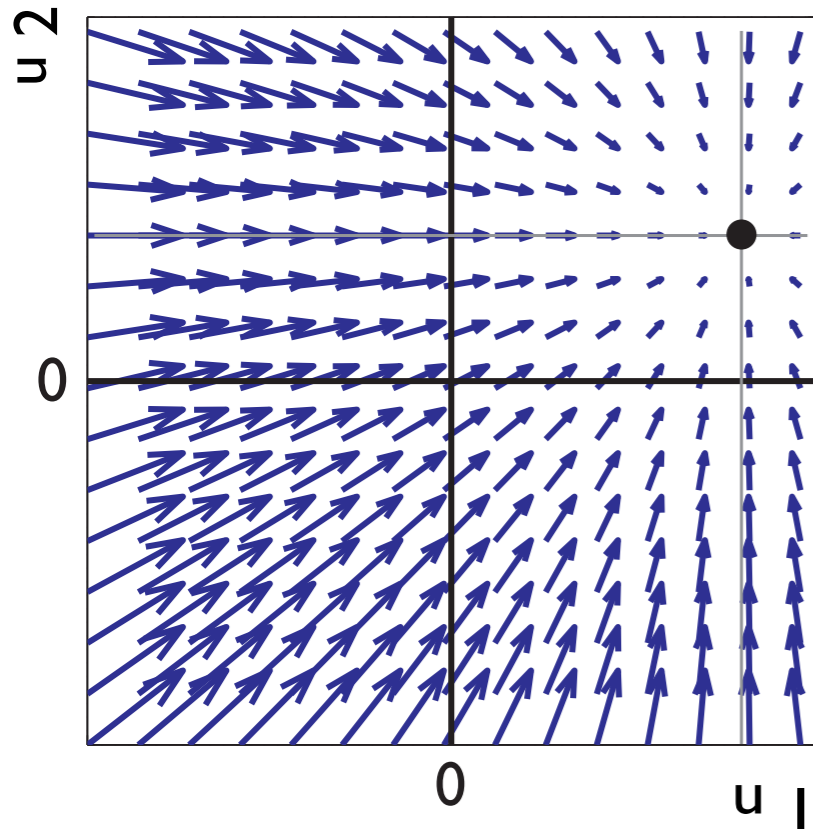
=> biased competition

stronger input to site 1:

