

RUHR-UNIVERSITÄT BOCHUM

NEURAL PROCESS MODELS OF LANGUAGE GROUNDING

Daniel Sabinasz – IK 2023



MOTIVATION

 Towards understanding the biological neural processes that give rise to the language competence



THEORETICAL STARTING POINT

- The language competence is "grounded" in perceptual-motor processes (Barsalou, 1999, 2008)
 - Makes use of these processes
 - Evolved "on top of" these processes



RESEARCH PROGRAM

 Build models of how the language competence may emerge from the neural principles postulated in DFT



RESEARCH PROGRAM

- Build models of how the language competence may emerge from the neural principles postulated in DFT
- ... possibly using and extending the same neural architectures as more primitive sensorymotor processes
 - Neural fields with their instabilities (detection, selection, short-term memory)
 - Visual search
 - Categorization
 - Coordinate transformations



PERCEPTUAL GROUNDING

Language understanding requires associating language with perceptual representations



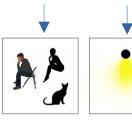
PERCEPTUAL GROUNDING

Language understanding requires associating language with perceptual representations

the black swan that sits below a tree















Towards a neural process model that perceptually grounds language



Modeling the perceptual grounding of language in general is an ambitious project



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 - Many words refer to abstract concepts
 - Not clear how those could be characterized perceptually



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 - There is a wide range of grammatical constructions that can be combined in a wide number of ways

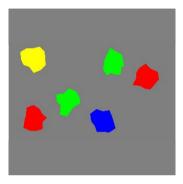


- Modeling the perceptual grounding of language in general is an ambitious project
 - Many words refer to abstract concepts
 - Not clear how those could be characterized perceptually
 - There is a wide range of grammatical constructions that can be combined in a wide number of ways
- Need to approach this in small steps



DFT MODELS OF LANGUAGE GROUNDING

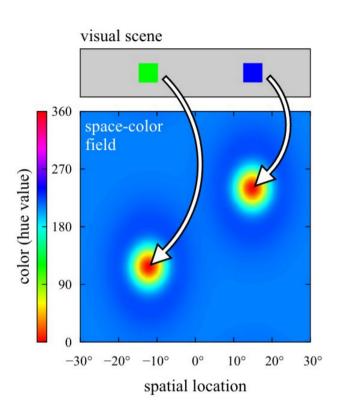
- Today: Simple visuo-spatial language grounding
 - e.g., "the red to the right of the green"
 - Lipinski et al. (2012), Richter et al. (2014)
- Outlook:
 - Movement relations
 - e.g., "the red that moves towards the green"
 - Richter, Lins, & Schöner (2021)
 - Compositional visuo-spatial language grounding
 - e.g., "the red ball that moves towards the big tree, which is to the left of the lake and to the right of the house"
 - Sabinasz & Schöner (2021)







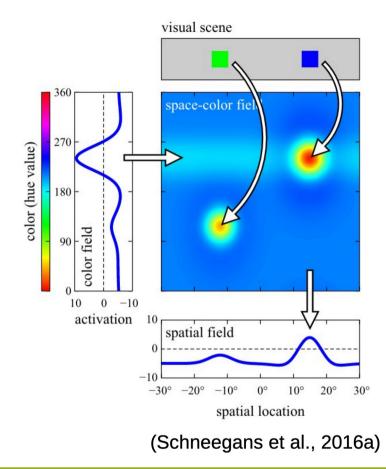
 Higher-dimensional fields enable binding dimensions



(Schneegans et al., 2016a)

