

Action Grammar for Grounding of Object-oriented Actions

Institute for Neural Computation

Sophie Aerdker

DFT Summer School 2021



Grounding of Everyday Actions







Pastra&Aloimonos: The Minimalist Grammar of Action, 2012

- O Agent
- O Action

O Coffee making, slice an apple, press button



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- O Agent
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 - O Coffee making, slice an apple, press button
- O Tool
 - $\mathsf{O}\xspace$ effector or object to perform the action $\mathsf{O}\xspace$ hand, knife



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O the action is directed at

O apple, button, speaker



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O Modifier

O scene, location, time

O car, kitchen



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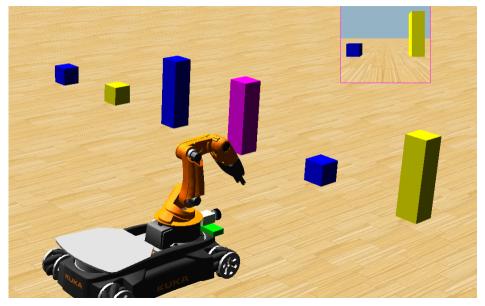
O scene, location, time

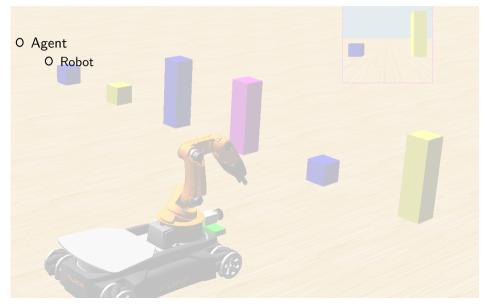
O car, kitchen

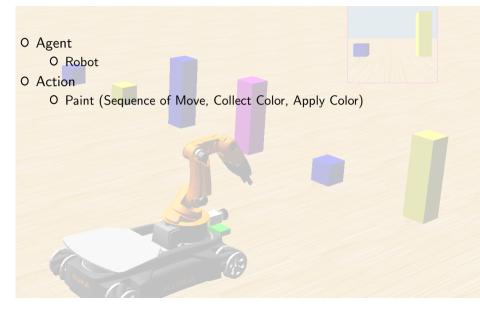
O Outcome

O change in the world

O cup of coffee, sliced apple, music playing







O Agent

O Robot

O Action

O Paint (Sequence of Move, Collect Color, Apply Color)

O Tool

O Endeffector, Collected Color

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O Outcome

O Change of Canvas Color, Coat Color collected, New Position

O Generate a sequence of actions leading to the desired state in the world

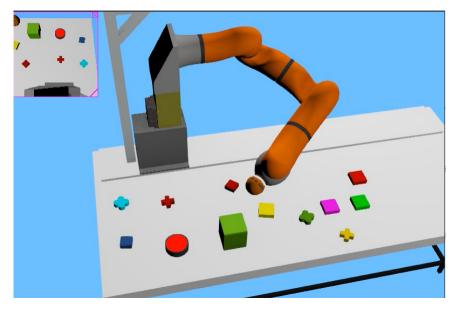
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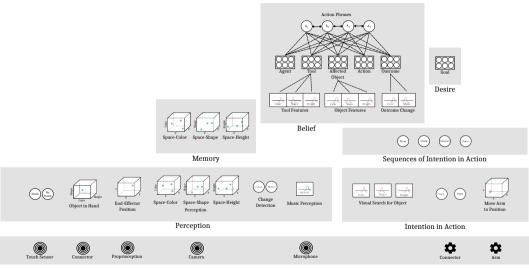
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- Structure between the intentional modes of *Belief, Memory, Perception, Desire, Prior Intention* and *Intention in Action*
- O Applicable for different actions, tools, objects in new scenes
- O Guide grounding of objects in the scene
- O Flexible when something goes wrong