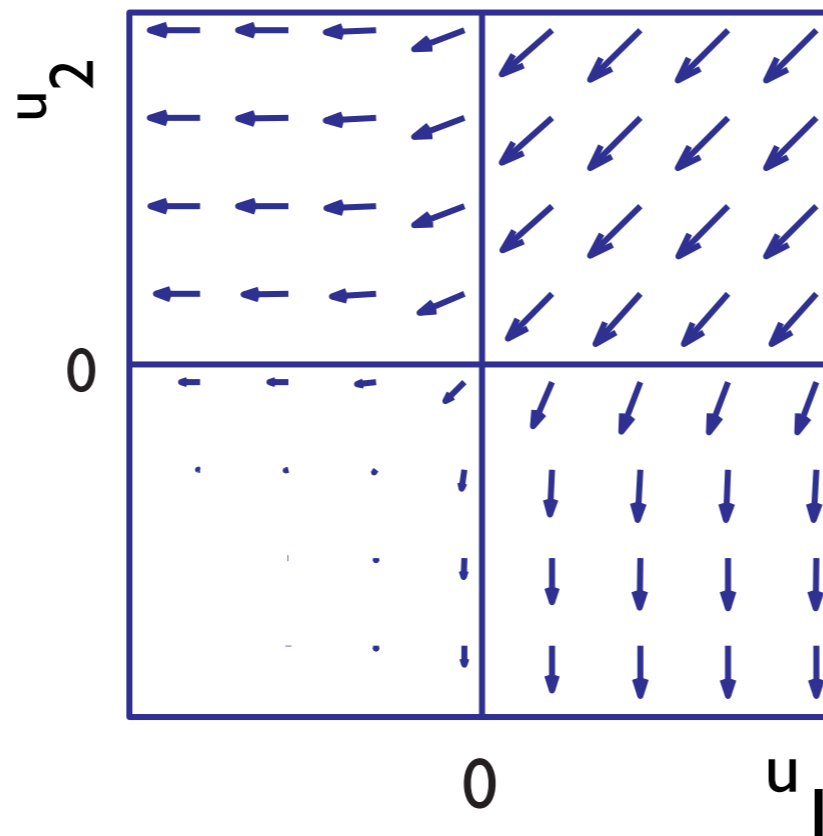
attractor with activated u_1 stronger,

attractor with activated u_2 weaker, may become unstable

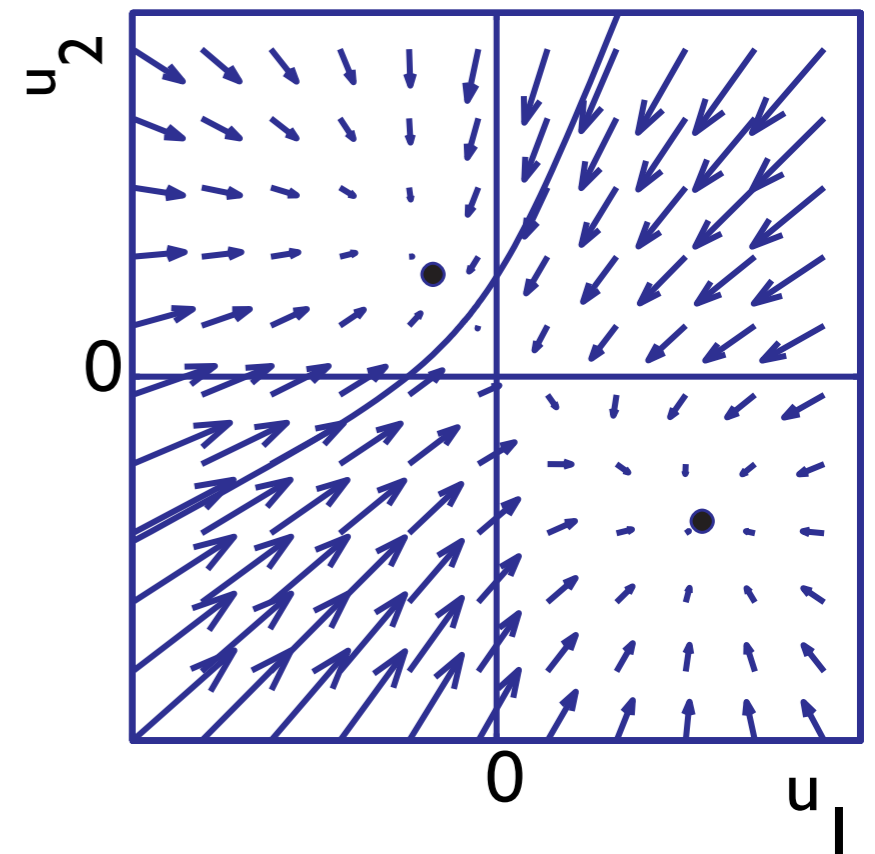
input



interaction

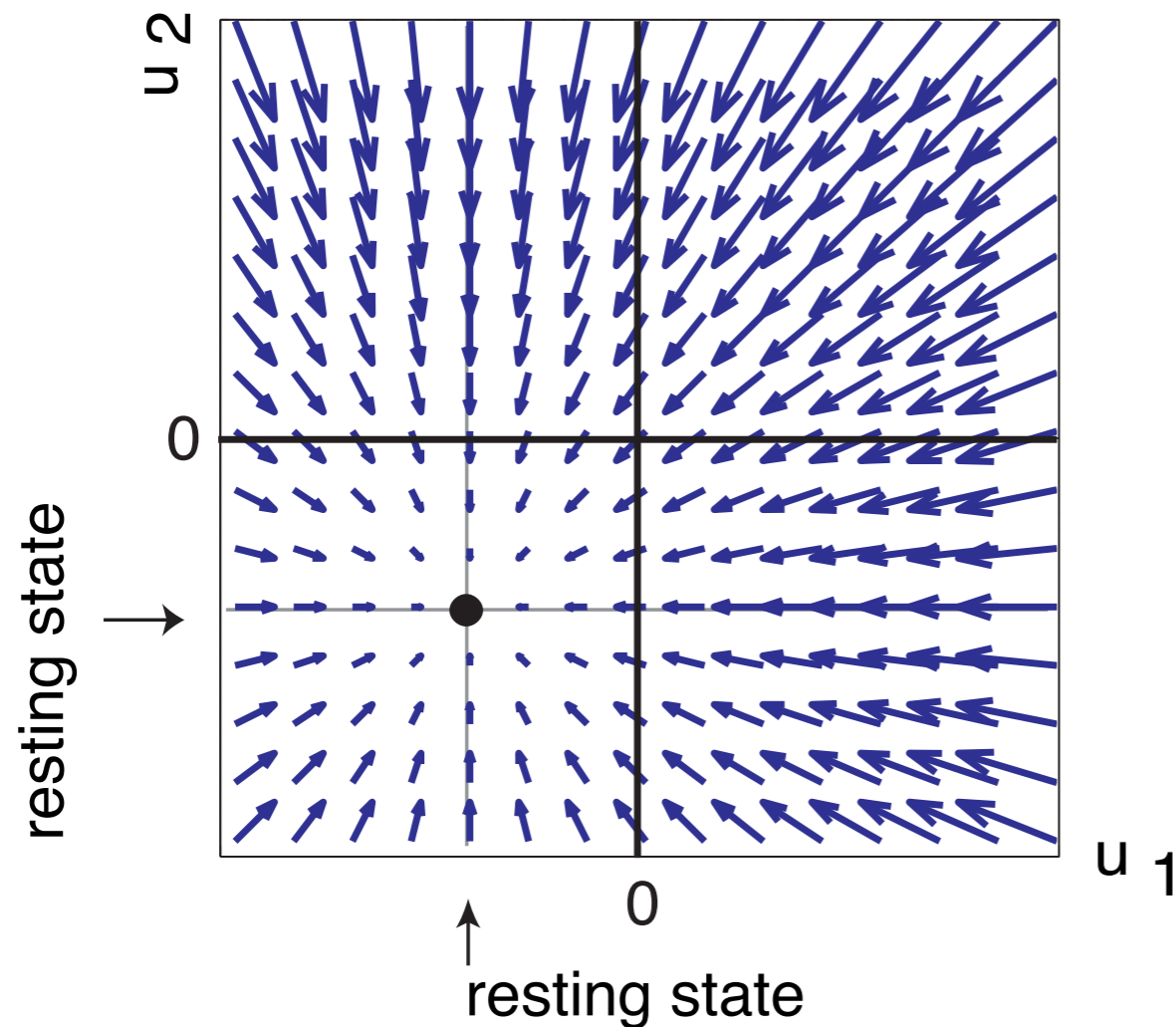


total

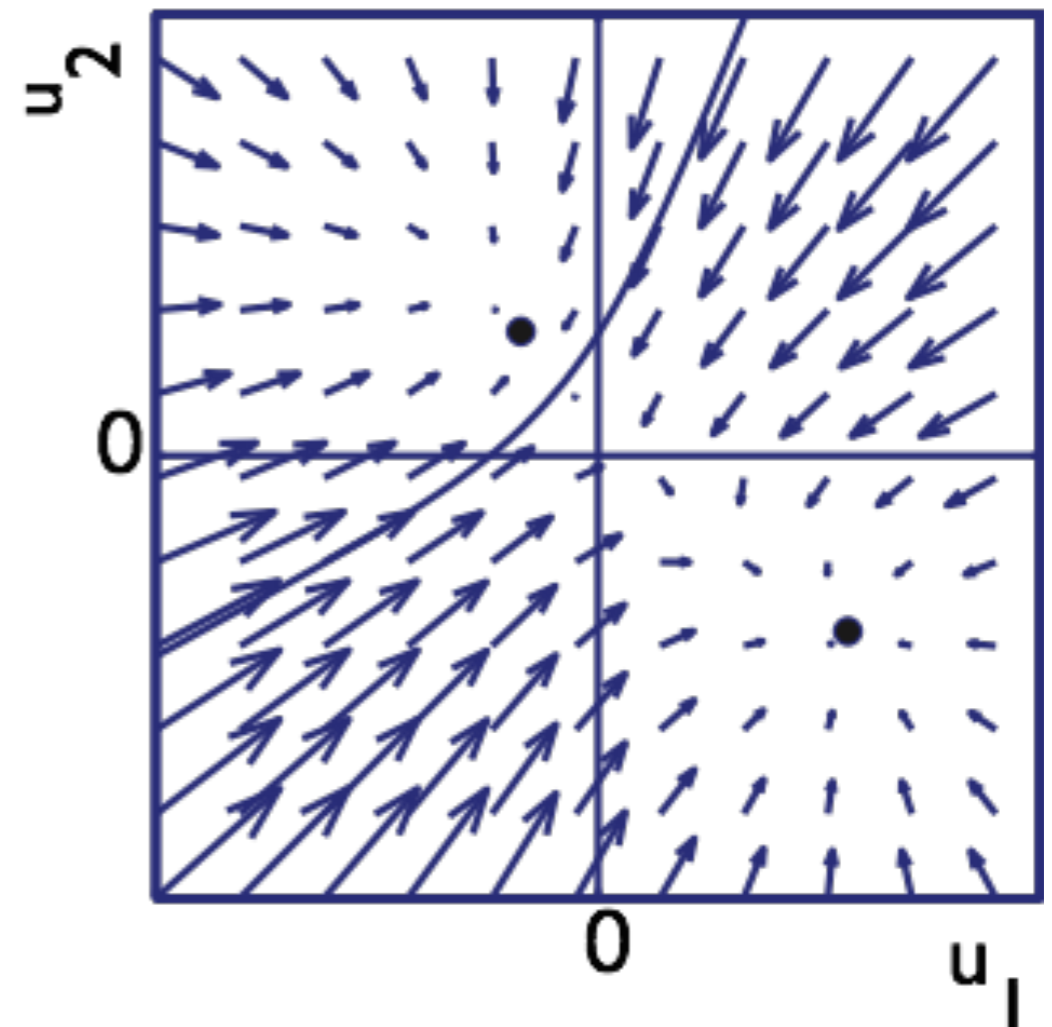


Neuronal dynamics with competition => biased competition

before input is presented



after input is presented



■ => simulation

Outlook

- Where do activation variables come from? How does an activation variable come to “stand” for a behavior or percept ?
- How do discrete activation variables reflect continuous behaviors?
- => DFT lecture