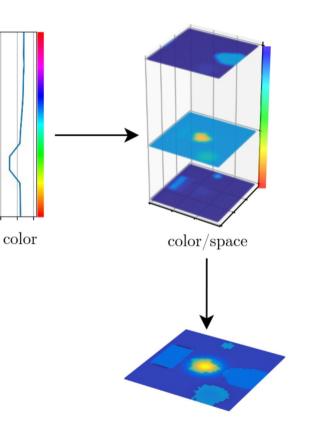


 Ridge input along one dimension can be used to extract bound information





 Ridge input along one dimension can be used to extract bound information

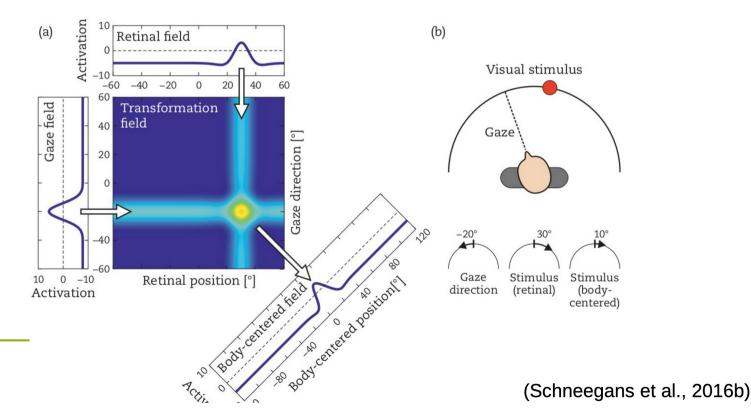






Transformation fields enable transforming spatial locations into a different coordinate system

RUB



- Evidence for neurons in the parietal cortex that have the response properties of transformation fields (Andersen and Mountcastle 1983; Andersen et al. 1985)
- Further evidence for the model (Schneegans & Schöner, 2012)



Lipinski et al., 2012

Cognitive architecture for grounding simple spatial language



SPATIAL COMPARISON

- Compare two objects w.r.t. their spatial relation
- "Where is the green object relative to the red object?" -> to the right





SPATIAL COMPARISON: REQUIRED OPERATIONS

(Following a computational analysis by Logan & Sadler, 1996)

- Spatial indexing: bind objects in the perceptual input to target and reference roles
 - "Where is the green object relative to the red object?"

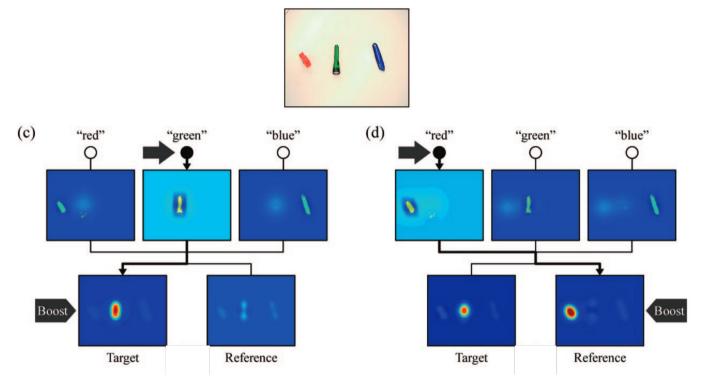
target reference

- Alignment of reference frame with reference object (coordinate transformation)
- Compare that relative position to spatial templates that represent regions of acceptability





FINDING OBJECTS IN THE PERCEPTUAL INPUT

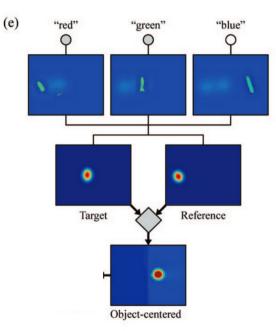


²² Lipinski et al. (2012)



COORDINATE TRANSFORMATION



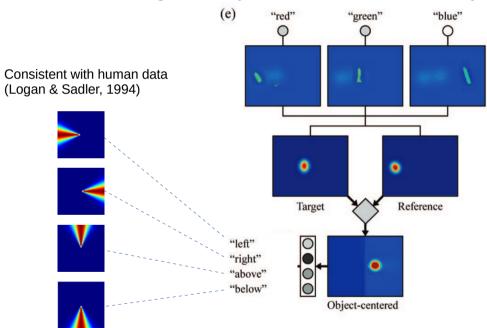






COMPARING TO A SPATIAL TEMPLATE

"Where is the green object relative to the red object?"