Table Top Scenario

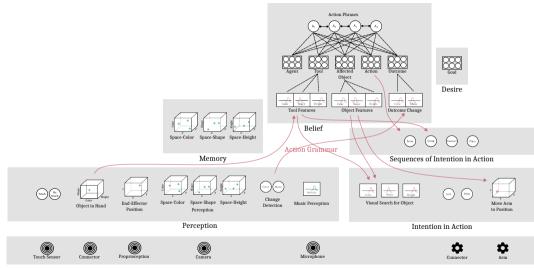


Intentional States Architecture



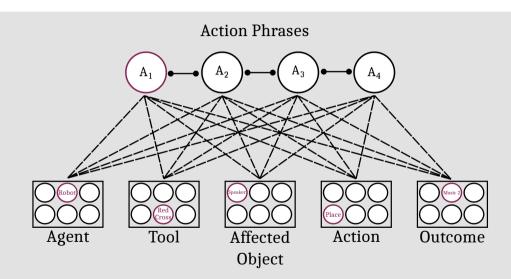
Sensor and Motor Surface

Intentional States Architecture

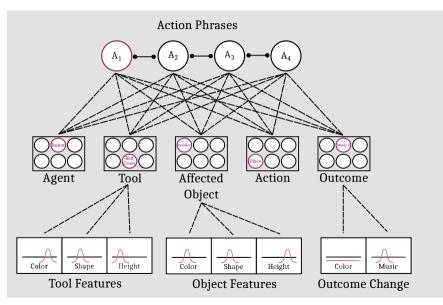


Sensor and Motor Surface

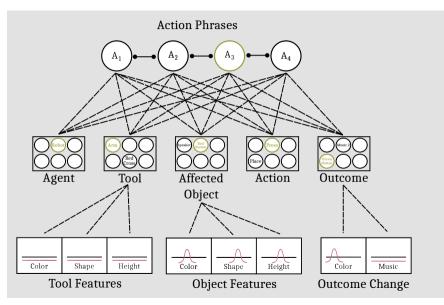
Action Phrases - Belief about Action and Expected Outcome



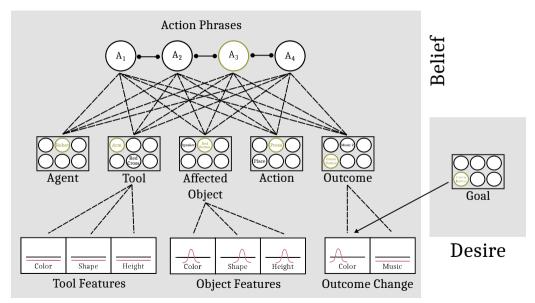
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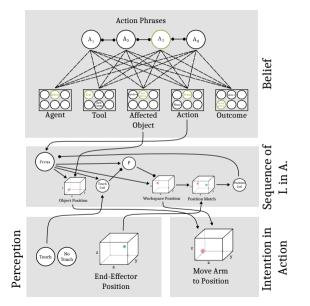
Action Phrases - Belief about Action and Expected Outcome



Activation of an Action Phrase



Prior Intention and Intention in Action



O Tool

O Tool

O Tool object "in hand"

O Tool

O Tool object "in hand" O Free "hand"

O Tool

O Tool object "in hand" O Free "hand" Affected Object

O Affected Object

0 Tool

O Tool object "in hand" O Free "hand"

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O Tool/Effector close to Affected Object

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O "Grasp tool with hand", "move to object"

Action Roles Define Preconditions

O Tool

O Tool object "in hand"

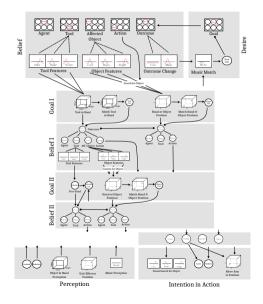
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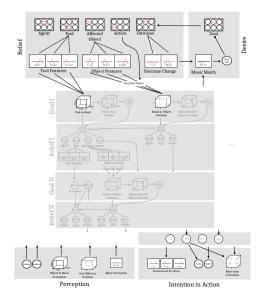
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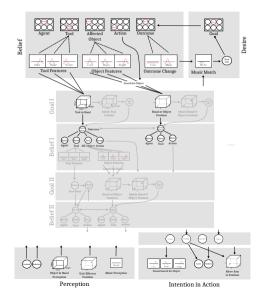
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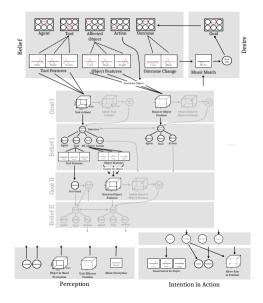
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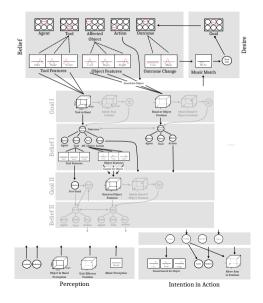
O Action tree with activated action phrase on top

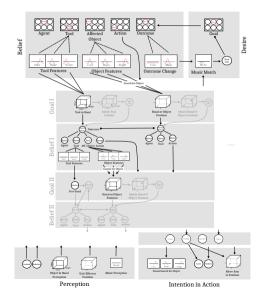


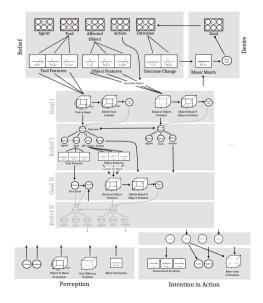


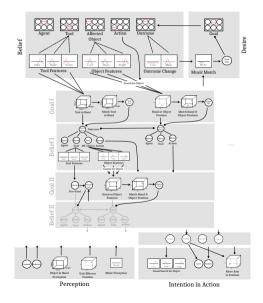












Videos



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- O Outlook: for complex action planning the action tree cannot be represented completely, use Belief structure to find new action phrase and form an action plan without forgetting previous goals

Thank you for your attention!