²⁴ Lipinski et al. (2012)



COMPARING TO A SPATIAL TEMPLATE

 Activation of the spatial relation nodes predict human acceptability ratings for spatial terms for a wide range of conditions



TARGET IDENTIFICATION

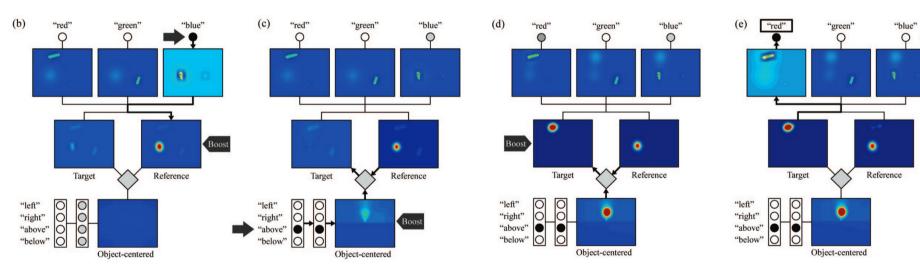
- Find an object which bears a given relation to a given reference object
- "Which object is above the blue object?"





TARGET IDENTIFICATION

"Which object is above the blue object?"



Boost



GROUNDING

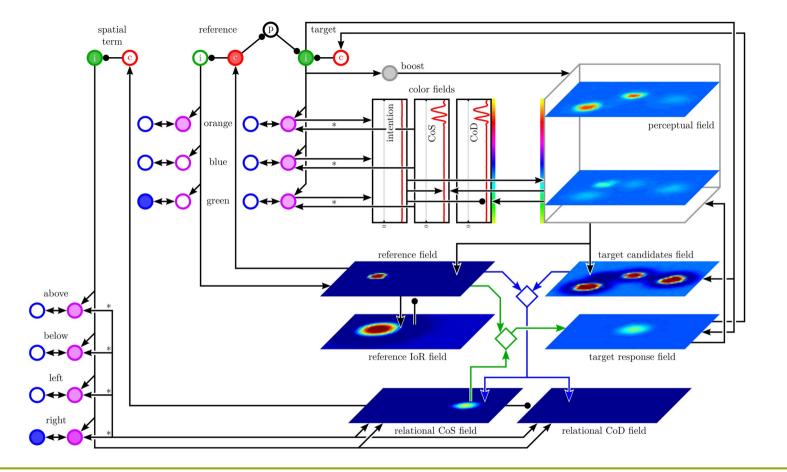
- Grounding a phrase which describes an object: finding the described object in the visual input
- e.g., "the red object to the left of the green object"
- Requires hypothesis testing



Another desideratum: Autonomy

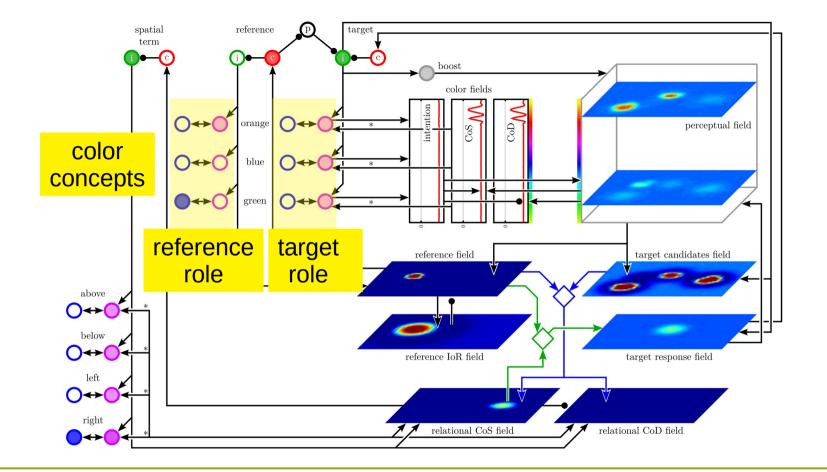






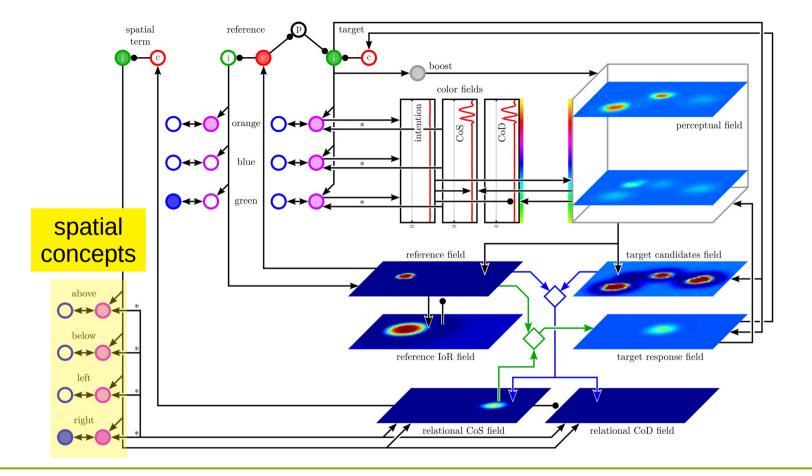
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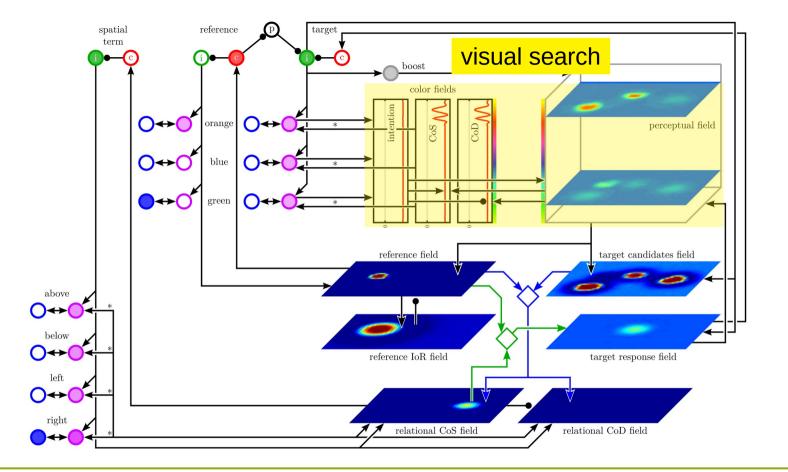
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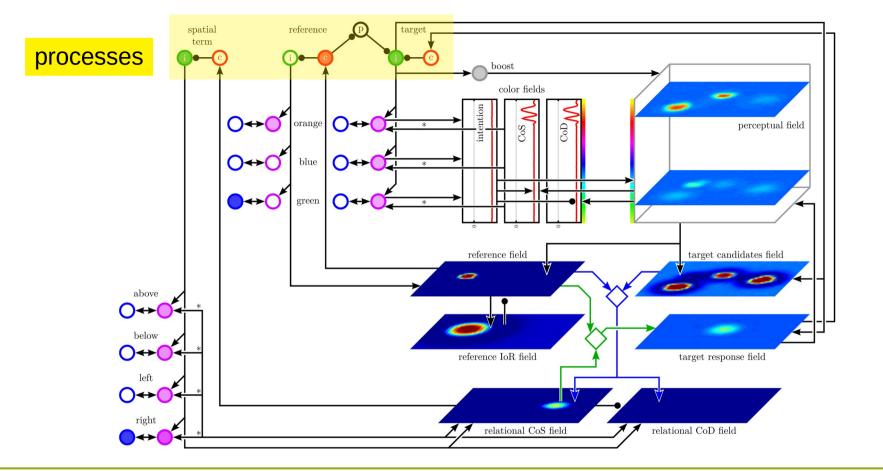
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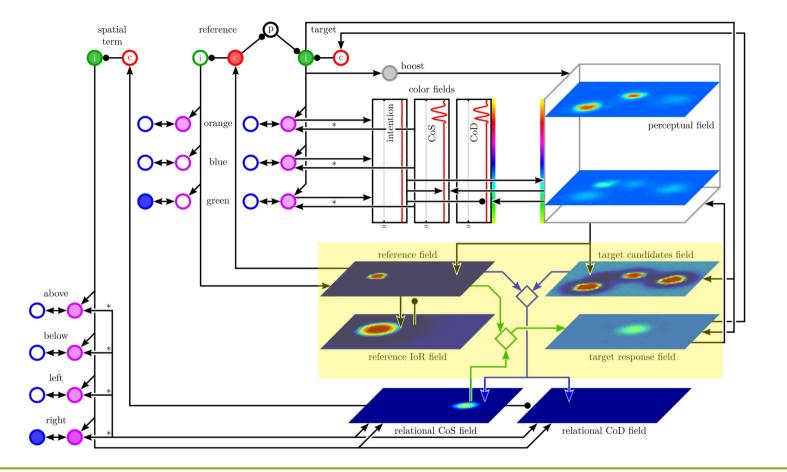
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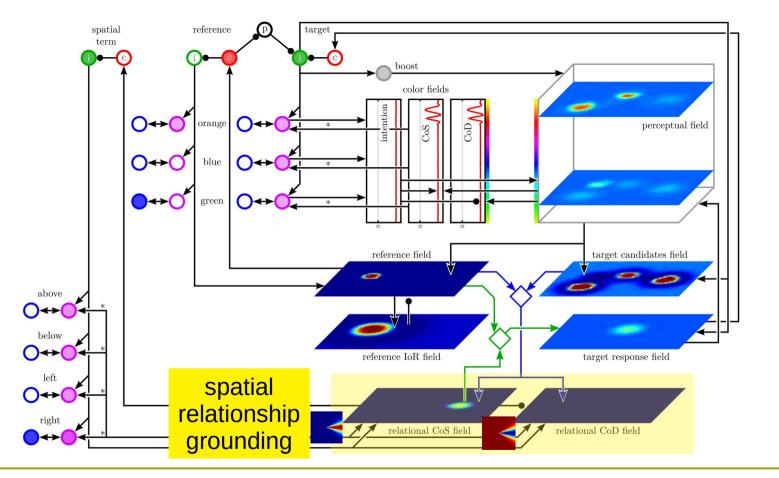
³³ Richter et al. (2014)



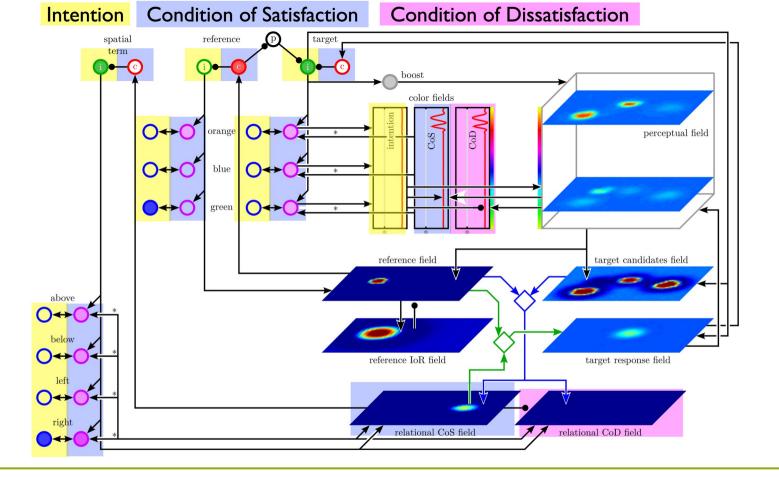


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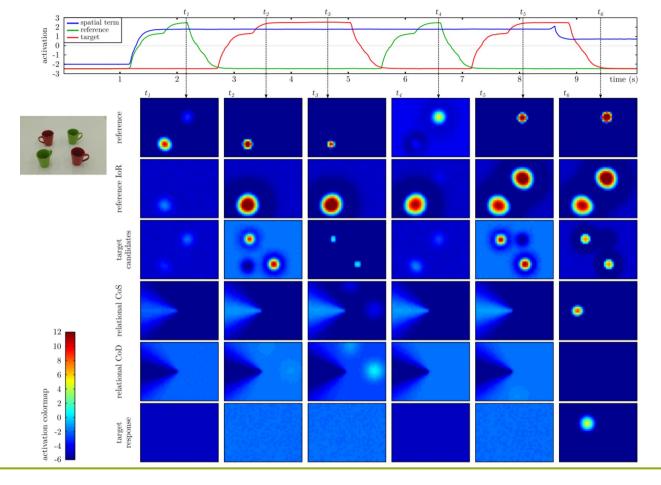
EXAMPLE



"The red object to the left of the green object"



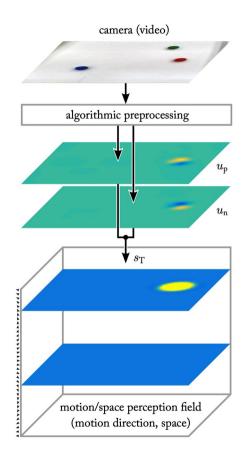


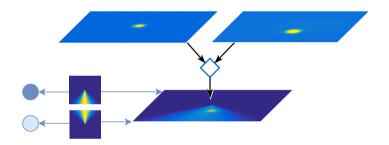


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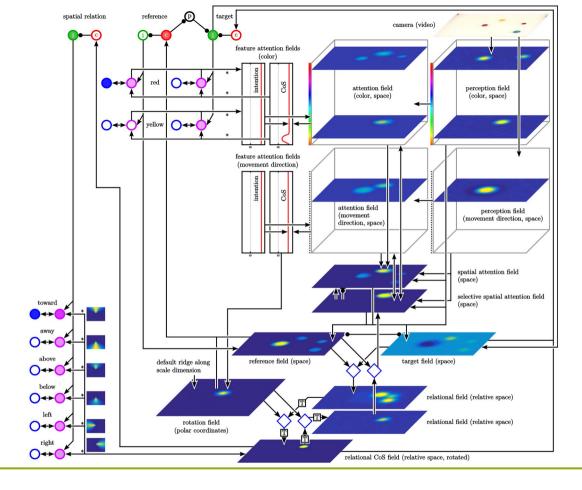
MOVEMENT RELATIONS



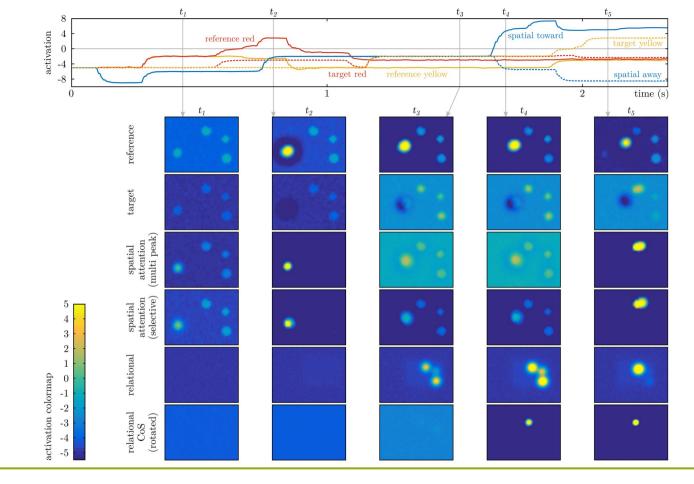




⁴⁰ Richter et al. (2017)









TOWARDS COMPOSITIONALITY

- the tree to the right of the tree below the lake
- the tree below the lake and above the house
- the red ball that moves towards the big tree, which is to the left of the lake and to the right of the house







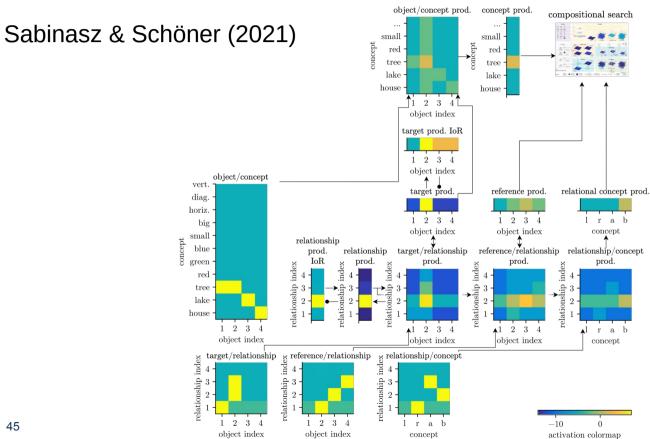
TOWARDS COMPOSITIONALITY

<u>The massiveness of the binding problem:</u>
e.g., "the lake above the tree above the house"

• <u>The problem of 2:</u> e.g., "the small tree above the big tree"



TOWARDS COMPOSITIONALITY





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